Tivoli® System Automation for z/OS

Version 3 Release 1

IBM

**TWS Automation
Programmer's Reference
and Operator's Guide**

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and Operator's Guide**

> **Note!**
>
> Before using this information and the product it supports, be sure to read the general information under "Notices" on page ix.

Contents

Figures

Tables

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Tivoli	VTAM	z/OS

Accessibility

Accessibility features help a user who has a physical disability, such as restricted mobility or limited vision, to use software products successfully. The major accessibility features in z/OS™ enable users to:

- Use assistive technologies such as screen readers and screen magnifier software
- Operate specific or equivalent features using only the keyboard
- Customize display attributes such as color, contrast, and font size

Using assistive technologies

Assistive technology products, such as screen readers, function with the user interfaces found in z/OS. Consult the assistive technology documentation for specific information when using such products to access z/OS interfaces.

Keyboard navigation of the user interface

Users can access z/OS user interfaces using TSO/E or ISPF. Refer to *z/OS TSO/E Primer*, *z/OS TSO/E User's Guide*, and *z/OS ISPF User's Guide Vol I* for information about accessing TSO/E and ISPF interfaces. These guides describe how to use TSO/E and ISPF, including the use of keyboard shortcuts or function keys (PF keys). Each guide includes the default settings for the PF keys and explains how to modify their functions.

z/OS information

z/OS information is accessible using screen readers with the BookServer/Library Server versions of z/OS books in the Internet library at:

http://www.ibm.com/servers/eserver/zseries/zos/bkserv/

About This Book

This book describes how to customize and operate TWS Automation. The TWS Automation part of IBM® Tivoli® System Automation for z/OS (SA z/OS) brings together batch and online console automation to a common focal point. TWS Automation automates, simplifies, and standardizes console operations and the management of component, application, and production related tasks.

Who Should Use This Book

This book is intended for the following user groups:

- System programmers, system designers, and application designers who will customize TWS Automation.

  For these users, all three parts of the book will be of interest.

  Installing and customizing TWS Automation requires a programmer's understanding of NetView, TWS, SA z/OS, and TWS Automation, because most of the definitions take place in these programs. Also, you will modify JCL, command lists, and programs for some of the automation functions

- Operators and administrators who manage and monitor TWS.

  For operators, a working knowledge of TWS will be assumed.

What's in This Book?

This book contains the following:

Part 1, "Introducing TWS Automation"
    Explains some main concepts and describes the functions of TWS Automation.

Part 2, "Operator's Guide"
    Describes the actions that an operator can perform with TWS Automation commands.

Part 3, "Programmer's Reference"
    This part describes the information needed to install and customize TWS Automation and the programming interface of TWS Automation.

Notation for Format Descriptions

The reference sections of this manual contain format descriptions of commands and of entries in the SA z/OS policy database. The notation used for these descriptions is as follows:

- Items shown in braces { } represent alternatives. You must choose one. For example,

  {A|B|C}

  indicates that you must specify one item only: A, B, or C.

- Items shown in brackets [ ] are optional. You may choose one. For example,

  [A|B|C]

  indicates that you may enter A, B, or C, or you may omit the operand.

- A series of three periods (...) indicates that a variable number of items may be included in the list.

- An underscored item shows the default that the system will choose if you do not specify an item. For example,

  [A|**B**|C]

  indicates that if no operand is specified, B is assumed.
- Lowercase italicized items are variables; substitute your own value for them.
- Uppercase items must be entered exactly as shown.
- Parentheses must be entered as shown.
- Where operands can be abbreviated, the abbreviations are shown in capital letters. For example, ALL can be entered as A or ALL.
- Commas are used as delimiters between parameters. The last parameter does not require a comma after it. Because of this, we place the comma in front of a parameter to show that if you add this parameter, you need a comma, as for example in

  XYZ   [A[,B[,C]]]

  However, the comma follows the preceding parameter and needs to be on the same line as that parameter.

Related Publications

The System Automation for z/OS Library

The following table shows the information units in the System Automation for z/OS library:

Table 1. System Automation for z/OS Library

Title	Order Number
IBM Tivoli System Automation for z/OS Planning and Installation	SC33-8261
IBM Tivoli System Automation for z/OS Customizing and Programming	SC33-8260
IBM Tivoli System Automation for z/OS Defining Automation Policy	SC33-8262
IBM Tivoli System Automation for z/OS User's Guide	SC33-8263
IBM Tivoli System Automation for z/OS Messages and Codes	SC33-8264
IBM Tivoli System Automation for z/OS Operator's Commands	SC33-8265
IBM Tivoli System Automation for z/OS Programmer's Reference	SC33-8266
IBM Tivoli System Automation for z/OS CICS Automation Programmer's Reference and Operator's Guide	SC33-8267
IBM Tivoli System Automation for z/OS IMS Automation Programmer's Reference and Operator's Guide	SC33-8268
IBM Tivoli System Automation for z/OS TWS Automation Programmer's Reference and Operator's Guide	SC23-8269
IBM Tivoli System Automation for z/OS End-to-End Automation Adapter	SC33-8271

The System Automation for z/OS books are also available on CD-ROM as part of the following collection kit:

    IBM Online Library z/OS Software Products Collection (SK3T-4270)

> **SA z/OS Home Page**
>
> For the latest news on SA z/OS, visit the SA z/OS home page at
> http://www.ibm.com/servers/eserver/zseries/software/sa

Related Product Information

You can find books in related product libraries that may be useful for support of
the SA z/OS base program by visiting the z/OS Internet Library at
http://www.ibm.com/servers/eserver/zseries/zos/bkserv/

Using LookAt to look up message explanations

LookAt is an online facility that lets you look up explanations for most of the IBM
messages you encounter, as well as for some system abends and codes. Using
LookAt to find information is faster than a conventional search because in most
cases LookAt goes directly to the message explanation.

You can use LookAt from these locations to find IBM message explanations for
z/OS elements and features, z/VM®, VSE/ESA™, and Clusters for AIX® and
Linux™:

- The Internet. You can access IBM message explanations directly from the LookAt
  Web site at http://www.ibm.com/servers/eserver/zseries/zos/bkserv/lookat/.
- Your z/OS TSO/E host system. You can install code on your z/OS or z/OS.e
  systems to access IBM message explanations using LookAt from a TSO/E
  command line (for example: TSO/E prompt, ISPF, or z/OS UNIX® System
  Services).
- Your Microsoft® Windows® workstation. You can install LookAt directly from
  the *z/OS Collection* (SK3T-4269) or the *z/OS and Software Products DVD Collection*
  (SK3T4271) and use it from the resulting Windows graphical user interface
  (GUI). The command prompt (also known as the DOS > command line) version
  can still be used from the directory in which you install the Windows version of
  LookAt.
- Your wireless handheld device. You can use the LookAt Mobile Edition from
  http://www.ibm.com/servers/eserver/zseries/zos/bkserv/lookat/lookatm.html
  with a handheld device that has wireless access and an Internet browser (for
  example: Internet Explorer for Pocket PCs, Blazer or Eudora for Palm OS, or
  Opera for Linux handheld devices).

You can obtain code to install LookAt on your host system or Microsoft Windows
workstation from:

- A CD-ROM in the *z/OS Collection* (SK3T-4269).
- The *z/OS and Software Products DVD Collection* (SK3T4271).
- The LookAt Web site (click **Download** and then select the platform, release,
  collection, and location that suit your needs). More information is available in
  the LOOKAT.ME files available during the download process.

Part 1. Introducing TWS Automation

This part describes some main concepts of SA z/OS, including some NetView-related information, and gives an overview of the facilities offered by TWS Automation.

Subtopics:
- Chapter 1, "Functions of TWS Automation," on page 3

Chapter 1. Functions of TWS Automation

This chapter describes the basic concept of TWS Automation, explains some aspects of its implementation, and sketches possible uses of TWS Automation.

For information about SA z/OS refer to *IBM Tivoli System Automation for z/OS User's Guide*.

Basic Concepts

TWS Automation is an extension of SA z/OS that capitalizes on the strengths of NetView, SA z/OS, and TWS by providing the ability to greatly expand job execution, scheduling, monitoring, and alert notification capabilities.

Tivoli Workload Scheduler for z/OS Automation consists of two basic functions.
1. Requests from TWS to SA z/OS and associated status updates.
2. Requests from SA z/OS to TWS and associated status updates.

TWS to SA z/OS Functions

Tivoli Workload Scheduler needs to be able to request desired state changes to subsystems under the control of SA z/OS. There are two interfaces that allow you to do this:
1. A request interface
2. A command or batch interface

Request interface
This interface uses an "automation" workstation named NV*xx* and the TWS exit EQQUX007 to pass a request via the NetView PPI to SA z/OS. NV*xx* workstations can make full use of the TWS scheduling capabilities: they can have predecessor links, time dependencies and special resources.

Request types are START, STOP, CANCEL, or any user defined type. The command behind the request type is defined in the SA z/OS policy database. The job name is used to determine the subsystem that is associated with the request. There can be multiple commands associated with the request type. In any case, the subsystem as well as the request types must be predefined in the policy database. For the standard request types START, STOP, and CANCEL, the appropriate default command is issued when no corresponding entry is found in the policy database.

The Tivoli Workload Scheduler status change exit has been changed to support WTO'd status changes. The purpose of the exit is to provide information to SA z/OS, which in turn will notify operators via NMC and SDF.

Command Interface
The command interface is designed to work with TWS in a way that is natural for TWS. It takes the form of a batch job that can be used to execute any NetView or SA z/OS command on any NetView interconnected in the enterprise.

The batch job may execute on any system in the sysplex that contains an SA z/OS Agent or NetView Agent running the TWS PPI batch command receiver. This

3

command receiver is a NON-MVS SA z/OS subsystem and may be controlled via the same interfaces as any other SA z/OS subsystem.

SA z/OS to TWS Functions

System Automation for z/OS needs to be able to control the operation of Tivoli Workload Scheduler. TWS operations can be made to wait until a previously requested SA z/OS state change has occurred. SA z/OS will make subsystem, application group, system and system group statuses available to TWS. This is done by reflecting the SA z/OS status in a pair of TWS Special Resources. TWS operations may be coded to wait until the appropriate special resource is in the desired state, thus preventing the batch job stream from proceeding until a TWS request to SA z/OS has been completed.

The INGOPC/INGTWS command allows an SA z/OS operator or automation function to request changes to the TWS current plan. This interface may be used for any Controller defined to SA z/OS or any Tracker (defined to SA z/OS) that represents a *foreign* Controller. A *foreign* Controller is one that resides outside the sysplex or that is not defined to SA z/OS.

Note: The old SA z/OS TWS commands have been deprecated. They are provided in this release for compatibility purposes and to allow for the migration to the new commands. The commands concerned are as follows:
1. OPCACMD

   Replaced by INGOPC REQ=LIST.
2. OPCALIST

   Replaced by INGOPC REQ=LIST.
3. OPCAMOD

   Replaced by INGOPC REQ=MOD.

Obtaining Information from TWS

The application program interface of OPC/ESA allows TWS Automation to act directly on the TWS current plan. Using this interface, TWS Automation directly requests and updates TWS-based information.

Recovery operations provide one possible use of the TWS API by TWS Automation. For example, if a communications link to a target NetView is not available, the operator can use the OPCACOMP or OPCAPOST command to manually post events that have occurred.

You can also use this interface when manual intervention is required, for example, when a user sequence error is detected. Use the OPCACMDoperator command to manually access the information from TWS about operations in the current plan through the TWS API. This allows the determination and resolution of the sequence error to occur from a single NetView console.

The host with the TWS Controller task provides the only availability to the TWS API interface. Because of this, all recovery is done only in the NetView on the processor running the TWS Controller task. Sometimes, when a user-written module utilizes this function, another NetView requires the information. TWS Automation maintains an entry in the policy database to allow TWS Automation to determine the domain ID of the TWS NetView to which the request is sent (CONTROLLER DETAILS policy object, OCS entry type). This entry has the

domain ID of the NetView on the processor running the TWS Controller. In this manner, all the SA z/OS applications can easily determine where to direct TWS Controller requests.

A user-written task or CLIST can also access the TWS Controller. Your own routines can list operations in the current plan with the INGOPC REQ=LIST command. You can modify the data in current plan operations with INGOPC. You can query the TWS calendar with INGOPC. You can synchronize TWS with OPCACOMP, or OPCAPOST if you write your own automation routines, and you can update the status of special resources in TWS with the SRSTAT CLIST. In this way you can trigger operations to run that have a special resource dependency in TWS.

Defining SA z/OS to Tivoli Workload Scheduler

There are no required Tivoli Workload Scheduler definitions.

Request Interface

To define a TWS request that TWS Automation can use, a workstation representing the target NetView domain is required. This workstation, which is defined with TWS using the standard TWS dialogs, should be a general, automatic reporting workstation. Its name *must* have the format NV*xx*.

Note: Reserve NV*xx* workstations for TWS Automation. Unpredictable and undesirable results may occur if these workstation names are used for other workstations.

For the request interface, you must define TWS workstations. There is a naming convention for these workstations that the names must begin with NV and are four characters long.

Command Interface

Because the command interface is a normal batch job as submitted by TWS, there are no extra TWS definitions. You may optionally create a batch job submission workstation that is used to submit the batch jobs to run commands against SA z/OS. The advantage in doing this is that the command processor that the batch job runs can automatically stop the workstation if the SA z/OS Agent or NetView Agent is not up or the PPI interface is not responding. When the SA z/OS Agent or NetView Agent starts up it will automatically restart the previously stopped workstation.

Currently only one PPI receiver non-MVS subsystem is provided in the sample add-on policy database. However, you may start more by specifying a different PPI receiver name for each one to be started. Batch jobs have a parameter that can be used to select the appropriate PPI receiver to execute the commands against. By specifying multiple TWS workstations, one per PPI receiver, TWS can schedule batch jobs to the appropriate receiver and thus get a better throughput of requests. However, only one of the workstations will be restarted when the SA z/OS Agent or NetView Agent starts up. The user can use TWS variable substitution to resolve the name of the PPI receiver from the name of the Workstation the job is assigned to.

Defining Tivoli Workload Scheduler to SA z/OS

The Tivoli Workload Scheduler Installation manual insists that each TWS subsystem in a sysplex is uniquely named.. Detailed instructions for defining this configuration can be found in *IBM Tivoli System Automation for z/OS Defining*
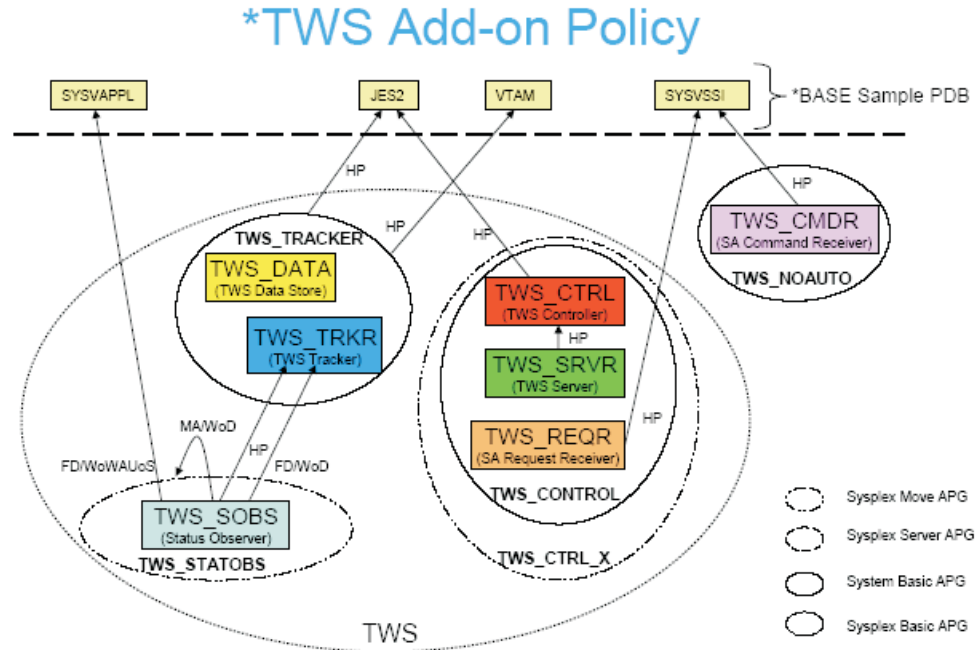
*Figure 1. *TWS Add-On Policy Database*

Tivoli Workload Scheduler consists of a number of MVS™ and non-MVS subsystems that need to be defined to SA z/OS. These are:

1. The TWS Controller
2. The TWS Tracker
3. The TWS Server
4. The TWS Data Store
5. The SA z/OS Batch Job Command Receiver
6. The SA z/OS Request Receiver
7. The SA z/OS Status Observer

Each will be described in turn.

The TWS Controller

TWS Controller subsystems may be defined to start simultaneously across multiple systems in a sysplex. However, only one of these subsystems will become the active subsystem. All other Controller subsystems will go into standby mode. Controller subsystems may be defined in a sysplex group, or in a system group that is attached to multiple systems. Controller subsystems require Tracker subsystems to manage the batch job stream.

Note that a sysplex move group has been defined in the *TWS addon policy that is used for backup rather than a hot standby as normal in TWS Automation.

The TWS Tracker

TWS Tracker subsystems may be defined to start simultaneously across multiple systems in a sysplex.

The TWS Server

TWS Server subsystems are usually automatically started by the Controller subsystem that has taken on the ACTIVE role.

The TWS Data Store

The data store is a separate address space. It collects structured information (steps and data sets) and, optionally, unstructured information (SYSOUT) for all submitted jobs. Typically, a data store is installed for each JES spool in a system. In a simple JES configuration this would mean one data store for each tracker.

The TWS DS is started as a normal SA z/OS subsystem.

TWS Data Store contain SYSOUT information collected from JES on behalf of the active Controller.

The SA z/OS Batch Job Command Receiver

These subsystems are non-MVS NetView subsystems that run in an SA z/OS Agent or NetView Agent. They provide PPI communications for servicing Batch Job Commands. This allows a batch job to execute a NetView or SA z/OS command and to get the output of the command back at the batch job.

The SA z/OS Request Receiver

These subsystems are non-MVS subsystems that run in the SA z/OS NetView Agent. They provide PPI communications to the TWS Controller that allow the TWS Controller to inject requests to SA z/OS. This allows TWS to control the status of resources being managed by SA z/OS.

The SA z/OS Status Observer

SA z/OS TWS Automation provides a facility that echoes the status of SA z/OS resources in TWS Special Resources. This facility allows you to define TWS operations that will wait until SA z/OS resources reach a desired state. Currently only two desired states are allowed. The UP state is when the automation manager sets the resource to the AVAILABLE state. The DOWN state is when the automation manager sets the resource to the UNAVAILABLE state.

NetView Interface to TWS Automation

The program-to-program interface (PPI), a high-performance interface, provides synchronization and bidirectional command and message flow between NetView and other applications. TWS provides additional application programming interfaces (APIs), which allow it to be updated by other programs.

The implementation of these interfaces in TWS Automation provides the following capabilities:

- Automation of TWS startup and termination
- Interception of TWS alerts for analysis by theoperator
- Expansion of the Status Display Facility to provide information about TWS errors
- Implementation of a two-way interface between TWS and NetView with SA z/OS:
  - TWS defines and controls interactive applications. Support is provided to start and stop subsystems that are defined to the SA z/OS application.
  - Database tasks can run in both interactive and batch systems with full synchronization between the activities.

– SA z/OS operators can access TWS calendars and other information as well as update TWS information using the INGOPC or INGTWS command.
- Two user extensions:
  – OPCACOMP allows the start up and shut down of subsystems independently of automation status changes.
  – UX*xxxxxx* allows automation of activities not associated with a specific subsystem.

TWS Automation provides commands and panels that allow a NetView operator to make inquiries and issue requests to TWS without actually logging on to TWS.

TWS Automation Special Resources

TWS Automation is able to globally control the creation and setting of TWS special resources based on the status of SA z/OS monitored subsystems. This will allow TWS to resolve job scheduling dependencies based on the status of SA z/OS managed resources.

The TWS special resources created/set by this function are as follows:

```
ING.res_sys.res_type.res_name.UP, and
ING.res_sys.res_type.res_name.DOWN
```

where:

res_sys	is the MVS sysid of the system where the subsystem status change was detected. If the resource is a SYSPLEX application group, then the value SYSPLEX is used.
res_type	is one of APL, APG, SYS, SYG, GRP, or MTR.
res_name	is the name of the resource.
UP	is a literal that defines the resource as being available only when the resource has an observed status of AVAILABLE and a desired status of AVAILABLE.
DOWN	is a literal that defines the resource as being available only when the observed status of the resource is one of the following Automation Manager statuses:

SOFTDOWN, HARDDOWN, STANDBY, UNKNOWN, SYSGONE,

and when its desired status is UNAVAILABLE. |

Possible Uses of TWS Automation

In data centers, certain groups assume responsibility for the daily operation of the systems. Frequently, these groups are split into these two areas that perform the following tasks:
- Controlling online systems
- Processing all batch work

User requests for hours of service form the basis for online planning decisions. The time available to process the jobs required for online systems for the next day, as well as requests for other batch work, determines batch processing.

A system using TWS executes the current plan (CP), which contains the information for batch processing. A help desk, hotline, or service-contact point merge user-change requests into the overall schedule. While processing control

executes batch processing, operations or master terminal operators control the online systems, thus adding to the confusion. Changes to online availability are frequently manual in nature. For example, instructions to change online availability often consist of slips of paper or phone calls to the operator.

TWS Automation allows changes which influence both batch and online systems through simple TWS dialogs. Because TWS manages both batch and online systems, these changes are needed only in one place. Because the processes are automated with SA z/OS and TWS, no interoperator communications are required. In fact, in a highly automated environment, no operator intervention or awareness of these user-requested changes is necessary.

TWS Automation can automate some of the more complex operator procedures and thereby provide several new functions. The following topics give some examples and scenarios which demonstrate these functions.

Changing Online Hours of Availability

Several possible methods exist for changing the hours of availability of online services. To illustrate these methods, consider the example of a service such as IMS™. Assume that the scheduled hours of availability for the IMS online service are 7 a.m. to 6 p.m. In NetView, under control of the current plan, TWS Automation performs the timed start and stop events.

- The help desk gets a request from a user group to extend the IMS hours of availability, for today only, from the original plan of 6 p.m. to 8 p.m. (extended service period).
- The help desk ensures that this extended service is acceptable within the service level agreement for this user group.
- The help desk now makes a change to the TWS current plan to reflect this extended IMS period.
- When the revised scheduled time is reached, now two hours later than usual, TWS executes the operation, requesting that TWS Automation stop IMS.
- TWS Automation requests that SA z/OS application stops IMS.
- Once SA z/OS has successfully stopped IMS, TWS Automation returns an operation-ended status to TWS, fulfilling TWS's dependencies on the online IMS.
- Jobs dependent on the termination of IMS are now released for execution.

No restructuring of the batch processing is necessary if the request is within planned service bounds.

Cycling Individual Online Databases

TWS Automation allows TWS to interact not only with the SA z/OS functions, but also with the MVS and MTO consoles, which enables the scheduling of interrelated sequences of events. For example, it is possible to cycle individual databases rather than the complete online system. Figure 2 on page 10 shows how this scheduling results in minimum disruptions to online applications.
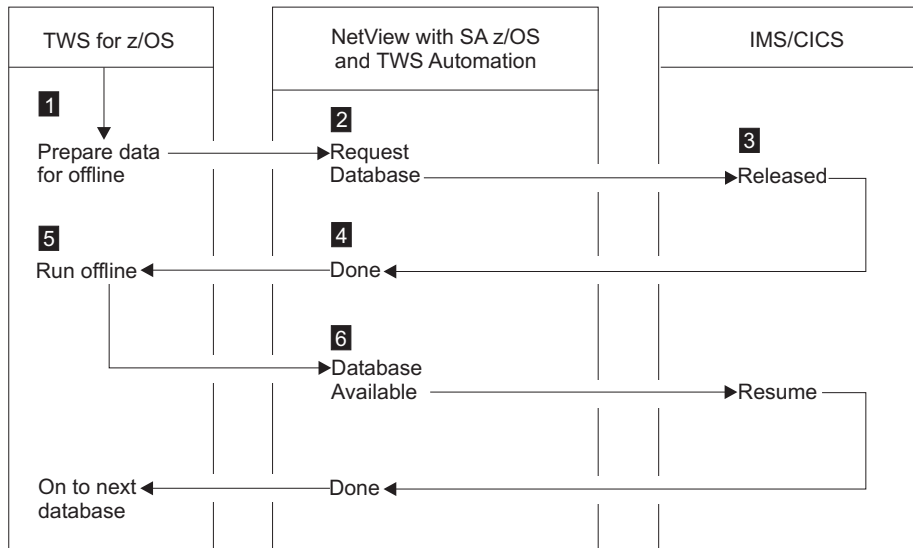
Figure 2. Example of Cycling Individual Online Databases

In Figure 2, the online databases are structured so that you can vary specific ones offline, without an impact to the system, as in the case of databases structured on a geographic or application basis. This process flows as follows:

1. Based on the current plan, TWS begins the READY TO START DATABASE UPDATE job.
2. A request is sent to TWS Automation to issue the command required to vary the subject database offline to allow for batch processing.
3. The request is issued through the MTO interface.
4. TWS Automation ensures that the database is offline.
5. TWS Automation posts the operation as completed in TWS.
6. With the operation completed, TWS dependency starts the batch processing for this database.
7. When the batch process is completed, TWS once again triggers TWS Automation, and the proper MTO command is issued to vary the database online to IMS.

When individual databases accomplish this type of process, the database/data communications (DB/DC) system is always up, and certain small portions of the data is unavailable for short periods. In some cases, you can restructure the databases to further shorten periods of data unavailability.

TWS Automation does not directly support the preceding example, which requires some user-written modules. (See "Interaction with CICS Automation" on page 103 and "Interaction with IMS Automation" on page 104 for some examples of this type of user-written module.) TWS Automation transports the request to the appropriate system and prepares the information for the user code. TWS Automation then returns the resulting status to the operation in TWS. TWS Automation also ensures that the actions requested are serialized with other requests to that specific target subsystem and that the status of the subsystem is such that it can accept the requests.

Scheduling Time for Testing

Another example is an automated mechanism that prepares a logically partitioned mode (LPAR) on a process resource/system management (PR/SM™) complex for testing periods.

In this example, a system programmer or application developer makes a request through the help desk for testing. The help desk checks that the resources for the test period are available and invokes a prepared TWS-controlled application, updating the information required to set up the time and duration of the test. No other action is needed.

At the proper time, TWS begins execution. It sends the requests to the target system control facility (processor operations) application to set up the LPAR for the test period, and to IML and IPL the PR/SM partition. If the requestor of the test period prepares the test system, so it is ready and waiting at the start of the test period, there is no waiting for an operator to set up the test environment or to structure the system as required by the testing.

Distributing and Updating Data Across Multiple Systems

As centralization of operations and support progresses, preparing data at a central site and then distributing it to other systems becomes necessary. Controlled execution of batch utilities is often required to update the target systems.

Installation of system maintenance provides an example of this type of distribution. Program temporary fixes (PTFs) are installed and tested at a central site. The PTFs are then shipped to target systems and applied with a system modification program (SMP/E). Frequently, a system programmer performs this by logging on to the target system and executing the job streams manually.

Another example is the creation of office system files on a central system, such as electronic telephone directories. These files are then distributed to the target systems.

TWS can control network job entry (NJE) jobs for the distribution of data, and thus controls the execution of the jobs on the target systems, to apply the data, using dependency control, if required.

TWS Automation extends this TWS capability and allows necessary cycling of the target system application once the maintenance is applied successfully. You can schedule this in such a way as to minimize any impact on the end-user community. The following is a typical scenario:

1. A PTF is installed, tested, and found acceptable. This PTF is then applied to all copies of TSO in a multisystem environment.
2. The application is defined to TWS. In most cases, the application is simply updated since it is already defined.
3. TWS presents the batch jobs that control the SMP/E process to the systems programmer for modifications, if required.
4. TWS schedules the transmission of the jobs to the target systems using NJE. The scheduling can use a time when network traffic is low.
5. Once the jobs are in the target system, TWS dependency control is used to schedule the SMP/E job execution.
6. TWS ensures that the SMP/E jobs run correctly. If TWS encounters problems, the TWS application provides backout procedures.

7. After installing the PTFs, TWS selects the appropriate time to issue a request to TWS Automation to restart TSO.
8. Since TWS fully controls the process for this PTF update, you can inquire at any time to see the progress of the operations. If errors or problems occur, TWS Automation informs the SA z/OS notification operator.

Complex Application Recovery

As computer applications become more critical to the daily operation of your enterprise, disaster recovery takes on an added significance. Usually, installations have the necessary equipment and facilities for disaster recovery, but the operational processes are so complicated that the chance of a successful backup in a short period, lasting from many minutes to no more than a few hours, is highly unlikely.

TWS Automation allows full or partial automation of this type of activity between systems and sites. In some cases, changing the NVxx-to-NetView domain ID relationship is adequate to transfer the control of the work load to a different system. However, the change may require some manual intervention for synchronization. Chapter 15, "Resynchronization and Recovery Considerations," on page 113 discusses several scenarios and the process of synchronization.

Although not all steps are required each time, most recoveries consist of three major operational steps that are executed sequentially and provide the following functions:

Step 1: Preparing the recovery system
  This may require stopping some or all the applications on the recovery systems, unloading data from disk-storage devices to tape, and reconfiguring the recovery system.

Step 2: Starting the critical applications on the recovery system.
  This can include the following:
  • Loading databases and applications from tape-to-disk devices
  • Starting the recovery system
  • Updating data from checkpoint data, logs, or other sources
  • Starting critical applications.

Step 3: Returning to the original production system
  This is a reversal of the recovery process. These procedures are as complex as the original recovery process, but are scheduled and do not have the urgency of the original recovery.

In the following example, a series of applications need starting on a system after the failure of the original system or possibly even the site. Assume that the installation has prepared properly for this type of problem. This implies tested procedures, current levels of the affected applications and operating environment, and data at the backup site. To simplify this example, assume that the database at the recovery site is adequate for a contingency recovery situation.

• Prior to the need, a series of interdependent recovery applications are defined to TWS, but not scheduled.
• The decision to recover the critical applications at the backup site is made. The scheduler uses normal TWS panels to modify the current plan to schedule the first backup application.
• Before recovery, several factors, which can result in modifications to procedures and JCL, need considering. These modifications are then presented to operators

at manual workstations with instructions in the operator instruction files of TWS. They are also presented to systems programmers at JCL workstations.

- The work load on the recovery system is stopped by scheduling a request to SA z/OS to stop all subsystems other than JES.
- Once the subsystems are stopped, a series of jobs are scheduled to transfer data from disk-to-tape to accommodate the requirements of the critical applications that are recovered.
- Depending on the situation, the same system is reused or restructured, and then followed by an IML and IPL of the recovery system. If this is the case, the focal point implementation option of SA z/OS is used to partially or completely automate this phase of the recovery. Regardless of the specifics, the result is an operating system platform ready to accept the recovery environment.
- TWS schedules a series of JES jobs that restore the databases from backup.
- TWS triggers NetView to issue the appropriate commands to start the subsystem.
- In some cases, NetView requires access to MTO functions to issue specific procedures before the DB/DC system can resume transaction processing. If that is the case, user-provided modules are required to fully automate the recovery.

At this point, the recovery is completed. Normal operating procedures should apply to the environment. Because a recovery situation creates an environment where resources are scarce, the actual applications that are offered are frequently a subset of the normal applications. To accommodate this environment, TWS and TWS Automation may need to change the scheduling of some of the applications controlled by TWS.

After recovery occurs and you resolve the problems which forced the original backup, the applications should be moved back to the original system. The scenario for this move is similar to the one above except that this move is planned instead of forced. This allows you to move specific applications one at a time, as opposed to the all-at-once scenario that a critical situation requires. The fact that some of the applications are moved to an already working system makes the takeback more complex than the original recovery.

Give special consideration to any synchronization procedure in an TWS Automation environment. For more information on the synchronization process, see Chapter 15, "Resynchronization and Recovery Considerations," on page 113.

Part 2. Operator's Guide

This part describes the actions that an operator can perform with TWS Automation commands.

Subtopics:

Chapter 2. Managing the TWS Current Plan

You can use the INGOPC command (or INGTWS, which is a synonym) to list or modify any current plan Application, Operation, Special Resource or Workstation, and to list any current plan Calendar. This function is described in the *IBM Tivoli System Automation for z/OS Operator's Commands*.

Selecting the TWS Controller to Access

The INGOPC command allows you to select the TWS Controller to access via the TWS API.

The positional parameter specifies the SA z/OS resource name of the TWS Controller. If the TWS Controller is in a sysplex and may have active and standby Controllers, you may specify an SA z/OS Application Group that contains the set of TWS Controller resources. The INGOPC command will automatically select the active Controller.

Using Multiple Resource Definitions

The Resource Parameter can take multiple arguments contained in brackets and separated by commas, for example:

```
INGOPC (CTL1/APL/SYS1,CTL2/APL/SYS2)
```

In this case both CTL1 and CTL2 TWS Controller subsystems will be scanned to see which is the Active Controller. The Active Controller is the subsystem that is in the AVAILABLE Automation Manager state and that is marked ACTIVE by the automation manager.

Using Wildcards

The Resource Parameter can take wildcards as defined in the INGLIST command, for example:

```
INGOPC CTL*/APL/*
```

In this case both CTL1 and CTL2 would be scanned as in the example for multiple resource definitions, however, the user specification is shorter.

Using Application Groups

The Resource Parameter may be SA z/OS Application Groups, for example:

```
INGOPC CTLR/APG
```

or:

```
INGOPC CTLG/APG/SYS1
```

Both SYSPLEX and SYSTEM type application groups are allowed. The members of the application groups are found and checked to see if they are TWS type applications. Only the TWS type applications with a subtype of CONTROLLER or TRACKER are checked.

Indirectly Selecting a Controller

In most cases the resource specification will resolve to a single TWS Controller subsystem. However, there are occasions when the Controller subsystem is not present on any system that SA z/OS has access to. In these cases, there must be at least one Tracker on the system or sysplex that SA z/OS is managing. This Tracker must have the "TWS Control" policy with the "Controller ID" and the "API LU Name" policy items specified.

If the INGOPC command cannot resolve the resources that you specify as an active TWS Controller, a final attempt is made to see if any of the resources are a TWS Tracker. If a single OPC Tracker is found in an AVAILABLE state and has an LUNAME policy entry, then this tracker will be used. If multiple controllers or trackers (or both) are found, and INGOPC is running in full screen mode, then a selection list is displayed; when OUTMODE=LINE is specified an error message is displayed.

The Tracker selected will be used to refer to a remote Controller via the definitions in the "TWS Control" policy as specified above.

Displaying the Current Plan

To display the Current Plan, use the INGOPC command with REQ=LIST and specify the type of TWS resource required from:
- APPL for applications
- OP for operations
- SR for special resources
- WS for workstations
- CAL for calendars

On each of the panels that display the current plan, pressing PF5 displays a filter selection panel similar to Figure 3.

```
 EVJKFLT                    SA z/OS  - Command Dialogs
 Domain ID   = IPSFM      ---------- EVJFILT  ----------    Date = 07/25/05
 Operator ID = SAOPER                                       Time = 16:36:48

 Specify or revise the filter criteria:

   Active Controller ==>  OPCF/APL/KEY1
   OPC/OPC resource  ==>  APPL           APPL, OP, SR, WS or CAL

   Generic Filter strings in the format NAME = value
   ==>  _____      ==>  _____
   ==>  _____      ==>  _____
   ==>  _____      ==>  _____
   ==>  _____      ==>  _____
   ==>  _____      ==>  _____
   ==>  _____      ==>  _____
   ==>  _____      ==>  _____
   ==>  _____      ==>  _____
   ==>  _____      ==>  _____
   ==>  _____      ==>  _____
```

Figure 3. INGOPC Filter Sample Panel

Specify filter strings in the following format:

field-name op contents

where:

- *field-name* is a valid field name as specified by the MODIFY command arguments in *Tivoli Workload Scheduler for z/OS Programming Interfaces*.
- *op* can have the following values:

  =

  ^=

  <

  <=

  >

  >=

- *contents* are the desired values to be matched by the *op*. The trailing wildcard character '*' may be used for *op*.

The operands must be separated by a blank.

Displaying TWS Applications

If you specify TYPE=APPL, this will select TWS Applications for display. To reduce the number of applications that are listed, you can use the optional parameters of AD= and IA= to specify the application ID and the Input Arrival time of the application.

In OUTMODE=LINE, a set of messages will be returned that contains all the data for the selected applications.

The fullscreen interface is as shown in Figure 4.

```
CMD: A Update    B Operations                                    / scroll
                         Application Occurrence List
                      Input Arrival        Error
CMD  Application Id    Date     Time Status   Code Description
---  ----------------  -------- ----- --------- ----- ------------------------
     RMFSTA            05/07/20 10:10 Error          Start RMF and RMFGAT
_    OPCAO#TESTAD      05/07/21 08:00 Completed      OPCAO NETV interface
_    OPCAO#TESTAD      05/07/22 08:00 Error          OPCAO NETV interface
_    OP00DPEXT         05/07/25 06:30 Completed      DAILY PLAN EXTENT OP00
_    TEST              05/07/25 07:00 Completed      Test application
_    OPCAO#TESTAD      05/07/25 08:00 Error          OPCAO NETV interface
_    RMFSTO            05/07/25 10:00 Completed      Stop RMF and RMFGAT furx
_    RMFSTA            05/07/25 10:10 Completed      Start RMF and RMFGAT
_    RMFSTOX7          05/07/25 11:00 Completed      Stop RMF with Exit 7
_    RMFSTAX7          05/07/25 11:10 Completed      Start RMF with Exit 7
_    OP00LTEXT         05/07/26 06:00 Waiting        LONGTERM PLAN EXTEND
_    OP00DPEXT         05/07/26 06:30 Waiting        DAILY PLAN EXTENT OP00
_
```

Figure 4. TWS Applications Interface Panel

You can scroll left and right with the PF11 (Next) and PF10 (Previous) keys. If
more data is available than is displayed on the screen, use the PF8 (Down) or PF7
(Up) keys to scroll the data up or down.

For details about the different column values, see the online help or the description
of the INGOPC command in *IBM Tivoli System Automation for z/OS Operator's
Commands*.

Figure 5 is displayed if you press the PF11 key.

```
CMD: A Update    B Operations                                    / scroll
                         Application Occurrence List
                      Deadline      Actual Arrival Completion
CMD  Application Id    Date     Time Date     Time Date     Time
---  ----------------  -------- ----- -------- ----- -------- -----
     RMFSTA            05/07/20 11:00 05/07/20 10:10   /  /    :
_    OPCAO#TESTAD      05/07/21 24:00 05/07/21 08:00 05/07/25 10:18
_    OPCAO#TESTAD      05/07/22 24:00 05/07/22 08:00   /  /    :
_    OP00DPEXT         05/07/25 06:40 05/07/25 06:30 05/07/25 06:32
_    TEST              05/07/25 10:00 05/07/25 07:30 05/07/25 07:30
_    OPCAO#TESTAD      05/07/25 24:00 05/07/25 08:00   /  /    :
_    RMFSTO            05/07/25 11:00 05/07/25 10:00 05/07/25 10:00
_    RMFSTA            05/07/25 11:00 05/07/25 10:10 05/07/25 10:10
_    RMFSTOX7          05/07/25 12:00 05/07/25 11:00 05/07/25 11:00
_    RMFSTAX7          05/07/25 12:00 05/07/25 11:10 05/07/25 11:10
_    OP00LTEXT         05/07/26 06:30   /  /    :     /  /    :
_    OP00DPEXT         05/07/26 06:40   /  /    :     /  /    :
_
```

Figure 5. TWS Applications Interface Panel, Screen 2

Figure 6 on page 21 is displayed if you press the PF11 key.

```
CMD: A Update    B Operations                                    / scroll
                       Application Occurrence List
                   Critical  ------------Operations----------------
CMD  Application Id  W.S. Op#  Number Compl Error Undec. Started Crit.
---  --------------- ---- ---- ------ ----- ----- ------ ------- -----
 _   RMFSTO          CPU1   10      4     1     1      0       3     2
 _   RMFSTA          CPU1   10      3     1     1      0       3     2
 _   OPCAO#TESTAD            0     16    16     0      0      16     0
 _   OPCAO#TESTAD    NV04   10     16     1     1      0       2     1
 _   OP00DPEXT              0      3     3     0      0       4     0
 _   TEST                   0      3     3     0      0       4     0
 _   OPCAO#TESTAD           0     16    14     1      0       0     0
 _   RMFSTO                 0      4     4     0      0       6     0
 _   RMFSTA                 0      3     3     0      0       4     0
 _   RMFSTOX7               0      3     3     0      0       3     0
 _   RMFSTAX7               0      3     3     0      0       3     0
 _   OP00LTEXT       DUMY   1      3     0     0      0       0     3
 _   OP00DPEXT       DUMY   1      3     0     0      0       0     3
```

Figure 6. TWS Applications Interface Panel, Screen 3

Displaying TWS Operations

If you specify TYPE=OP, this will select TWS Operations for display. To reduce the number of operations that are listed, you can use the optional parameters of AD=, IA= and OPNO= to specify the application ID, the Input Arrival time of the application and the operation number.

In OUTMODE=LINE, a set of messages will be returned that contains all the data for the selected operations.

The fullscreen interface is shown in Figure 7.

```
CMD: A Update                                                    / scroll
                             Operations List
     Op.  -------JES-------                               Err. Work
CMD  Num. Name     Number    Status    Reason             Code Stn.
---  ---- -------- --------- --------- ----------------------------- ---- ----
        1 DUMMYJOB           Completed                               DUMY
 _     10 OPCAO1             Completed                               NV04
 _     11 RMF                Error                              U001 NV04
 _     12 RMF                Waiting                                 NV04
 _     20 OPCNONST           Completed                               NV04
 _     30 OPCBTCH  JOB09193  Completed                               CPU1
 _     40 OPCNONSP           Completed                               NV04
 _     50 OPCAO1             Completed                               NV04
 _     56 CICSFILE           Completed                               NV04
 _     57 CICSFILE           Completed                               NV04
 _     58 IMSDB              Completed                               NV04
 _     59 IMSDB              Completed                               NV04
```

Figure 7. TWS Operations Interface Panel

You can scroll left and right with the PF11 (Next) and PF10 (Previous) keys. If more data is available than is displayed on the screen, use the PF8 (Down) or PF7 (Up) keys to scroll the data up or down.

For details about the different column values, see the online help or the description of the INGOPC command in *IBM Tivoli System Automation for z/OS Operator's Commands*.

Figure 8 is displayed if you press the PF11 key.

```
CMD: A Update                                                     / scroll
                              Operations List
      Op.  Job      Planned Start  Planned End    Operation Arr. Deadline
CMD  Num. Name     Date     Time  Date     Time  Date      Time  Date     Time
---  ---- -------- -------- ----- -------- ----- -------- ----- -------- -----
        1 DUMMYJOB 05/08/09 09:53 05/08/09 09:53 05/07/25 08:00 05/07/25 24:00
_      10 OPCAO1   05/08/09 09:53 05/08/09 09:53   /  /     :    05/07/25 24:00
_      11 RMF      05/08/09 09:53 05/08/09 09:53   /  /     :    05/07/25 24:00
_      12 RMF      05/08/09 09:53 05/08/09 09:53   /  /     :    05/07/25 24:00
_      20 OPCNONST 05/08/09 09:53 05/08/09 09:53   /  /     :    05/07/25 24:00
_      30 OPCBTCH  05/08/09 09:53 05/08/09 09:53   /  /     :    05/07/25 24:00
_      40 OPCNONSP 05/08/09 09:53 05/08/09 09:53   /  /     :    05/07/25 24:00
_      50 OPCAO1   05/08/09 09:53 05/08/09 09:53   /  /     :    05/07/25 24:00
_      56 CICSFILE 05/08/09 09:53 05/08/09 09:53   /  /     :    05/07/25 24:00
_      57 CICSFILE 05/08/09 09:53 05/08/09 09:53   /  /     :    05/07/25 24:00
_      58 IMSDB    05/08/09 09:53 05/08/09 09:53   /  /     :    05/07/25 24:00
_      59 IMSDB    05/08/09 09:53 05/08/09 09:53   /  /     :    05/07/25 24:00
_
```

Figure 8. TWS Operations Interface Panel, Screen 2

Figure 9 is displayed if you press the PF11 key.

```
CMD: A Update                                                     / scroll
                              Operations List
      Op.  Job      Actual Start   Actual End     Est.  Act.       Predecessors
CMD  Num. Name     Date     Time  Date     Time  Dur.  Dur.  Pri. Num.   Comp
---  ---- -------- -------- ----- -------- ----- ----- ----- ---- ----   ----
        1 DUMMYJOB   /  /     :   05/07/25 11:02 00:01 00:00   5    0      0
_      10 OPCAO1   05/07/25 11:02 05/07/25 11:02 00:01 00:00   5    1      1
_      11 RMF        /  /     :   05/07/25 11:02 00:01 00:00   5    1      1
_      12 RMF        /  /     :     /  /     :   00:01   :      5    1      0
_      20 OPCNONST 05/07/25 11:02 05/07/25 11:02 00:01 00:00   5    1      1
_      30 OPCBTCH  05/07/25 11:02 05/07/25 11:02 00:01 00:00   5    1      1
_      40 OPCNONSP 05/07/25 11:03 05/07/25 11:03 00:01 00:00   5    1      1
_      50 OPCAO1   05/07/25 11:03 05/07/25 11:03 00:01 00:00   5    1      1
_      56 CICSFILE 05/07/25 11:03 05/07/25 11:03 00:01 00:00   5    1      1
_      57 CICSFILE 05/07/25 11:03 05/07/25 11:03 00:01 00:00   5    1      1
_      58 IMSDB    05/07/25 11:03 05/07/25 11:03 00:01 00:00   5    1      1
_      59 IMSDB    05/07/25 11:03 05/07/25 11:03 00:01 00:00   5    1      1
_
```

Figure 9. TWS Operations Interface Panel, Screen 3

Figure 10 is displayed if you press the PF11 key.

```
CMD: A Update                                                     / scroll
                              Operations List
      Op.  Job      Job  High -Restart & Cleanup- -------Workstation-------
CMD  Num. Name     Sts  RC   Mode      Status    Name Type     Status  Sub
---  ---- -------- ---- ---- --------- --------- ---- -------- ------- ---
        1 DUMMYJOB         0 None                DUMY General  Unknown
_      10 OPCAO1           0 None                NV04 General  Active
_      11 RMF             0 None                NV04 General  Active
_      12 RMF             0 None                NV04 General  Active
_      20 OPCNONST        0 None                NV04 General  Active
_      30 OPCBTCH  Rel.   4 None                CPU1 Computer Active
_      40 OPCNONSP        0 None                NV04 General  Active
_      50 OPCAO1          0 None                NV04 General  Active
_      56 CICSFILE        0 None                NV04 General  Active
_      57 CICSFILE        0 None                NV04 General  Active
_      58 IMSDB           0 None                NV04 General  Active
_      59 IMSDB           0 None                NV04 General  Active
_
```

Figure 10. TWS Operations Interface Panel, Screen 4

Displaying TWS Special Resources

If you specify TYPE=SR, this will select TWS Special Resources for display. To reduce the number of special resources that are listed, you can use the optional parameter of SRNAME= to specify the special resource name.

In OUTMODE=LINE, a set of messages will be returned that contains all the data for the selected special resources.

The fullscreen interface is shown in Figure 11.

```
CMD: A Update                                             / scroll
                        Special Resources List
                                              --Actual-- -Default--
CMD  Name                                     Av. Quant. Av. Quant.
---  -------------------------------------    --- ------ --- ------
  _  ING.KEY4.APL.BLSJPRMI.DOWN               No     1 Yes    1
  _  ING.KEY4.APL.BLSJPRMI.UP                 Yes    1 Yes    1
  _  ING.KEY4.APL.CICS.DOWN                   Yes    1 Yes    1
  _  ING.KEY4.APL.CICS.UP                     No     1 Yes    1
  _  ING.KEY4.APL.CICS_SA_PPI.DOWN            No     1 Yes    1
  _  ING.KEY4.APL.CICS_SA_PPI.UP              Yes    1 Yes    1
  _  ING.KEY4.APL.CICSBI1.DOWN                No     1 Yes    1
  _  ING.KEY4.APL.CICSBI1.UP                  Yes    1 Yes    1
  _  ING.KEY4.APL.CICSBI1_NC.DOWN             Yes    1 Yes    1
  _  ING.KEY4.APL.CICSBI1_NC.UP               No     1 Yes    1
  _  ING.KEY4.APL.CICSBI1_TS.DOWN             Yes    1 Yes    1
  _  ING.KEY4.APL.CICSBI1_TS.UP               No     1 Yes    1
```

Figure 11. TWS Special Resources Interface Panel

If more data is available than is displayed on the screen, use the PF8 (Down) or PF7 (Up) keys to scroll the data up or down.

For details about the different column values, see the online help or the description of the INGOPC command in *IBM Tivoli System Automation for z/OS Operator's Commands*.

Displaying TWS Workstations

If you specify TYPE=WS, this will select TWS Workstations for display. To reduce the number of workstations that are listed, you can use the optional parameter of WSNAME= to specify the workstation name.

In OUTMODE=LINE, a set of messages will be returned that contains all the data for the selected workstations.

The fullscreen interface is shown in Figure 12.

```
CMD: A Update                                             / scroll
                        Work Stations List
                        Reporting  JCL              Alt. Para.
CMD  Name Status  Type   Attribute  Prep STC WTO ReRoute WS   Server
---  ---- ------- ------ ---------- ---- --- --- ------- ---- ------
  _  NV03 Unknown General Automatic  No   No  No  No           No
  _  DUMY Unknown General Non        No   No  No  No           No
  _  CPU1 Active  Computer Automatic No   No  No  No           Yes
  _  NV04 Active  General Automatic  No   No  No  No           No
```

Figure 12. TWS Workstations Interface Panel

You can scroll left and right with the PF11 (Next) and PF10 (Previous) keys. If more data is available than is displayed on the screen, use the PF8 (Down) or PF7 (Up) keys to scroll the data up or down.

For details about the different column values, see the online help or the description of the INGOPC command in *IBM Tivoli System Automation for z/OS Operator's Commands*.

Figure 13 is displayed if you press the PF11 key.

```
CMD: A Update                                               / scroll
                              Work Stations List
         --Comp. Ops.-- --Int. Ops.---- -Started- --Ready-- -Waiting-
CMD  Name Num. eDur aDur Num. eDur aDur Num. eDur Num. eDur Num. eDur
---  ---- ---- ---- ---- ---- ---- ---- ---- ---- ---- ---- ---- ----
  _  NV03    0    0    0    0    0    0    0    0    0    0    0    0
  _  DUMY   12   11    0    0    0    0    0    0   26   20  115  115
  _  CPU1   13    0    1    0    0    0    2    0    0    0  102    8
  _  NV04   19    1    2    0    0    0    0    0    5    0   97    6
```

Figure 13. TWS Workstations Interface Panel, Screen 2

Displaying TWS Calendars

If you specify TYPE=CAL, this will select TWS Calendars for display. To reduce the number of calendars that are listed, you can use the optional parameter of CALENDAR= to specify the calendar name.

In OUTMODE=LINE, a set of messages will be returned that contains all the data for the selected calendars.

The fullscreen interface is shown in Figure 14.

```
CMD: No Commands allowed                                    / scroll
                           Calendar List

CMD  Name            Days Shift Description
---  ---------------- ---- ----- -----------------------------
     APC              8 0000  general APC calendar
     DEFAULT          8 0000  general APC calendar
```

Figure 14. TWS Calendar Interface Panel

If more data is available than is displayed on the screen, use the PF8 (Down) or PF7 (Up) keys to scroll the data up or down.

For details about the different column values, see the online help or the description of the INGOPC command in *IBM Tivoli System Automation for z/OS Operator's Commands*.

Specifying Additional LIST Criteria

Additional search criteria can be specified with INGOPC REQ=LIST by using the TWSPARM= parameter. TWSPARM= is only valid with REQ=LIST and OUTMODE=LINE and can be used to specify any valid combination of TWS/OPC LIST arguments and associated values.

The *TWS for z/OS Programming Interfaces* manual describes the TWS/OPC LIST arguments in detail. Arguments must match the current plan segment that is being

searched; for example, TYPE=OP searches the CPOP segment (current plan operations) so only CPOP arguments are valid with TYPE=OP.

For example:

```
INGOPC opc_controller,REQ=LIST,TYPE=OP,TWSPARM=(JOBCRT=Y),
                      OUTMODE=LINE
```

will display all operations with the critical job flag set to Y.

```
INGOPC opc_controller,REQ=LIST,TYPE=OP,OUTMODE=LINE,
                      TWSPARM=(JOBCRT=Y;OPNO=1)
```

will display all operations with the critical job flag set to Y and the operation number equal to 1.

```
INGOPC opc_controller,REQ=LIST,TYPE=APPL,TWSPARM=(JOBCRT=Y),
                      OUTMODE=LINE
```

is invalid because the JOBCRT argument is not valid with TYPE=APPL (segment type CPOC).

You can specify additional search criteria in two ways:

1. Firstly, via the command parameter TWSPARM=. TWS/OPC LIST arguments are specified as keyword value pairs separated by an equals sign (=). Pairs of data are separated by the semicolon character (;). For example:

   ```
   INGOPC ... TWSPARM=(PRIORITY=3;STATUS=A)
   ```

2. Secondly, via the default safe as passed to the INGOPC command. TWS/OPC LIST arguments are specified as keyword value pairs separated by an equals sign (=). Each pair is contained as a single line of a multiline message in the default safe. For example:

   ```
   twsparms.0 = 2
   twsparms.1 = 'JOBCRT = Y'
   twsparms.2 = 'STATUS = A'
   'PIPE STEM twsparms. | COLLECT | SAFE * '
   'PIPE NETV INGOPC ......'
   ```

If TWS/OPC LIST arguments are specified via the default safe and via the TWSPARM command parameter in the same invocation of INGOPC then the values specified via TWSPARM= will take precedence.

Modifying the Current Plan

To modify the Current Plan, use the INGOPC command with REQ=MOD and specify the type of TWS resource required from:

- APPL for Applications
- OP for Operations
- SR for Special Resources
- WS for Workstations
- CAL for Calendars

Alternatively you can use the modify line commands in the INGOPC display panels.

Line Mode Modifications

You can use the INGOPC command to modify TWS Current Plan resources in line mode. First, you must specify the TWS resource, and then specify the data that is to be modified.

You specify the TWS resource with, selection criteria parameters that are different for each TWS resource type, as shown in Table 2:

Table 2. TWS Resource Type Selection Criteria Parameters

TWS Resource Type	Selection Criteria Parameters	
APPL	**AD=**	The Application Description of the applications occurrence in the current plan.
	IA=	The Applications Input Arrival Time of the applications occurrence in the current plan.
OP	**AD=**	The Application Description of the application to which the operation belongs in the current plan.
	IA=	The Applications Input Arrival Time of the application to which the operation belongs in the current plan.
	OPNO=	The Operation Number of the operation in the current plan.
SR	**SRNAME=**	The Special Resource Name in the current plan of the required special resource.
WS	**WSNAME=**	The Work Station Name in the current plan of the required work station.

You can specify the data to be modified for a given TWS resource in two ways:

- Firstly, via the command parameter UPDATE=. The data are specified as keyword value pairs separated by an equals sign (=). Pairs of data are separated by the semi-colon character (;). For example:

```
INGOPC ... UPDATE=(PRIORITY=3;STATUS=A)
```

- Secondly, via the default safe as passed to the INGOPC command. The data are specified as keyword value pairs separated by ″ = ″ (the blanks either side of the equals sign are required). Each pair is contained as a separate message in the default safe. For example:

```
updateStem.0 = 2
updateStem.1 = 'PRIORITY = 3'
updateStem.2 = 'STATUS = A'
'PIPE STEM updateStem. | COLLECT | SAFE * '
'PIPE NETV INGOPC ......'
```

The valid keywords are derived from the TWS-related manual, *Tivoli Workload Scheduler for z/OS Programming Interfaces* (SH19-4545-00). Any keyword as specified in the ″Modify Request″, ″Arguments″ section may be used. Table 3 matches the INGOPC TYPE= parameter value to the TWS resource types.

Table 3. INGOPC TYPE= Parameters Matched to TWS Resource Types.

TYPE=	TWS Current Plan Resource	TWS Manual Section
APPL	CPOC	Modify CPOC Arguments
OP	CPOP	Modify CPOP Arguments
SR	CSR	Modify CSR Arguments
WS	CPWS	Modify CPWS Arguments

Modifications via Panel Interaction

TWS Applications

From a list of applications (TYPE=APPL) use the "A" (update) command code against an application. The panel shown in Figure 15 is displayed.

```
  EVJKYRQ1                    SA z/OS - Command Dialogs
  Domain ID   = IPSFM      ---------- INGOPC  ----------     Date = 07/25/05
  Operator ID = OPER1                                        Time = 07:22:37
                              Application Modification
   Application =>  RMFSTOX7
   IA Date/Time=>  0507251100        (YYMMDDHHMM)

   New IA      =>                    (YYMMDDHHMM)
   Deadline    =>                    (YYMMDDHHMM)
   Priority    =>
   Error Code  =>
   Status      =>                    (C or W)
   Group Def.  =>
   JCL Var.Tbl.=>
   Monitor ALL =>                    External Monitor all operations (Y or N)




  Command ===>
    PF1=Help     PF2=End     PF3=Return                       PF6=Roll
                                                              PF12=Retrieve
```

Figure 15. TWS Applications Modification Panel

Fill in the fields to achieve the desired result and press the ENTER key.

For details about the different fields see the online help.

TWS Operations

From a list of operations (TYPE=OP) use the "A" (update) command code against an operation. The panel shown in Figure 16 on page 28 is displayed.

```
EVJKYRQ2                    SA z/OS - Command Dialogs      Page   1 of 3
Domain ID   = IPSFM     ---------- INGOPC   ----------    Date = 07/25/05
Operator ID = OPER1                                       Time = 08:57:26
                          Operation Modification
  Application => OPCAO#TESTAD
  IA Date/Time=> 0507250800          (YYMMDDHHMM)
  Operation # => 60

  Oper. Cmd.  => _____           (EX=Execute/MH=Hold/MR=Release/NP=Nop
                                     UN=Un-Nop)
  Status      => _____              (A/C/E/I/R/S/U/W/*)
  Error Code  => _____
  JOB Name    => _____
  WS Name     => _____              Workstation job is to run on
  Description => _____
  Est. Duratn => ____               Estimated duration of operation (HHMM)
  Parallel Srv=> ____               Number of parallel servers used
  R1 Use      => ____               Number of type 1 resources used
  R2 Use      => ____               Number of type 2 resources used
  JCL Class   => _____              Job Class

Command ===>
   PF1=Help     PF2=End     PF3=Return                    PF6=Roll
                                          PF11=Next   PF12=Retrieve
```

Figure 16. TWS Operations Modification Panel

For details about the different fields see the online help.

Fill in the fields to achieve the desired result, then press the ENTER key or press
PF11 key to scroll to the next page. If you press the PF11 key, the panel shown in
Figure 17 is displayed.

```
EVJKYRQ3                    SA z/OS - Command Dialogs      Page   2 of 3
Domain ID   = IPSFM     ---------- INGOPC   ----------    Date = 07/25/05
Operator ID = OPER1                                       Time = 09:00:46
                          Operation Modification
  Auto. Error => ___              Automatic Error Completion (Y or N)
  Auto. Submit=> ____             Automatic JOB submission   (Y or N)
  Auto. Hold  => ___              Automatic JOB hold/release (Y or N)
  Time Depend.=> _____           Job is dependent on time   (Y or N)
  WLM critical=> _____           Critical WLM Job           (Y or N)
  WLM policy  => _____           WLM Assist Policies        ( /L/D/S/C)
  Cancel Late => ____             Cancel job if LATE         (Y or N)
  Highest RC  => __               Highest acceptable Return Code
  Form        => _____           Print form name
  OP. IA      => _____         Operation Input Arrival    (YYMMDDHHMM)
  OP. Deadline=> _____         Operation Deadline         (YYMMDDHHMM)
  Re-Route    => ____             Re-Route JOB to Alt. WS    (Y or N)
  User Data   => _____
  Re-startable=> ____             Operation is restartable   (Y or N)
  Deadline WTO=> _____           Issue deadline WTO         (Y or N)
  DSN Clean   => _____           Dataset Cleanup Type       (A/I/M/N)

Command ===>
   PF1=Help     PF2=End     PF3=Return                    PF6=Roll
                              PF10=Previous  PF11=Next   PF12=Retrieve
```

Figure 17. TWS Operations Modification Panel, Screen 2

For details about the different fields see the online help.

Fill in the fields to achieve the desired result, then press the ENTER key or press
PF11 key to scroll to the next page. If you press the PF11 key, the panel shown in
Figure 18 on page 29 is displayed.

```
EVJKYRQ4                SA z/OS - Command Dialogs     Page   3 of 3
Domain ID   = IPSFM     ---------- INGOPC  ----------   Date = 07/25/05
Operator ID = OPER1                                     Time = 09:18:07
                          Operation Modification
   Expanded JCL=>  _____         Expanded JCL Option     (Y or N)
   User SYSOUT =>  _____         User SYSOUT Support      (Y or N)
   Ext. Monitor=>  _____         External Monitor         (Y or N)




 Command ===>
    PF1=Help     PF2=End     PF3=Return                   PF6=Roll
                                    PF10=Previous          PF12=Retrieve
```

Figure 18. TWS Operations Modification Panel, Screen 3

Fill in the fields to achieve the desired result, then press the ENTER key.

For details about the different fields see the online help.

TWS Special Resources

From a list of special resources (TYPE=SR) use the "A" (update) line command
against a special resource. The panel shown in Figure 19 is displayed.

```
EVJKYRQ5                SA z/OS - Command Dialogs
Domain ID   = IPSFM     ---------- INGOPC  ----------   Date = 07/25/05
Operator ID = OPER1                                     Time = 09:21:04
                       Special Resource Modification
  SR Name     =>  ING.KEY1.APL.CICS_SA_PPI.DOWN_____

  Used For    =>  _____        (C/P/B/N)
  ON Error    =>  _____        ( /F/FX/FS/K)
  Deviation   =>  _____
  Available   =>  _____          (Y or N)
  Quantity    =>  _____

  Default Values
  Available   =>  _____          (Y or N)
  Quantity    =>  _____



 Command ===>
    PF1=Help     PF2=End     PF3=Return                   PF6=Roll
                                                           PF12=Retrieve
```

Figure 19. TWS Special Resources Modification Panel

Fill in the fields to achieve the desired result and press the ENTER key.

For details about the different fields see the online help.

TWS Workstations

From a list of workstations (TYPE=WS) use the "A" (update) line command against a work station. The panel shown in Figure 20 is displayed.

```
EVJKYRQ6                      SA z/OS - Command Dialogs
Domain ID   = IPSFM    ---------- INGOPC  ----------   Date = 07/25/05
Operator ID = USER1                                    Time = 09:23:52
                          Workstation Modification
   Workstation =>  NV01

   Reporting   =>  _____          (A/C/N/S)
   Par. Servers=>  _____          Number of parallel Servers
   R1 Resources=>  _____          Number of type 1 resources
   R2 Resources=>  _____          Number of type 2 resources
   Status      =>  _____          (A/F/O)
   START act.  =>  _____        (R/E/L)
   Alt. WS     =>  _____
   WS Linked   =>  _____          (L/U/ )




   Command ===>
     PF1=Help      PF2=End      PF3=Return                 PF6=Roll
                                                           PF12=Retrieve
```

Figure 20. TWS Workstations Modification Panel

Fill in the fields to achieve the desired result and press the ENTER key.

For details about the different fields see the online help.

Chapter 3. Monitoring using SDF

The Status Display Facility uses color to represent the various subsystem resource statuses such as error, warning, action, or informational states. Typically, a subsystem shown in green on a Status Display Facility status panel indicates that it is up, whereas red indicates a stopped or problem state.

The Status Display Facility status display panels can be tailored to present the status of system components in a hierarchical manner. The hierarchical display of status information is implemented using tree structures. A tree structure always starts with the system name as the root component. The "leaves" of the tree are the monitored resources.

Color can be propagated up or down the leaves of the tree structure based on the order of dependencies. The effect of propagation is to consolidate, at the root component, the status of all the monitored resources in that system. In this way, the color of the root component reflects the most important or critical status in a computer operations center. If all the monitored resources are green, the root component (the system) will be green.

TWS Automation provides additional Status Display Facility panels that monitor the events that occur in the following areas for all TWS regions defined to TWS Automation:

Applications in Error
> Shows the TWS applications that have encountered an error.

To use the TWS Automation Status Display Facility panels, enter SDF at a NetView panel command line.

```
 AOC10                     OPC MONITOR PANEL




         Critical Messages


         Applications in Error








                                                       06/20/05 17:17
   ===>
 PF1=HELP 2=DETAIL 3=RETURN    6=ROLL 7=UP 8=DN              12=TOP
```
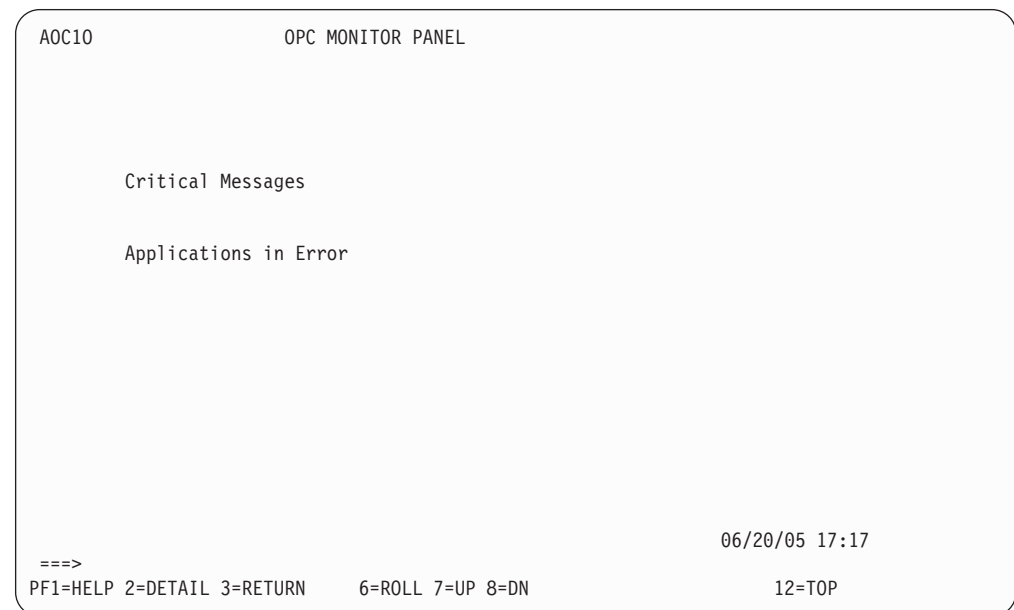
Figure 21. The TWS Monitor Panel

Chapter 4. NMC Display Support

SA z/OS TWS Automation will display the status of TWS applications or operations in error. In addition, the status of TSO users may optionally be displayed.

NMC Resource Definitions

TWS Naming Convention

For TWS status monitoring the anchor "TWS" enables the status of TWS operations to be accessed without the need to know the name of the currently active TWS Controller. TWS resources are represented by objects with a minor name of:

```
jobname
```

TSO Naming Convention

For TSO user monitoring the anchor "TSO" likewise enables the status of all TSO users to be accessed from one view. TSO users are represented by objects with a minor name of:

```
systemId_tsoUserName
```

where:

systemId   is the name of the system that the TSO user is logged onto.

tsoUserName   is the name of the TSO user.

NMC BuildViews for TWS objects

To show the TWS objects on a view off the main tree, use the buildviews statements shown in Figure 22:

```
VIEW=K1.OPC,
   ANNOTATION='OPC Monitoring in Sysplex K1'

WILDCARD=(?,*)

NONSNA=K1.OPC/ANCH*,
   QUERYFIELD=MYNAME
```

Figure 22. Sample TWS BuildViews Statements

To show the TSO objects on a view off the main tree, use the buildviews statements shown in Figure 23:

```
VIEW=K1.TSO,
   ANNOTATION='TSO Monitoring in Sysplex K1'

WILDCARD=(?,*)

NONSNA=K1.TSO/ANCH*,
   QUERYFIELD=MYNAME
```

Figure 23. Sample TSO BuildViews Statements

Chapter 5. Managing the PPI Receivers

This chapter describes how to start up and shut down the NetView PPI receivers. There are two types of receiver subsystems. The *Request* receiver is responsible for handling status updates and requests from the TWS exit. The *Command* receiver is responsible for handling commands issued from a batch program.

If requests for automation services from TWS need to be stopped for some reason, then the TWS Request Receiver in the appropriate SA z/OS Agent or NetView Agent should be stopped. Requests are typically starting or stopping a SA z/OS resource and are TWS operations assigned to a workstation with a name like NV**.

If batch interface commands are to be stopped for some reason, then the TWS Command Receiver in the appropriate SA z/OS Agent or NetView Agent should be stopped. Batch commands are typically used to gather information for further processing.

Use the following procedures to start and/or stop the desired PPI receivers. Because there may be more than one Command or Request receiver involved, you should check with your System Programmer to determine the correct subsystems to start or stop.

Subtopics:
- "Starting and Stopping the Request Receiver"
- "Starting and Stopping the Command Receivers" on page 36

Starting and Stopping the Request Receiver

The Request receiver is controlled by SA z/OS. It is defined to SA z/OS as a NON-MVS subsystem. If the system programmer has taken the defaults when customizing TWS Automation, then the name of the Request receiver will be TWSREQR. If this is not the case, then you must find out the SA z/OS subsystem name of the Request receiver from the system programmers.

To start the Request receiver, Issue the INGREQ REQ=START command against the appropriate subsystem, for example:

```
INGREQ TWSREQR/APL/SYS1 REQ=START
```

You should not have to start the Request receiver in normal circumstances because it should automatically start when the SA z/OS Agent registers with the Automation Manager.

To stop the Request receiver, Issue the INGREQ REQ=STOP command against the appropriate subsystem, for example:

```
INGREQ TWSREQR/APL/SYS1 REQ=STOP
```

Starting and Stopping the Command Receivers

The Command receivers are controlled by SA z/OS. They are defined to SA z/OS as NON-MVS subsystems. If the system programmer has taken the defaults when customizing TWS Automation, then there will be only one Command receiver and its name will be TWSCMDR. However, there can be multiple Command receivers and you need to find the names of them from the system programmers.

To start the Command receiver, Issue the INGREQ REQ=START command against the appropriate subsystem, for example:

```
INGREQ TWSCMDR/APL/SYS1 REQ=START
```

You should not have to start the Command receiver in normal circumstances because it should automatically start when the SA z/OS Agent registers with the Automation Manager.

To stop the Command receiver, Issue the INGREQ REQ=STOP command against the appropriate subsystem, for example:

```
INGREQ TWSCMDR/APL/SYS1 REQ=STOP
```

Part 3. Programmer's Reference

This part describes the information needed by system programmers to install and customize the TWS Product Automation of System Automation for z/OS.

Subtopics:

Chapter 6. Installing TWS Automation

This chapter describes the steps to follow when installing TWS Automation.

Enabling and Disabling TWS Automation

SA z/OS TWS Automation may be disabled and enabled by specification of subsystems with an application type of OPC.

To disable SA z/OS TWS Automation, do not specify any TWS applications in the Policy Database for the System that is to have TWS Automation disabled. Disabling occurs on a system by system basis, so by not linking TWS type applications to a system, automatically disables TWS Automation.

Disabling TWS Automation causes the message traps in the SA z/OS NetView to also be disabled. This will speed message processing for those systems that do not participate in TWS functions. Disabling TWS Automation does not prevent execution of the INGOPC command. As long as at least one system in the sysplex contains a Controller or Tracker, the INGOPC command will work.

If you disable SA z/OS TWS Automation for any reason, be sure to unlink the TWS Command Receiver NON-MVS subsystem and the TWS Request Receiver NON-MVS subsystem from systems for which TWS Automation is disabled.

To enable SA z/OS TWS Automation, specify the TWS applications for the Controllers and Trackers in the Policy Database of all systems that have either Controllers and Trackers running on them. Include any Trackers that belong to foreign Controllers. That is Controllers not present anywhere in the sysplex that the Trackers belong to.

Defining System Automation Policy

Several automation policy items are required for correct operation of TWS Automation. These policy items are:

- The Automation Operators that are required for function enablement.
- The required non-MVS subsystem that is the PPI request receiver. This subsystem provides support to pass requests from TWS to SA z/OS.
- The optional non-MVS subsystem that defines the PPI batch command receiver.
- The definition of TWS Controller, Tracker, Server, and Data Store.
- The definition of workstation names to be automatically activated on SA z/OS Agent startup (command interface).
- Definition of the status observer subsystem to ensure that SA z/OS status changes are reflected in TWS special resource statuses.

Detailed instructions for defining this configuration can be found in *IBM Tivoli System Automation for z/OS Defining Automation Policy* and in the *TWS add-on policy database, as shown in Figure 1 on page 6.

Define SA z/OS Automation Operators

The Automation Operators that are required for correct operation of SA z/OS TWS Automation are listed in Table 4.

Table 4. Automation Operators

Automation Operator	Description	Messages
OPCAMSTR	Main Automation Operator, required to enable SA z/OS TWS Automation	EVJ*
OPCAOPR2	TWS Request execution operator	none
OPCACMDR	TWS Batch Command Execution operator	none

These automation operator definitions can be found in the *TWS add-on sample PDB definitions under the Auto Operators policy with the name "TWS_AUTO_OPS".

Automated Operator Tasks

TWS is an SA z/OS-controlled subsystem. Normal definitions in the SA z/OS policy database can describe TWS. In addition, SA z/OS defines an automated operator task (called *automated function* by SA z/OS) for the TWS Controller in the system containing the Controller, as well as one for the TWS Tracker in each system. These automated operator tasks perform the TWS-requested functions in the SA z/OS application.

TWS Automation requires actions in a specific order. Changes in this order can result in unpredictable and undesirable results. To ensure that a proper sequence of processing is maintained, you must complete the actions in a single-thread fashion. In TWS, this is the responsibility of the user and is achieved through dependency control or critical resource specifications.

NetView maintains this control by ensuring that actions are executed sequentially through the use of automated operator tasks. Specify only one automated operator task for the TWS Controller functions and only one for the Tracker functions. Stipulating any additional automated operator tasks for TWS Automation results in loss of synchronization. This, in turn, can create an uncontrolled environment, requiring a substantial amount of operator/system programmer effort to recover, and additional loss of synchronization until a single automated operator task for the Tracker and Controller functions is reinstated. When TWS Automation detects any violations, it checks for out-of-sequence requests and stops processing for a specific application through an error code to TWS Automation.

However, separate automated operator tasks for Controller and Tracker are required. Running TWS Automation on the Controller system with a single automated operator task specified for both Controller and Tracker functions results in a lockout condition. Consider this especially on backup systems, which do not normally run Controller functions. If you specify only one automated operator task for both systems, each task runs properly until they become an active backup system and lock.

For the automated operator task OPCAMSTR, the operator ID must be AUTOPCP. For the automated operator task OPCAOPR2, you may specify whatever operator ID meets your installation standards. However, do not change the TWS Automation operator task names OPCAMSTR and OPCAOPR2.

RMTCMD Security Considerations

NetView® RMTCMD is used to communicate with remote domains (that is, gateway connected domains outside the system/sysplex where the TWS Controller is running). RMTCMD will be used if TWS Automation is controlling applications on a remote domain and recovery is required for the TWS Automation-controlled operations after the remote system or gateway has failed.

The operator IDs for OPCAMSTR and OPCAOPR2 (AUTOPCP and AUTOPCE or user specified operator ID) must have the appropriate NetView or RACF® authority to use RMTCMD on the local system (that is, the system running the TWS Controller). NetView or RACF definitions may also be required on the remote systems. For more details about the NetView or RACF security implications when using RMTCMD please refer to the *Tivoli NetView Security Reference*.

Define Optional Workstations

The batch jobs that execute NetView and SA z/OS commands may be submitted by any TWS Computer/Automated Workstation. However, if the NetView PPI receiver is not operational at the time of execution of the batch job, the batch job may optionally set the workstation that submitted it to an inoperative state. If this function is to be used, which is the default for the batch job, then it may be prudent to create additional batch job submission workstations to which these NetView-related batch jobs are assigned. This will allow the rest of the batch job stream to be submitted, whilst holding the NetView-related jobs until NetView starts.

The Workstations that are automatically re-enabled at SA z/OS startup are those defined on the WORKSTATION User message policy for either the Trackers or Controllers defined to SA z/OS. An example of this is shown in Figure 24, which shows the definition of workstation N001, where:

- CODE1 represents the name of the sysplex that the Batch Command Server non-MVS subsystem is running on.
- CODE2 represents the name of the system that the Batch Command Server non-MVS subsystem is running on.
- CODE3 is not used.

This allows the same Controller or Tracker subsystem definition to be run on different systems or sysplexes and the name of the workstation can be different on each sysplex or system combination.

```
Code 1          Code 2          Code 3          Value Returned
*_____  *_____  *_____  N001_____
```

Figure 24. Defining Workstation User Message Policy

Non-MVS Subsystem Definition for the TWS Request Server

This non-MVS subsystem is required to allow requests from Tivoli Workload Scheduler to SA z/OS.

See the add-on sample PDB *TWS that contains the subsystem definition TWSREQR. This subsystem definition contains the policy definition for the TWS Request Server.

For details of relationships see the *TWS add-on policy database and its documentation.

Non-MVS Subsystem Definition for the TWS Command Server

This non-MVS subsystem is required to allow commands from the batch command interface to SA z/OS.

See the sample add-on PDB *TWS that contains the subsystem definition TWS_CMDR. This subsystem definition contains the policy definition for the TWS Command Server.

For details of relationships see the *TWS add-on policy database and its documentation.

Define Workstation Domain Entries

Customize the WORKSTATION DOMAINS (ODM entry type) policy objects in the SA z/OS policy database and connect them to all systems where the TWS controller may run.

These policy objects map TWS workstations to NetView domain IDs to show where the requests should be routed to be executed.

Define Controller Details

Customize the CONTROLLER DETAILS (OCS entry type) policy objects in the SA z/OS policy database and connect them to all systems where the TWS controller may run and all systems where applications will be automated by TWS Automation (that is, Tracker only systems).

These objects specify the location of a controller and can be associated with a set of TWS special resources. See *IBM Tivoli System Automation for z/OS Defining Automation Policy* for more information.

Define System Details

Customize the OPC SYSTEM DETAILS policy objects (OEN entry type) in the SA z/OS policy database and connect them to systems where the TWS controller may run and to all systems where applications will be automated by TWS Automation (that is, Tracker only systems).

These objects contain control information for TWS Automation, such as the checking of subsystem status of START and STOP requests, the retention of critical messages, the operation reset delay, and PPI name of the Batch Interface Server. See *IBM Tivoli System Automation for z/OS Defining Automation Policy* for more details.

Define Special Resources Policy

If required, define TWS special resources as TWS SPECIAL RESOURCES policy objects (OSR entry type) in the SA z/OS policy database and link them to CONTROLLER DETAILS objects. See *IBM Tivoli System Automation for z/OS Defining Automation Policy* for more information.

Define or Modify Subsystem Messages/User Data

You must define each subsystem you wish to automate from TWS to SA z/OS. In many cases, you will also have to define OPCA and OPCACMD entries in the MESSAGES/USER DATA policy item for these subsystems (see "Executing TWS Requests with TWS Automation" on page 72).

Defining the SA z/OS Status Observer

SA z/OS TWS Automation provides a facility that echoes the status of SA z/OS resources in TWS Special Resources. This facility allows you to define TWS operations that will wait until SA z/OS resources reach a desired state. Currently only two desired states are allowed. The UP state is when the automation manager sets the resource to the AVAILABLE state. The DOWN state is when the automation manager sets the resource to the UNAVAILABLE state.

The Status observer is implemented as an automation agent function. This function registers with the automation manager and receives status changes. It then translates the status changes to the appropriate TWS special resources and issues an MVS subsystem broadcast to all TWS Controllers and Trackers on the system that the agent is running on.

The SA z/OS Status Observer is defined as a non-MVS SA z/OS subsystem. This subsystem should run on the system that contains the TWS Controller or alternatively a TWS Tracker.

For details of relationships see the *TWS add-on policy database and its documentation.

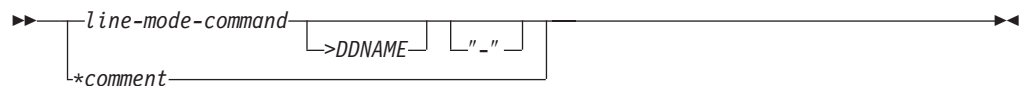# Chapter 7. Submitting NetView Commands from a Batch Job

This chapter describes how to execute NetView commands from a Batch job. This is particularly useful for Tivoli Workload Scheduler, but can be used stand alone without either Tivoli Workload Scheduler or Operations Planning for Control.

Sample Batch Job JCL

A sample batch job can be found in the System Automation for z/OS Installation library SINGSAMP. Member EVJSJ001 contains the sample JCL. The batch job must be run on the same system as the SA z/OS Agent that contains the Command receiver specified by the batch job. In most cases there will be a Command receiver running on every SA z/OS Agent. However, customization of the Command receivers can alter the names of the Command receivers and also the number and configuration of the Command receivers. You should check with your system programmers to determine the correct system and command receiver to use for these batch jobs.

Command Statement Syntax

The commands supplied to the batch job in the //SYSIN ddname have the following syntax:

```
►►─┬─line-mode-command────────────────────┬─────────────────────►◄
   │               └─>DDNAME─┘ └─"-"─┘     │
   └─*comment───────────────────────────────┘
```

1. All blank lines are ignored.
2. All lines starting with an asterisk (*) are comment lines and are printed in the output but otherwise ignored.
3. Comments on the end of commands are not allowed.
4. Comments are not allowed between continuation lines.
5. A command can be continued by appending a "-" (dash) to the line.
6. Command output normally goes to //SYSTSPRT.
7. Command output may be redirected to other DDNAMEs via the ">" (right angle bracket) symbol.
8. PIPE > stage is prohibited. Use PIPE QSAM instead.
9. Full Screen commands are not allowed.

Valid Command Types

Any command, clist or Rexx program that issues correlated line messages may be used.

This means almost all NetView commands, all SA z/OS commands that support OUTMODE=LINE and any clist or Rexx program that either issues SAY messages or PIPES the messages to CONSOLE.

The return code from the command can be used to stop the remaining commands from being executed. See the HIGHRC= parameter of the EVJRYCMD procedure definition in Part 3, "Programmer's Reference," on page 37.

Command Continuation

Commands are continued across lines by appending a dash to the end of the command, for example:

```
PIPE NETVIEW LIST STATUS=OPS | -
CONSOLE ONLY
```

Command Output Redirection

Normally command output is printed on the //SYSTSPRT DDNAME. However, the output of commands may be redirected to other DDNAMEs. This is achieved via the ">" symbol, for example:

```
PIPE NETVIEW LIST STATUS=OPS | CONSOLE ONLY >MYOUTPUT
```

This allows subsequent steps in the batch job or other batch jobs to use the output of the command for their own purpose.

The DCB characteristics of the output DDNAME should be as follows:

```
LRECL=132,RECFM=FB
```

Executing a Command on a Different NetView

Almost all SA z/OS commands can specify the TARGET= parameter to force the command to execute on the target system. If a command does not have this facility, for example the NetView LIST command, you can use PIPE labels to send the command to the appropriate NetView, for example:

```
PIPE CC dom01: LIST STATUS | CONSOLE ONLY
```

or even

```
PIPE CC dom01/auto1: LIST STATUS=OPS | CONSOLE ONLY
```

JCL for the Batch Command Interface

Figure 25 on page 47 shows the sample from the product sample library (SINGSAMP).

```
//*---------------------------------------------------------------***
//S0       EXEC PGM=IEFBR14
//CONCAT   DD  DSN=TEMP.CONCAT.LIST,
//             DISP=(MOD,DELETE,DELETE),
//             UNIT=SYSDA,SPACE=(1,1),AVGREC=M,
//             LRECL=132,RECFM=FB,STORCLAS=SMS
//*---------------------------------------------------------------***
//*%OPC SCAN
//S1       EXEC PGM=IKJEFT01,DYNAMNBR=30,REGION=4M,
//             PARM='EVJRYCMD &OWSID SERVER=EVJCMDRV HIGHRC=16'
//STEPLIB  DD  DSN=SYS1.NETV.V510.SEKGLNK1,DISP=SHR   NETVIEW LIBRARY
//*TEPLIB  DD  DSN=SYS1.NETV.V510.SCNMLNKN,DISP=SHR   NETVIEW V5 LIB
//SYSPROC  DD  DSN=SYS1.SAM.V310.SINGNREX,DISP=SHR    SA LIBRARY
//EQQMLIB  DD  DSN=SYS1.TWS.V810.SEQQMSG0,DISP=SHR    TWS LIBRARY
//OUTPUT   DD  SYSOUT=*
//CONCAT   DD  DSN=TEMP.CONCAT.LIST,
//             DISP=(MOD,CATLG),
//             UNIT=SYSDA,SPACE=(1,1),AVGREC=M,
//             LRECL=132,RECFM=FB,STORCLAS=SMS
//SYSTSPRT DD  SYSOUT=*
//SYSTSIN  DD  DUMMY
//SYSIN    DD  *
* THIS IS A COMMENT
MVS D A,L >OUTPUT
D NET,MAJNODES >CONCAT

PIPE NETV WHO | -
     NLOC /AUT/ | -
     CONS ONLY
INGLIST */APL/* OUTMODE=LINE >CONCAT
/*
```

Figure 25. Sample JCL for the Batch Command Interface

Please ensure that the appropriate NetView library is assigned to //STEPLIB. This library should contain the DSIPHONE module.

S0	This Step deletes a temporary listing data set that is used for concatenation of output from the command.
%OPC	This statement is used to tell TWS to begin scanning for TWS substitution variables and to replace them when found with their contents.
S1	This Step executes a BATCH TSO TMP to run the REXX command that sends commands to a SA z/OS Agent.
EVJRYCMD	This is the Command that runs to process batch commands.
&OWSID	This is a Tivoli Workload Scheduler substitution variable that represents the name of the workstation that submitted the job.
//STEPLIB	The NetView library SEKGLNK1 (or equivalent) is used to provide the DSIPHONE Rexx function. Please substitute the correct library name for the appropriate release of NetView that is being used by SA z/OS.
	If Module EQQYCOM cannot be found in the system LINK LIST, then concatenate the appropriate TWS Load library here.
//SYSPROC	The SA z/OS library that contains the EVJRYCMD Rexx procedure.
//EQQMLIB	The Tivoli Workload Scheduler for z/OS message library.
//OUTPUT	Optional output DDname for command output redirection.

//CONCAT	Optional output DDname for command output redirection. In this case a data set that will have successive command output concatenated to it.
//SYSTSPRT	Required TSO TMP output DDNAME.
//SYSTSIN	Required TSO TMP command input DDNAME. Dummied out because the only command to be executed is in the parameter to the TSO TMP.
//SYSIN	Commands to be executed in the SA z/OS Agent.

EVJRYCMD Description

Purpose

EVJRYCMD is a REXX procedure that issues commands to a SA z/OS agent and receives the results of those commands.

```
►►──EVJRYCMD──wsid─┬────────┬──┬─SERVER=EVJCMDRV─┬──┬─TIMEOUT=60──────┬──►
                   └─NOWKSTS─┘  └─SERVER=server───┘  └─TIMEOUT=seconds─┘


 ►─┬─HIGHRC=0────────────────┬───────────────────────────────────────────►◄
   └─HIGHRC=return_code───────┘
```
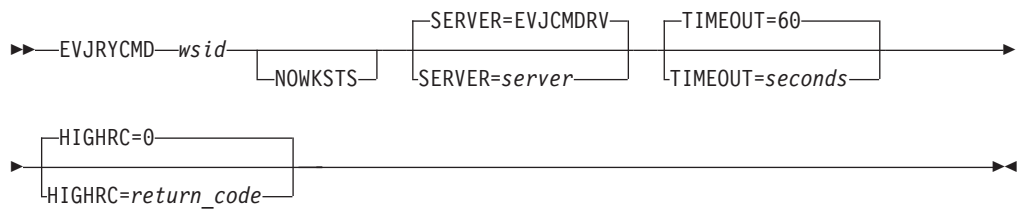
Parameters

wsid   This is a required parameter.

This parameter specifies the name of the Tivoli Workload Scheduler work station that submitted this batch job. This information is used by the command to disable the work station in the event that communications between the batch job and the SA z/OS Agent cannot be established. See "the NOWKSTS parameter" to modify this behavior.

This parameter must be specified, even if it is not to be used.

In the case of the NOWKSTS parameter being specified or the batch job being submitted manually or by a product other than Tivoli Workload Scheduler, specify any non-blank character sequence.

NOWKSTS

This parameter is optional.

This parameter modifies the behavior of the command. In the event of a failure in communications to the SA z/OS Agent, this parameter prevents the command from disabling the Tivoli Workload Scheduler workstation as defined by the *wsid* parameter.

If this parameter is not specified, any NetView PPI communications problem will cause the command to issue a TWS WSSTAT command to place the workstation offline.

SERVER=

This parameter is optional.

The default for this parameter is EVJCMDRV. This parameter specifies the name of the PPI receiver in the SA z/OS Agent NetView to which commands will be sent.

TIMEOUT=

This parameter is optional.

The default for this parameter is 60 seconds.

This parameter specifies the time in seconds that the batch job will wait for a command to execute in the System Automation Agent NetView. This timeout is applied separately to each command.

HIGHRC=

This parameter is optional.

The default for this parameter is 0 (zero).

This parameter specifies the highest acceptable Return Code for the job. Any return codes from commands that are less then or equal to this value will reset the JCL Step return code to zero. Any command return code that is greater than this value will be passed as the JCL Step return code.

Note: The JCL Step return code will be the highest return code of all the command return codes.

Usage

When the SA z/OS Agent is started, it will automatically issue a WSSTAT command to mark the work station online. The specifications of which work stations to mark online at agent restart is contained in the WORKSTATION message/user data policy for the tracker or controller. Multiple work stations may be defined. Work stations that are assigned to trackers should have their WORKSTATION policy defined to the same trackers that they are assigned to. See "Define Optional Workstations" on page 41.

Each command is submitted in turn and the results of the command are retrieved. These results are then written to either SYSTSPRT or to the output redirection DDNAME.

Chapter 8. Using TWS Special Resources

This chapter describes the TWS Special Resources created by SA z/OS and how to use them.

SA z/OS can dynamically create TWS special resources based on the status of SA z/OS resources. These TWS special resources can in turn be used to control the flow of applications and operations in TWS.

TWS Special Resource Definition

SA z/OS creates TWS Special Resources if allowed to via policy definitions. The definition of the name of these special resources is as defined in "TWS Automation Special Resources" on page 8.

Each SA z/OS Resource (application, application group, system or system group) has two TWS special resources. One tracks the state of the SA z/OS resource in the UP case. The other tracks the state of the SA z/OS resource in the DOWN case. Setting the availability of these two TWS special resources are independent of each other. It is possible for the SA z/OS resource to have both the UP and DOWN TWS special resources UNAVAILABLE. This can occur when the SA z/OS resource is starting for example. It is neither UP or DOWN.

It should not normally be possible to have both TWS special resources AVAILABLE at the same time.

Enabling SA z/OS TWS Special Resources

To enable the SA z/OS TWS Special Resource tracking, do the following:

1. Ensure that the SA z/OS Resources that are to be monitored are defined SA z/OS

   All these policy items are described in *IBM Tivoli System Automation for z/OS Defining Automation Policy* in the section "Defining Automation for OPC Components":

   a. Set the OPCA PCS Special Resources Policy.

      Use NO if you do not want any Special Resources Set.

      Use ALL if you want ALL SA z/OS Resources echoed as TWS Special Resources (this will create a large number of TWS special resources).

      Use YES if you want a selection of SA z/OS Resources echoed as TWS Special Resources.

   b. If YES was specified above, ensure that the TWS Special Resources policy item is updated with the appropriate resource masks and linked to the appropriate systems via the WHERE USED entry.

2. Ensure that the definitions for the TWS Status Observer are entered into the Automation Policy. The instructions for this are given in "Defining the SA z/OS Status Observer" on page 43.

3. Ensure that TWS option RESOPTS DYNAMICADD(YES) is specified.

Using SA z/OS TWS Special Resources in an Application

Holding an Operation until an SA z/OS Resource Reaches a Desired State

To use a SA z/OS special resource to hold an operation until the appropriate status is achieved do the following:

1. Create the special resource in the TWS Database.

   Use the TWS ISPF dialog to create the special resource. Set the Availability of the special resource to N, as shown in Figure 26.

```
------------------------ CREATING A SPECIAL RESOURCE ------------------------
Option ===>

Select one of the following:

1 INTERVALS  - Specify intervals
2 WS         - Modify default connected workstations

SPECIAL RESOURCE    ===> ING.KEY1.APL.CICSK1G.UP
TEXT                ===>
SPECRES GROUP ID    ===>
Hiperbatch          ===> N DLF object Y or N
USED FOR            ===> B Planning and control C , P , B or N
ON ERROR            ===>    On error action F , FS , FX , K or blank



Defaults
  QUANTITY          ===> 1      Number available 1-999999
  AVAILABLE         ===> N Available Y or N


F1=HELP      F2=SPLIT     F3=END      F4=RETURN    F5=RFIND     F6=RCHANGE
F7=UP        F8=DOWN      F9=SWAP     F10=LEFT     F11=RIGHT    F12=RETRIEVE
```

Figure 26. Creating a Special Resource

2. Create the Operations in the application:

   The first operation should submit the batch job to execute the requested function.

   The second operation runs at a General Completion Workstation and waits for the appropriate Special Resource, as shown in Figure 27.

```
-------------------------------- OPERATIONS ---------------- Row 1 to 2 of 2
Command ===>                                          Scroll ===> CSR

Enter/Change data in the rows, and/or enter any of the following
row commands:
I(nn) - Insert, R(nn),RR(nn) - Repeat, D(nn),DD - Delete
S - Select operation details, J - Edit JCL
Enter the TEXT command above to include operation text in this list, or,
enter the GRAPH command to view the list graphically.

Application            : JKOPCTST1      Test Batch Iface

Row  Oper    Duration  Job name  Internal predecessors      Morepreds
cmd  ws  no. HH.MM.SS                                        -IntExt-
''''  N001 001 00.00.01  SAMPJOB   __ __ __ __ __ __ __         0 0
''''  GAC1 005 00.05.00  _____  001 __ __ __ __ __ __          0 0
****************************** Bottom of data ******************************
```

Figure 27. Creating the Operations

3. The Special resource for operation 005 is as shown in Figure 28.

```
----------------------------- SPECIAL RESOURCES ------------- Row 1 to 1 of 1
Command ===>                                           Scroll ===> CSR

Enter/Change data in the rows, and/or enter any of the following
row commands:
I(nn) - Insert, R(nn),RR(nn) - Repeat, D(nn),DD - Delete


Operation              : GAC1 005

Row  Special                                   Qty    Shr Keep On
cmd  Resource                                         Ex  Error
''''  ING.KEY1.APL.CICSK1G.UP                   1     S   _
****************************** Bottom of data ******************************
```

Figure 28. Special Resource for Operation 005

4. Make sure you define the Special Resource toTWS with an initial Availability of
   N.

In this case Operation Number 005 will wait until SA z/OS sets the special
resource ING.KEY1.APL.CICSK1G.UP to Y. This will only happen if the observed
and desired status of CICSK1G/APL/KEY1 are both AVAILABLE.

Starting or Stopping an SA z/OS Resource

To start or stop a SA z/OS Resource, use the previous section as a base.

1. In the JCL for job SAMPJOB copy the sample job EVJSJ001 from SINGSAMP
   and tailor it for your environment.
2. Put the INGREQ command in the //SYSIN and specify the OUTMODE=LINE
   option for INGREQ.
3. If you are starting a resource (APL or APG) update the Special Resource for the
   operation 005 to reflect the name of the resource specified in the INGREQ
   command. e.g. for INGREQ TEST/APG/SYS1 use special resource
   ING.SYS1.APG.TEST.UP.
4. If you are stopping a resource (APL or APG) update the Special Resource for
   the operation 005 to reflect the name of the resource specified in the INGREQ
   command. e.g. for INGREQ TEST/APG/SYS1 use special resource
   ING.SYS1.APG.TEST.DOWN.
5. Remember to create the special resource in the TWS Database via option 1.6 in
   the TWS dialogs.

The operation is now ready for LTP and Current Plan planning functions.

When TWS submits the first operation, the JCL will run the Batch Command
Interface and execute the INGREQ command on the SA z/OS Agent. SA z/OS
will then process the command and issue the appropriate orders to the Agents to
achieve the desired status. When the resource has achieved the desired status,
SA z/OS will notify TWS that this has occurred by updating the special resource.
This will cause operation number 005 to be marked Complete - especially if you
assign it to a General Non-Reporting work station. Operations and Applications
that have a predecessor of operation number 005 will now be able to run.

Chapter 9. The Structure of TWS Request Automation

This chapter explains the structure of TWS request automation in some detail.

Flow Overview

TWS Automation is an interface between NetView, TWS, and SA z/OS. These components provide the facilities which make up the interface. This section provides an introduction to these components and their interactions.

Initialization

Initialization involves the following two sequences:

1. Initialization of the TWS components.
2. Initialization of TWS Automation functions in each NetView. TWS Automation initialization includes the automated recovery sequences described in "Automated Recovery Functions" on page 116.

Request Flow

This section contains a detailed description of the flow of a request from TWS to NetView and the return confirmation. This flow provides an explanation of the involved modules.

Figure 29 on page 56 uses a request to start RMF™, located in a NetView domain NVREG with a workstation definition of NV04. This request is an operation in a TWS-defined application known as MAINT.
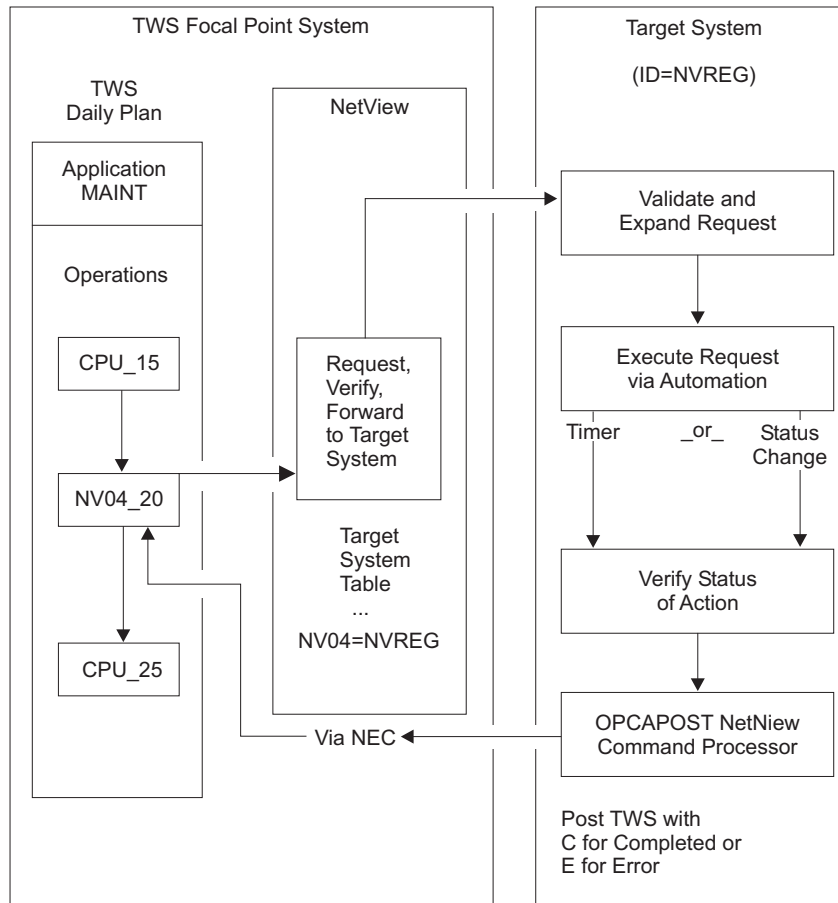
Figure 29. NetView-TWS Interface Flow. Syntax and definition errors, target system availability, recovery, and resynchronization via TWS API and NetView program-to-program interface are not shown in this example.

Using dependency control to ensure an orderly flow of operations, TWS defines the TWS-controlled application named MAINT. TWS defines the application on an automatic general workstation, specifying the NetView to which the request is sent. NV*xx* specifies a NetView automatic general workstation with a NetView domain index of *xx*, which is resolved in the Controller NetView into the target NetView domain ID through the definitions in the SA z/OS policy database. TWS can define the NV*xx* workstation with all regular specifications, such as parallel servers and special resources.

In the MAINT example in Figure 29, TWS defines the last batch application processed before starting RMF with an operation number of 15. Once this completes properly, the normal TWS dependency control readies the NV04_20 operation on the NV04 workstation. This signifies that the request contained within the operation description field is sent to the NetView with a domain ID of NVREG.

TWS Automation uses the NetView PPI to transfer the request from TWS to NetView. This transfer is through the EQQUX007 exit in the OPC/ESA controller.

EQQUX007 Exit

Each change of status on any workstation causes TWS to call user exit 7 (EQQUX007). The TWS Automation user exit EVJUX007 calls modules EVJ07001 and EVJ07004.

- EVJ07001 sends automation commands and data across the NetView PPI for all status changes on NV*xx* workstations.
- EVJ07004 WTO's Operation status information for any operation that ends in Error or is changed from Error state to any other TWS state. This information is used to update SDF and NMC monitoring of TWS operations.
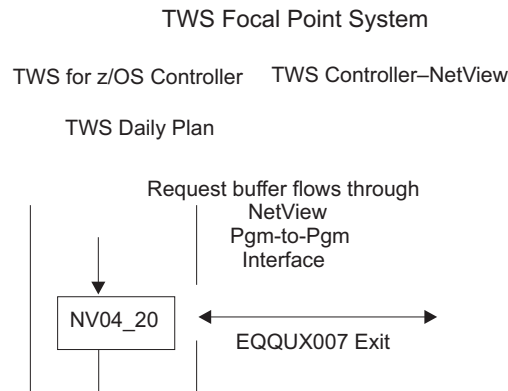
Figure 30 shows the flow of the EVJ07001 exit.

TWS Focal Point System

TWS for z/OS Controller   TWS Controller–NetView

    TWS Daily Plan

Request buffer flows through
NetView
Pgm-to-Pgm
Interface

NV04_20   ⟵⟶

      EQQUX007 Exit

Figure 30. EQQUX007 Exit

When an NV*xx* workstation moves to the R status, the workstation generates a request buffer. Fields pointed to by registers in the EQQUX007 exit provide all of the data for the request buffer. For the layout of the fields in the request buffer, see Table 6 on page 94 and Table 7 on page 94.

TWS Automation supplied EQQUX007 exit logic verifies that all fields exist (except the optional request parameter fields). If this exit logic determines that any field is missing or the value is not valid, it issues an error WTO and changes the operation to E status, with an error code indicating a user-definition error. Since the EQQUX007 exit contains no capability to directly change the status of a TWS operation when an error code is posted to TWS, the EQQUX007 exit uses the EQQUSINT module to respond.

If the information is correct, TWS builds the request buffer and calls the CNMCNETV module, which is the NetView program-to-program interface module. This module transfers the request to the Controller-NetView, where TWS verifies the return codes from the call function to ensure that there are no errors. If TWS detects errors, the EQQUSINT module changes the status to E (ended-in-error), with the error code on the basis of the PPI module return code. The module issues a WTO and completes processing the EQQUX007 logic. TWS Automation then restores registers and returns control to TWS.

If the TWS Automation EQQUX007 exit is unable to load the CNMCNETV module or use it to send data, it directs TWS to mark the requested operation in error, with an error code of UNTV. TWS Automation will attempt to reset operations which have ended in a UNTV error, subject to a user-defined time limitation, whenever the TWS controller is restarted.

Program-to-Program (PPI) Interface Dispatcher

The NetView program-to-program interface passes the request buffer to the PPI dispatcher task in the SA z/OS application. The PPI dispatcher task (EVJTOPPI), a

NetView subtask, receives the requests for an SA z/OS action from the buffers from the EQQUX007 exit. Figure 31 shows this flow.
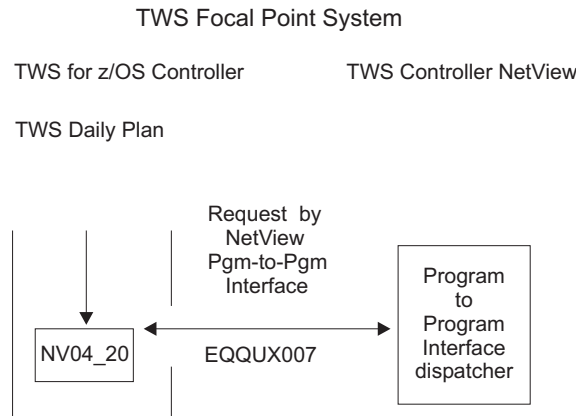
TWS Focal Point System

TWS for z/OS Controller   TWS Controller NetView

TWS Daily Plan

Figure 31. PPI Dispatcher

On the basis of the sending task identifier, the PPI dispatcher determines the function in SA z/OS that is sent. For TWS Automation, the dispatcher selects the verify function.

Verify Module (EVJESPVY)

The verify module, which runs on a NetView autotask, runs only in the Controller NetView. This module receives the action request buffer from the PPI dispatcher task. Figure 32 shows this process.
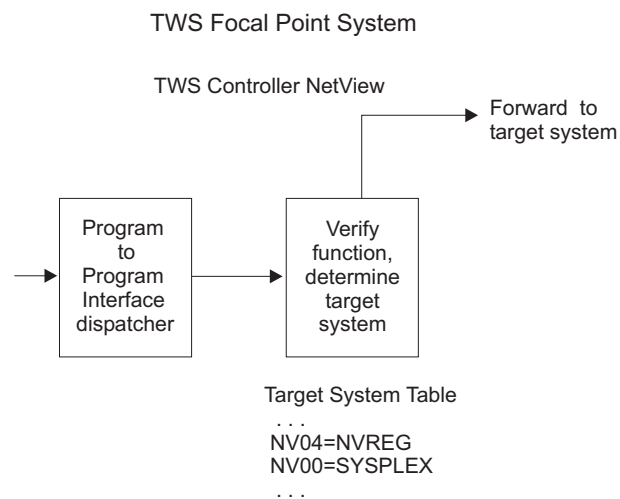
TWS Focal Point System

TWS Controller NetView

Target System Table
. . .
NV04=NVREG
NV00=SYSPLEX
. . .

Figure 32. Verify Module

The verify module uses the NV*xx* index to obtain the destination NetView domain ID from the SA z/OS policy database. If the relevant NV*xx* index specifies SYSPLEX, then all SA z/OS systems in the local sysplex are queried for the status of the application associated with the job name of the request. The destination is determined to be the system which has the application in the most active state.

If the destination NetView and the requesting NetView are the same, TWS Automation logs the request buffer and invokes the request module. If the

destination NetView and the requesting NetView are different, TWS Automation sends the request to the proper NetView domain by message forwarding.

If TWS Automation does not find the NV*xx* index then TWS Automation issues a message, posts the operation status to E (ended-in-error, U003), and logs the results. No communications can occur with this workstation until the definition is corrected. On the domain where the TWS controller is running, the workstation must be defined in the WORKSTATION DOMAINS policy object (ODM entry type). You must manually reset operations that are posted-in-error since TWS Automation carries out no automated recovery for definition errors.

If NV*xx* is associated with the sysplex on which the TWS controller is running (SYSPLEX keyword in the WORKSTATIONS DOMAIN entry) and TWS Automation does not find the job defined to any online SA z/OS in the local sysplex, then TWS Automation issues a message, posts the operation status to E (ended-in-error, S998), and logs the results. To cater for the situation where all domains where the job runs are offline, the operation will be retried if a gateway connection to another SA z/OS becomes active.

If TWS Automation successfully forwards messages, it logs the request buffer and returns control to the module. If TWS Automation cannot send the request, it issues an error message and logs it to indicate communication loss with the requested NetView domain. TWS Automation then posts the operation status to E (ended-in-error, S999) due to loss of contact. When TWS Automation re-establishes communications with this NetView domain, it checks for all outstanding errors because of loss of communications on this workstation. If TWS Automation finds any of these errors, it resets the TWS-operation status to R (ready), which re-invokes the EQQUX007 exit.

Request Module (EVJESPRQ)

The arrival of a request from the verify module drives the request module in the Tracker NetView. TWS Automation installs the request module on each system running an OPC/ESA Tracker. Figure 33 on page 60 shows the flow of this process.

The main function of the request module is to translate the TWS-generated request into a subsystem related command, or to schedule a user-defined function that is not related to a subsystem. The control flow of the module is shown in Figure 33 on page 60.
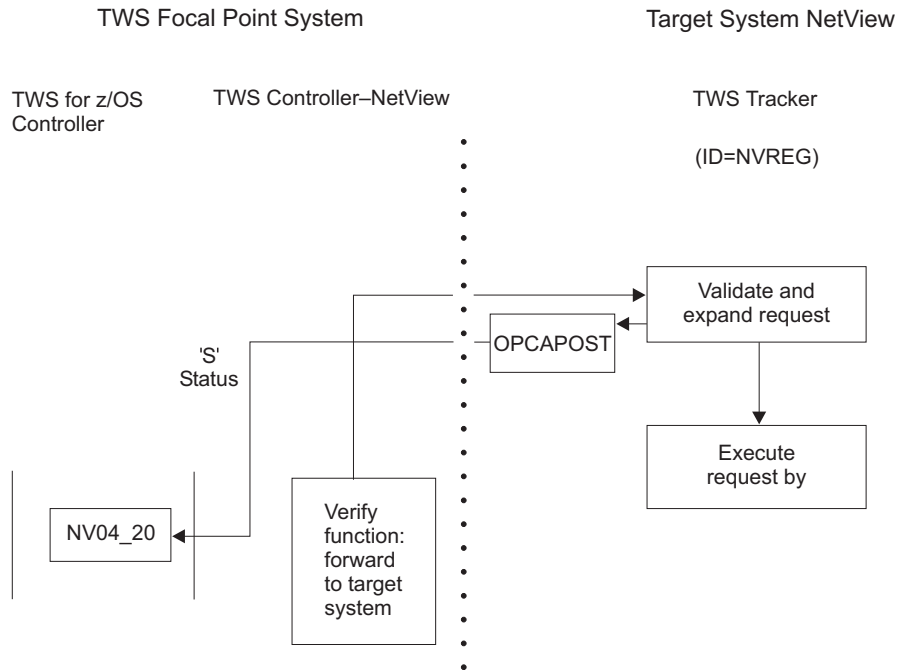
Figure 33. Request Module

If required, the request module uses definitions in the SA z/OS policy database to create the command that initiates the function requested. The policy database contains entries (OPCA, OPCACMD keywords; see Chapter 11, "MESSAGES/USER DATA Entries and USER E-T Pairs for TWS Automation," on page 77) from which the command text and the parameter syntax for the actual request are obtained. If any of these entries are not found, the processing cannot continue. The OPCAPOST module posts an error to TWS, which logs the error and issues a WTO. Since this is a user-definition error, TWS attempts no automation recovery. The user must correct the definitions and reset the operations in error.

In Figure 33, the request module translates the requested action in the buffer to the SA z/OS command required to start RMF. The SA z/OS command then starts RMF.

Except for starting, stopping, or recycling SA z/OS-controlled subsystems, other functions may require user programming. To support these functions, TWS Automation provides a user exit capability. For a detailed description of user responsibilities required to handle a user call, see Chapter 13, "Guidelines for User-Written Operations," on page 97.

For subsystem-related operations, the OPCAPOST command processor posts to TWS if the required entries are found in the policy database. TWS changes the status from R (ready) to S (started). TWS Automation then issues a timer request on the basis of the delay specified in the policy database (OPCA keyword, see "OPCA" on page 78), issues the command, and checks the return code. Then the request module terminates.

A change of subsystem status calls the status-change exit module. If the status change does not occur, the timer-driven module executes when the timer interval expires. This ensures that a request resulting in an unexpected status processes. For

example, if TWS requests a START operation, and the subsystem fails to start due to a JCL error or other problem, then the OPCAPOST module posts TWS with an error status.

TWS Automation dynamically generates the TWS request by using definitions in the policy database and dynamic substitution of command fragments on the basis of the parameters.

Status Change Module (EVJESPSC)

SA z/OS calls the status-change module for each change of status. This module determines whether a status change is the result of a previous TWS Automation request. If the status change is not the result of a previous request, TWS Automation ignores the status change. Figure 34 shows the flow of this process.

If an outstanding request for the changed subsystem exists, and the new status is compliant with the expected status, TWS Automation cancels the timer. OPCAPOST updates the TWS operation status to C (completed) status.

With the timer values properly set and the operation processing normally, the change of status should always occur before the timer interval expires.

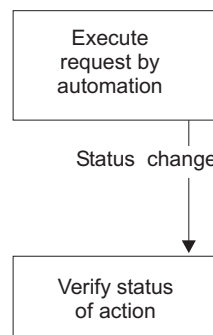Target System NetView

(TWS Tracker–NetView)

```
┌─────────────┐
│   Execute   │
│  request by │
│  automation │
└─────────────┘
       │
  Status  change
       │
       ▼
┌─────────────┐
│ Verify status│
│  of action  │
└─────────────┘
```

Figure 34. Status Change Module

Timer Module (EVJESPTE)

Under normal conditions, a request passed to SA z/OS results in the desired status change before the timer expires, and TWS Automation purges the timer. When this sequence does not occur, and the timer remains at the end of the timer interval, SA z/OS drives the timer module.
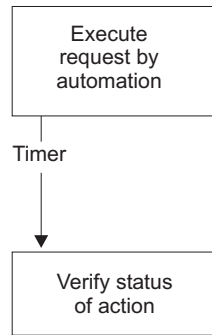
Target System NetView

(TWS Tracker–NetView)

Figure 35. Timer Module

| For subsystem-related functions, EVJESPTE compares the current status with the
| expected status. If a match is obtained, the OPCAPOST command processor posts
| a C (completed) status to TWS. If EVJESPTE determines a mismatch between the
| current and expected status, OPCAPOST posts an error to TWS for review by the
| TWS administrator. Figure 35 shows the flow of this process.

OPCAPOST Command Processor

The OPCAPOST command processor calls EQQUSINT, which passes the
completion code to the TWS Tracker in this system. The TWS Tracker forwards the
completion code to the system running the Controller through the mechanism used
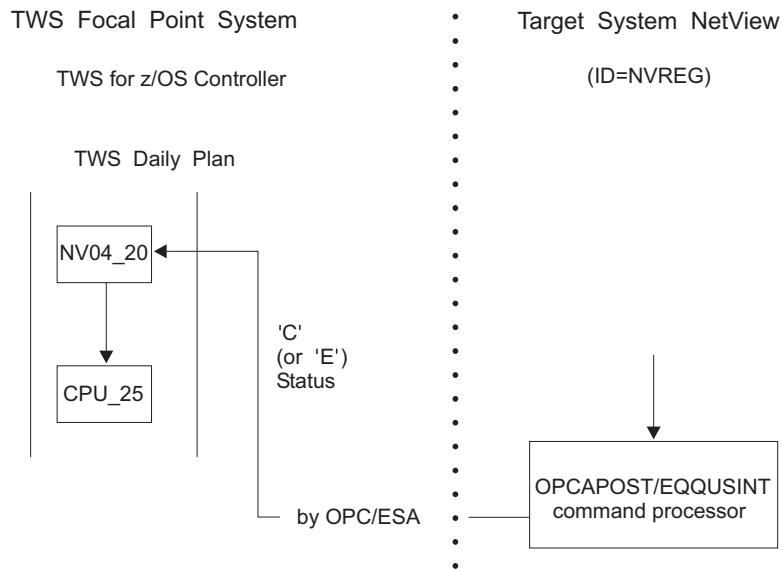by OPC/ESA. Figure 36 shows the flow of this process.

Figure 36. OPCAPOST Command Processor

Other functions use the OPCAPOST command. See "OPCAPOST" on page 91 for
documentation on the syntax.

This module completes the processing for this specific TWS operation. If the
request executes successfully, TWS Automation sets the TWS operation status to C
(completed) and normal TWS-dependency control allows the next operation to

start. See the CPU_25 batch job in Figure 36 on page 62. If the operation completes in error, TWS Automation sets an E status and a 4-character return code. The application does not continue processing until some intervention occurs. An operator or TWS Automation's recovery can sometimes provide this intervention.

Completion and Timer Flags

Both the status change and timer modules check for each other's completion. If one function completes first, the second function exits to avoid false double posting to TWS. Double posting is avoided by using timer and completion flags, as the following text discusses.

NetView schedules work on automated operator tasks on a first-in/first-out basis. Work elements resulting from the status change or timer modules become ready as NetView schedules them on the queue. Since NetView automated operator tasks process in a sequential manner, the queue can hold both the status change and the timer work elements at the same time. When this occurs, NetView must process only one work element, because handling both results in double posting to TWS, leading to errors in the TWS-defined application.

To avoid these errors, TWS Automation uses two flags in the automation status file entry. One of these flags is related to the status change module, the other to the timer module. When the modules are called, they examine the flags. If neither flag is on, the respective module turns on the flag associated with the active function and continues processing. If a flag is found on, the function exits, because the processing is completed by the other function while this work element was queued. This process depends on defining a single automated operator task for each NetView Tracker.

Chapter 10. Automating Applications with TWS Automation

This chapter explains how to set up TWS Automation in TWS and in SA z/OS.

Defining Automated TWS Applications

This section describes what you need to do when you define an application in TWS that you can automate using TWS Automation.

Note: This section contains some specific details about how to define applications and other items to TWS. However, it does not explain basic TWS functions because it assumes that you have a prerequisite knowledge of TWS and will refer to the TWS documentation when necessary.

Defining Information for TWS Automation in TWS

The information that is passed to TWS Automation is entered in standard TWS description fields. This information is used to route requests where they are verified and executed. When the request is completed, a status change for the operation is sent back to TWS. The minimum information that needs transferring to accomplish this is listed in Table 5.

Table 5. TWS Automation Items Defined in TWS

Definition in TWS	Information item	Refer to
General reporting workstations that represent target NetView domains	TWS workstation ID representing the NetView domain ID	"Defining the Target NetView Domains" on page 65
TWS-defined application making requests to TWS Automation	Application name	Application field in Figure 38 on page 67
Target subsystem, such as RMF, for which this function is executed	Job name	Job name field in Figure 38 on page 67
Operations executed within a job	Operation number or numbers	No. field in Figure 38 on page 67
Request and request parameters to be performed for the specific operation	A request, such as STOP, START, or CANCEL and optional parameters	Operation text field in Figure 39 on page 67 and Figure 40 on page 68

Defining the Target NetView Domains

To define a TWS request that TWS Automation can use, a workstation representing the target NetView domain is required. This workstation, which is defined with TWS using the standard TWS dialogs, should be a general, automatic reporting workstation. Its name *must* have the format

NV*xx*

Note: Reserve NV*xx* workstations for TWS Automation. Unpredictable and undesirable results may occur if these workstation names are used for other workstations.

Figure 37 shows a typical definition.

```
--------------------- BROWSING A WORK STATION DESCRIPTION --------------------
Command ===>

Enter the command R for resources , A for availability or M for access method
above.

Work station        : NV04
Description          : NetView Workstation for SYS4

Work station type    : General
Reporting attribute  : Automatic
FT Work station      : No
Printout routing     : SYSPRINT
Server usage         : Planning

Splittable           : No
Job setup            : No
Started task STC     : No
WTO                  : No
Destination          :

Transport time       : 00.00
Duration             :
Last updated by      : SAUSER    on 05/06/29 at 14.30
```

Figure 37. Sample NVxx Workstation Definition in TWS

Entries in the SA z/OS policy database (WORKSTATION DOMAINS policy object, entry type ODM) translate NV*xx* to an actual NetView domain ID. The automation programmer defines these entries. In this manner, the scheduler defining the TWS applications does not need to know the NetView domain ID names, but rather works with the workstation representation of those names. This allows changes to the relationship of workstations to NetView domain IDs without modifying the TWS definitions.

Note: You may use TWS database management dialogs or batch loader jobs to define the NV*xx* workstations.

Defining Applications for TWS Automation in TWS
Standard TWS application description panels are used to define applications that put requests to TWS Automation. The following items are defined:
- Application making the request
- Function requested

Application Making the Request: The application making the request is defined to TWS with operations specified on the NV*xx* workstation, as shown in Figure 38 on page 67.

```
-------------------------------- OPERATIONS ----------------- Row 1 to 2 of 2
Command ===>                                                Scroll ===> PAGE


Enter/Change data in the rows, and/or enter any of the following
row commands:
I(nn) - Insert, R(nn),RR(nn) - Repeat, D(nn),DD - Delete
S - Select operation details, J - Edit JCL
Enter the PRED command above to include predecessors in this list, or,
enter the GRAPH command to view the list graphically.


Application            : MAINT            Test for maint appl


Row  Oper      Duration Job name  Operation text
cmd  ws   no.  HH.MM.SS
'''' NV04 005  00.01.00 RMF_____  STOP_____


                                        ──▶ The subsystem
                                      ──▶ The operation
                                 ──▶ The NetView Domain ID workstation
```

Figure 38. Defining the MAINT Application in TWS

Function Requested: The function requested and the request parameters, if any, are not standard TWS definitions. Enter these fields in the **Operation text** field using blanks as delimiters.

Figure 39 shows an example of how to define a request to stop and start RMF.

```
-------------------------------- OPERATIONS ----------------- Row 1 to 2 of 2
Command ===>                                                Scroll ===> PAGE


Enter/Change data in the rows, and/or enter any of the following
row commands:
I(nn) - Insert, R(nn),RR(nn) - Repeat, D(nn),DD - Delete
S - Select operation details, J - Edit JCL
Enter the PRED command above to include predecessors in this list, or,
enter the GRAPH command to view the list graphically.


Application            : MAINT            Test for maint appl


Row  Oper      Duration Job name  Operation text
cmd  ws   no.  HH.MM.SS
'''' NV04 005  00.01.00 RMF_____  STOP_____
'''' NV04 010  00.01.00 RMF_____  CANCEL_____
```

Figure 39. 'Operations' TWS Panel Showing TWS Automation Requests

TWS Automation permits the inclusion of two optional parameters in the request buffer. The target system builds the required command with these parameters, using information contained in the SA z/OS policy database. Alternatively, the parameters pass control information to optional user-written modules. Figure 40 on page 68 shows an example of the request using these optional parameters.

```
--------------------------------- OPERATIONS ----------------- Row 1 to 2 of 2
Command ===>                                                Scroll ===> PAGE

Enter/Change data in the rows, and/or enter any of the following
row commands:
I(nn) - Insert, R(nn),RR(nn) - Repeat, D(nn),DD - Delete
S - Select operation details, J - Edit JCL
Enter the PRED command above to include predecessors in this list, or,
enter the GRAPH command to view the list graphically.

Application          : FORCE          Test for maint appl

Row  Oper    Duration Job name  Operation text
cmd  ws   no.  HH.MM.SS
''''  NV04 005  00.01.00  RMF_____  STOP FORCE IMM_____
```

Figure 40. Request Using Optional Parameters

Displaying TWS Automation Requests in TWS

Because TWS Automation requests are stored as operation text, you can view them
in TWS, as shown in Figure 41.

```
--------------------------- BROWSING OPERATIONS ---------------- ROW 1 OF 2
Command ===>                                                Scroll ===> PAGE

Enter the PRED command above to include predecessors in this list, or,
enter the GRAPH command above to view operations graphically.
Enter the row command S to select the details of an operation.

Application          : RMFBKUP          RMF Backup Processing

Row  Oper    Duration Job name  Operation text
cmd  ws   no.  time
'    NV04 005   0:01    RMF        STOP
'    NV04 010   0:01    RMF        START
***************************** BOTTOM OF DATA ********************************
```

Figure 41. Browsing Operations Including TWS Automation Requests

The following list defines several of the fields that are shown on the panel in
Figure 41.

NV04	Represents the target NetView domain or the sysplex the request is sent to.
RMFBKUP	The application submitting the request to TWS Automation.
RMF	Target subsystem. This looks like a job to TWS, but is actually a subsystem.
005 and 010	Standard operation sequence numbers used by TWS.
STOP and START	Requested function. There are no parameters in this example.

Example of an Application Making a Request

This section provides an example of how an application that puts a request to TWS
Automation is defined in TWS.

The application name is MAINT. This application consists of three operations:

- Stop RMF on the target system
- Schedule a batch job
- Restart RMF on successful completion of the batch job

Figure 42 shows the initial panel in the application creation process.

```
-------------------------- CREATING AN APPLICATION --------------------------
Command ===> oper

Enter/Change data below:
Enter the RUN command above to select run cycles or enter the OPER command
to select operations.


Application:
 ID               ===> MAINT_____
 TEXT             ===> RMF Maintenance_____   Descriptive text
 TYPE             ===> A          A - Application, G - Group definition
Owner:
 ID               ===> SAOPER_____
 TEXT             ===>        _____
                              Descriptive text of application owner
PRIORITY          ===> 5          A digit 1 to 9 , 1=low, 8=high, 9=urgent
VALID FROM        ===> 05/07/05   Date in the format YY/MM/DD
STATUS            ===> A          A - Active, P - Pending
AUTHORITY GROUP ID ===> _____    Authorization group ID
CALENDAR ID       ===> _____   For calculation of work and free days
GROUP DEFINITION  ===> _____   Group definition id
```

Figure 42. RMF Maintenance Application Primary Panel in TWS

In Figure 42, certain fields, such as calendar ID, are not used. However, TWS
Automation does not preclude the use of normal application and operation
functions.

Selecting OPER as a primary command allows the entry of the individual
operations for this application.

In Figure 43, three operations are defined. The first and third send requests to TWS
Automation in the NetView domain that is associated with the NV00 workstation.
The second is a batch job named RMFMAINT that performs the batch maintenance
tasks.

```
--------------------------------- OPERATIONS ----------------- Row 1 to 3 of 3
Command ===> text                                         Scroll ===> PAGE

Enter/Change data in the rows, and/or enter any of the following
row commands:
I(nn) - Insert, R(nn),RR(nn) - Repeat, D(nn),DD - Delete
S - Select operation details, J - Edit JCL
Enter the TEXT command above to include operation text in this list, or,
enter the GRAPH command to view the list graphically.


Application         : MAINT          RMF maintenance

Row  Oper     Duration  Job name  Internal predecessors          Morepreds
cmd  ws   no.  HH.MM.SS                                           -IntExt-
''''  NV00 001  00.01.00  RMF____   __ __ __ __ __ __ __ __          0  1
''''  CPU1 010  00.10.00  RMFMAINT  005 __ __ __ __ __ __ __          0  0
''''  NV00 015  00.01.00  RMF____   010 __ __ __ __ __ __ __          0  0
****************************** Bottom of data ******************************
```

Figure 43. Operations in the MAINT Application

Selecting TEXT as a primary command allows entry of the operation text. TWS
Automation uses the **Operation text** field to contain the request and up to two

optional parameters for operations with the workstation defined for TWS
Automation. Figure 44 shows the resulting operations text detail panel.

```
 ------------------------------ OPERATIONS ---------------- Row 1 to 3 of 3
 Command ===>                                             Scroll ===> PAGE

 Enter/Change data in the rows, and/or enter any of the following
 row commands:
 I(nn) - Insert, R(nn),RR(nn) - Repeat, D(nn),DD - Delete
 S - Select operation details, J - Edit JCL
 Enter the PRED command above to include predecessors in this list, or,
 enter the GRAPH command to view the list graphically.


 Application              : MAINT          RMF maintenance

 Row  Oper     Duration Job name  Operation text
 cmd  ws   no. HH.MM.SS
 ''''  DUMY 001  00.01.00  RMF_____   STOP_____
 ''''  CPU1 010  00.10.00  RMFMAINT   _____
 ''''  DUMY 015  00.01.00  RMF_____   START_____
 ***************************** Bottom of data ********************************
```

Figure 44. Operations Text Detail Panel

In the applications, TWS Automation defines TWS requests in a generic manner.
Figure 44 shows the MAINT application with the first and last operations defined
for the NetView workstation NV00. The requests that are forwarded to the
NetView workstation NV00 are STOP and START. These requests are expanded by
definitions in the policy database into commands; see "Executing TWS Requests
with TWS Automation" on page 72.

Handling Time Dependencies

If you require a time dependency, do not place the time consideration on the NV*xx*
defined operation because the status change drives the TWS user exit EQQUX007,
regardless of the timer status. For a general workstation, such as those defined for
TWS Automation, this occurs when all dependencies are fulfilled except the time
consideration.

To avoid this problem, define a dummy, non-reporting workstation. Place the timer
dependency on this dummy workstation. Define any dependencies on the dummy
workstation, which is the predecessor to the NV*xx* workstation. Once you satisfy
all other dependencies and complete the time dependency, the dummy timer
workstation completes immediately and starts the operation on the NV*nn*
workstation.

As an example, redefine the MAINT application shown in Figure 42 on page 69,
and Figures 43 and 44 on page 70, with a timer dummy workstation (TIMR) as the
first operation of the application. The panel in Figure 45 on page 71 shows this
new definition.

```
  -------------------------------- OPERATIONS ----------------- Row 1 to 3 of 3
  Command ===>                                                  Scroll ===> PAGE

  Enter/Change data in the rows, and/or enter any of the following
  row commands:
  I(nn) - Insert, R(nn),RR(nn) - Repeat, D(nn),DD - Delete
  S - Select operation details, J - Edit JCL
  Enter the PRED command above to include predecessors in this list, or,
  enter the GRAPH command to view the list graphically.


  Application              : MAINT          RMF maintenance


  Row  Oper     Duration  Job name  Internal predecessors          Morepreds
  cmd  ws   no. HH.MM.SS                                            -IntExt-
  ''''  TIMR 005  00.01.00  _____  ___ __ __ __ __ __ __ __          0  1
  ''''  DUMY 010  00.01.00  RMF____  005 __ __ __ __ __ __ __          0  0
  ''''  CPU1 015  00.10.00  RMFMAINT 010 __ __ __ __ __ __ __          0  0
  ''''  DUMY 020  00.01.00  RMF____  015 __ __ __ __ __ __ __          0  0
  ****************************** Bottom of data ******************************
```

Figure 45. Using Time as a Dependency

With this type of structure, TWS Automation can schedule the NV*xx* operation,
rather than the timer-dependent dummy workstation, if the application needs
scheduling on demand or restarting. This manually initiated procedure is
independent of the time consideration, if appropriate.

Changes to the Status of the Operation

The operation with the NV*xx* workstation goes through several status changes as
the request defined in the operator text is processed. The initial trigger is one of
three status changes. When the operation moves to the A (arrival), R (ready), or *
(ready with non-reporting predecessor) status, the TWS Automation function in the
EQQUX007 exit is triggered. The exit then examines the request. If the request is
valid, the exit transfers it to the target NetView.

If any definition problems are determined, TWS Automation updates the status to
E with an error code of U*xxx*. See *IBM Tivoli System Automation for z/OS Messages
and Codes*. TWS Automation takes no further action. The user is then responsible
for correcting the error and restarting the application at the failed operation.

If TWS Automation encounters a connectivity problem, it marks the operation with
a status of E (error) and an error code of S*xxx*. If this happens, TWS Automation
automatically restarts the operation once the connectivity problem is resolved.
However, if the operation status is changed manually, the automatic restart is
suppressed.

After TWS Automation resolves the request and verifies it, the status is updated to
S (started) before TWS Automation submits it. Once the request is submitted and
action is requested, TWS Automation updates the status to C (completed).

If the desired result did not occur within the time period specified, the operation
ends with an E status and a U*xxx* code, indicating that user intervention is
required.

Extending the Daily Plan

TWS Automation does not call EQQUX007 for time-delay operations added at
daily planning. To provide time-delay operations added at daily planning, you
need to define an operation on a dummy workstation as a predecessor to the NV*xx*
workstation. The operation on that workstation completes immediately after the
daily plan is extended, and the operation on the NetView workstation is READY

when all of its other dependencies are satisfied. See "Handling Time Dependencies" on page 70 for more information and an example of this technique.

Defining an operation on a dummy workstation is required because the operation-status-change exit is called whenever an operation in the current plan changes status. That exit is also called when a new operation has been added to the current plan by a function other than daily planning jobs, for example, by PIF or by the MCP dialog. The exit is called when the operation is added either to an existing occurrence or as a result of a new occurrence being added to the current plan.

Sending a Request to Optional Installation-Provided Functions

TWS Automation allows installation-specific extensions through optional user-provided modules. Two types of functions are supported:
- Issuing a non-SA z/OS command or request
- Sending a request through to TWS Automation to an installation extension

Because these user-provided modules are unique to your installation, you need to obtain information from your systems programmer/analyst on the use and syntax of these functions.

Executing TWS Requests with TWS Automation

Generally, you must use the TWS-specific OPCA, OPCACMD, and (optionally) OPCAPARM keywords to put an application defined to SA z/OS under the control of TWS Automation. You must define these entries under the MESSAGES/USER DATA policy item of the respective application in the SA z/OS policy database. See *IBM Tivoli System Automation for z/OS Defining Automation Policy* for more information on the MESSAGES/USER DATA policy item, and Chapter 11, "MESSAGES/USER DATA Entries and USER E-T Pairs for TWS Automation," on page 77 for the TWS-specific keywords.

You can vary the amount of fine-tuning considerably. If you only want to start and stop subsystems known to SA z/OS through TWS in a standard way, you need not even code any of these keywords. On the other hand, you can call user-written modules with OPCACMD that perform tasks not related to any SA z/OS subsystem and that must inform TWS about the success of their execution independently of TWS Automation.

The following sections explain the connection between the TWS request and the TWS-specific MESSAGES/USER DATA keywords by a fairly typical example, describe the use of request parameters, and give an overview of the different request types.

Request Types

TWS requests can be classified into four types depending on the existence or non-existence of TWS-specific keywords and on the type of command associated with the OPCACMD keyword. The following sections give an overview of these types.

Starting and Stopping Subsystems without TWS-Related Keywords

For START and STOP requests, you need not code any TWS-specific MESSAGES/USER DATA keyword in the policy database. TWS Automation will issue a default command when it detects that no OPCA entry exists for the START or STOP request in the MESSAGES/USER DATA policy item of the subsystem to

be started or stopped. In these cases you can specify a valid startup, respectively, shutdown type. The valid startup types are NORM and any startup type that has been defined in the STARTUP policy item of the subsystem to be started. The valid shutdown types are NORM, IMMED, or FORCE.

The start command issued by TWS Automation will be as follows:

```
INGREQ subsystem_name REQ=START,OUTMODE=LINE,SOURCE=EXTERNAL,VERIFY=NO
```

If you specify a startup type, this type will be added to the command.

The format of the stop command issued by TWS Automation is:

```
INGREQ subsystem_name REQ=STOP,OUTMODE=LINE,SOURCE=EXTERNAL,VERIFY=NO
```

If you specify a shutdown type, this type will be added to the command.

Note that if you want to add or change any parameter other than the TYPE parameter, you must specify your INGREQ command in an OPCACMD entry and code the associated OPCA entry. For more information on INGREQ, see *IBM Tivoli System Automation for z/OS Operator's Commands*.

Also note that when a default start or stop is selected, SA z/OS does *not* set a start or stop delay timer to ensure that the request finishes within a specified time. If a start or stop delay timer is required, the OPCA and OPCACMD entries should be coded.

When the startup or shutdown type is invalid for the subsystem in question, or when the command encounters any problem, the operation will fail with a user abend code of U003.

Canceling a Start or Stop Request

In many cases after a subsystem has been started or stopped, the previous request to SA z/OS needs to be removed to allow normal automation actions to continue. This can be achieved by issuing a CANCEL request type without parameters. Internally an INGSET CANCEL command will be issued to remove the previous START or STOP request for the resource.

Requests Using SA z/OS Automation Functions

These are requests for which an OPCACMD entry is coded, and where the command specified in that entry changes the automation status of the subsystem to UP, RUNNING or AUTODOWN. This can be an SA z/OS base command (for example, INGREQ), but also a user-written command that calls INGREQ. The name of the request must not begin with 'UX'. When the request contains parameters, these are stored in the &EHKVAR1 and &EHKVAR2 variables, respectively, and you can pass them to the command by incorporating these variables into the command text.

For every OPCACMD entry you must code an associated OPCA entry. An OPCAPARM entry is not required.

For START and STOP requests, you may want to use this type instead of coding no OPCACMD entry at all, if you want to override the default values for certain INGREQ parameters.

Subsystem Related Requests not Using SA z/OS Automation Functions

These are requests for which an OPCACMD entry is coded, and where the command specified does not trigger a status change of the subsystem that it relates to. The name of the request must not begin with 'UX'. When the request contains parameters, these are stored in the &EHKVAR1 and &EHKVAR2 variables, respectively, and you can pass them to the command via these variables.

For every OPCACMD entry with such a command you must code an associated OPCA entry. You must also define a corresponding OPCAPARM entry. This entry must specify a user-written timer module that informs TWS whether or not the request was successful (by calling OPCACOMP); this module is called by TWS Automation after the timer defined in the OPCA entry has expired.

For more information on this request type, see "User Functions Related to an SA z/OS-Defined Subsystem" on page 97.

Non-Subsystem Requests

These are requests that an OPCACMD entry is coded for, and where the command specified in that entry does not relate to a subsystem known to SA z/OS. The name of these requests must begin with 'UX'. The OPCACMD entry for a non-subsystem request must be coded as a USER E-T pair. With requests of this type, the complete request buffer will be stored in &EHKVAR1, and it is up to the user-written command to analyze this information. &EHKVAR2 contains the input arrival time.

For the format of the request buffer for 'UX' requests, see Table 7 on page 94.

No OPCA or OPCAPARM entry is needed for non-subsystem requests. The responsibility for informing TWS about the success of the operation lies entirely with the user-written command.

For more information on this request type, see "Non-Subsystem Operations" on page 101.

TWS Requests and MESSAGES/USER DATA Keywords

You put a request to TWS Automation by specifying the requested function and (optionally) one or two parameters in the **Operation text** field of the **Operations** panel for a TWS application (for details, see "Defining Applications for TWS Automation in TWS" on page 66). For example:

```
Row  Oper     Duration Job name  Operation text
cmd  ws   no. HH.MM
''''  NV04 005  0.01    RMF_____   START_____
''''  NV04 010  0.01    CICS1H__   START COLD_____
```

Figure 46. OPC/ESA Operations Panel

The request is START in both entries. The second entry has one parameter, namely COLD.

OPCACMD Keyword

TWS Automation uses the **Job name** and the **Operation text** fields of the TWS operation to translate requests into commands. After identifying the subsystem through the **Job name** entry, it consults the OPCACMD entry in the MESSAGES/USER DATA policy item of this subsystem. The CMD attributes of

this entry contain the commands that are to be issued in response to various requests, or combinations of request and parameter(s), that can be specified in the **Operation text** field. The following panel gives an example entry for RMF:

```
Pass/Selection Automated Function/'*'
Command Text
START
INGREQ RMF REQ=START,TYPE=NORM,SOURCE=EXTERNAL


OPMSG
MSG ALL RMF MSG
```

Figure 47. Specifying the Command for a Request

These entries specify in the **Command Text** field the commands that are to be issued for RMF when START, respectively, OPMSG requests are put to TWS Automation. Thus, when the 005 request of Figure 46 on page 74 has been put to TWS Automation, TWS Automation will issue the command

`INGREQ RMF REQ=START,TYPE=NORM,SOURCE=EXTERNAL`

OPCA Keyword

Besides specifying the command to be issued in response to the request, you must also tell TWS Automation

- Which status you expect the subsystem to assume as a result of this command
- The time interval within which the subsystem must assume this status.

This is done with the OPCA keyword. The following panel continues the example of Figure 47.

```
Code 1          Code 2          Code 3          Value Returned
START                                           UP,2,RMFUTMER
OPMSG                                           UP,1,
STOP                                            DOWN,2,
```

Figure 48. Specifying Expected Status and Time Interval

Here, the request is specified in the **Code 1** column. The **Value Returned** column contains the expected status, the time interval (in minutes), and optionally a timer name. The **Code 2** and **Code 3** columns are intended for eventual request parameters and consequently left blank in this example.

Flow of Control

By the entries of Figure 47 and Figure 48, TWS Automation will execute the start request of Figure 46 on page 74 for RMF as follows:

1. It sets the RMFUTMER timer to two minutes.
2. It issues the command `INGREQ RMF REQ=START,TYPE=NORM,SOURCE=EXTERNAL`.
3. If RMF has assumed the UP state before two minutes have passed, TWS Automation cancels the timer and posts the completion code C (for COMPLETED) back to TWS.
4. After the timer has expired, TWS Automation checks the status of RMF. If RMF is in the UP status, TWS Automation posts C to TWS; otherwise, it posts E (for ERROR) and an additional error code.

Request Parameters and the &EHKVARn Variables

Besides the request itself, the TWS request can contain one or two parameters. You can use this additional information to associate different commands with different variants of the same request; as an example, consider the different startup types for CICS®. You can pass the parameters to your command through the task global &EHKVAR1 and &EHKVAR2 variables.

As an example, suppose you want to specify the startup type for a CICS application in a TWS start request. Then you enter it as a request parameter in the **Operation text** field (see the 010 request in Figure 46 on page 74) and pass the startup type to the command specified in the OPCACMD entry by incorporating the &EHKVAR1 variable in the command text. In the following example, this command is not an SA z/OS command, but a user-written CLIST named MYCLIST that uses the startup information to apply the desired startup method.

```
Pass/Selection Automated Function/'*'
Command Text
START
MYCLIST CICS1H &EHKVAR1
```

Figure 49. Specifying a Command that Requires Parameter Information

Then, when the request of the 010 operation in Figure 46 on page 74 is put to TWS Automation, MYCLIST will be called with the arguments CICS1H and COLD. A very simple version of MYCLIST could be as follows:

```
/* MYCLIST SAMPLE */
PARSE UPPER ARG CICSNAME STARTTYPE

IF STARTTYPE='COLD' THEN
   "INGREQ "||CICSNAME||" REQ=START,TYPE=COLD,OUTMODE=LINE"
ELSE
   "INGREQ "||CICSNAME||" REQ=START,TYPE=AUTO,OUTMODE=LINE"
EXIT 0
```

If you use parameters, you must code an OPCA entry for every parameter (combination). For the example of Figure 49, the OPCA entry could look like Figure 50.

```
Code 1          Code 2          Code 3          Value Returned
START           COLD                            UP,10,CICS1TMR
START           AUTO                            UP,5,CICS1TMR
```

Figure 50. Specifying Expected Status and Time Interval for Different Request Parameters

Chapter 11. MESSAGES/USER DATA Entries and USER E-T Pairs for TWS Automation

As TWS Automation is integrated into SA z/OS, you must enter any information for TWS Automation in the policy database via the customization dialogs. In most cases the customization dialogs precisely determine the format in which this information must be entered. There are, however, some TWS application-specific automation parameters that must or can only be specified as entries in the MESSAGES/USER DATA policy items of the respective application, or as USER E-T pairs; for general information on the MESSAGES/USER DATA policy item and USER E-T pairs, see *IBM Tivoli System Automation for z/OS Defining Automation Policy*. In these cases, the customization panels provide no information about the keywords and the format of their parameters.

The following chapter contains detailed descriptions of these automation entries. Note, however, that a general understanding of the MESSAGES/USER DATA policy item will be assumed.

the OPCACMD entry must be coded in a USER E-T pair if the command to be specified is not related to a subsystem known to SA z/OS.

TWS-Specific MESSAGES/USER DATA Keywords

The following keywords are specific for TWS Automation.

Entry	Description
"OPCA" on page 78.	Use this ID to define the expected state of the subsystem and the time interval within which this state must have been reached.
"OPCACMD" on page 80.	Use this ID to specify the command to be issued in response to a TWS request.
"OPCAPARM" on page 82.	Use this ID to specify modifications of eventual request parameters and a timer module for user-written commands.

OPCA

Purpose

With the OPCA entry, you define the state that is the expected result of a request (with or without parameters), and the time interval within which this state must have been reached. The OPCA entry is defined in the MESSAGES/USER DATA policy item of the subsystem which is to be put under control of TWS.

Format

```
Code 1           Code 2           Code 3           Value Returned
START                                              UP,3,RMFUTMER
STOP                                               DOWN,2,RMFDTMER
```

Parameters

Code 1
> Request specified in the TWS operation text.

Code 2
> Parameter 1 as specified in the TWS operation text.

Code 3
> Parameter 2 as specified in the TWS operation text.

Value Returned

> *expstatus*
>> Expected status of the subsystem at the completion of the request. *expstatus* stands for one of the following values: UP, RUNNING or DOWN.
>>
>> **Note:** For backward compatibility CTLDOWN and AUTODOWN are also allowed for this entry and will be treated the same as DOWN.
>
> *timerint*
>> Timer interval in minutes. The maximum value permitted is 1439 (23 hours and 59 minutes).
>>
>> Set a timer interval that is long enough for the operation to complete reasonably. If the operation does not complete in the interval specified, then an error is posted to TWS.
>
> *timerid*
>> Timer ID — from 1 to 8 characters.
>>
>> This must be a valid NetView timer ID with a value not equal to ALL or beginning with SYS, ING, or AOF. This field is optional.

Usage Notes

For every OPCACMD entry there must be a corresponding OPCA entry.

Example

```
Code 1           Code 2           Code 3           Value Returned
START            AUTO                               UP,5,CICS1TMR
START            COLD                               UP,10,CICS1TMR
```

This example shows two entries, one for an automatic start, and one for a cold start. The AUTO or COLD parameter is added to the START request in TWS to indicate which one of several startup procedures is to be used. Presumably the two operations will take differing amounts of time, so the timer intervals are different.

This OPCA code entry is used in conjunction with a user-written CLIST, specified in the OPCACMD entry; see "Example 1" on page 80 for details of that entry and the sample CLIST.

OPCACMD

Purpose

With the OPCACMD entry, you define the command that is executed in response to a request (with or without parameters). Except for non-subsystem commands, there must be a corresponding OPCA entry for every OPCACMD entry.

Format

```
Pass/Selection Automated Function/'*'
Command Text
START
INGREQ RMF REQ=START,VERIFY=NO,SOURCE=EXTERNAL,TYPE=NORM,OUTMODE=LINE


STOP
INGREQ RMF REQ=STOP,VERIFY=NO,SOURCE=EXTERNAL,TYPE=NORM,OUTMODE=LINE
```

Parameters

Pass/Selection
> Request specified in the TWS operation text.

Command Text
> The actual command to be executed.

Usage Notes

This entry is necessary for all request types except START, STOP, and CANCEL requests. If no entries are supplied for START, STOP and CANCEL, the actions taken are detailed in "Starting and Stopping Subsystems without TWS-Related Keywords" on page 72 and "Canceling a Start or Stop Request" on page 73. The place where the OPCACMD entry is defined depends on the request type. When the request is related to a subsystem, it is defined in the MESSAGES/USER DATA policy item of the respective application. When the request is a non-subsystem request (see "Non-Subsystem Operations" on page 101), the OPCACMD entry must be entered in a USER E-T PAIRS entry.

Use SA z/OS commands to shut down and start up subsystems. This avoids the problem of having to determine the specific commands required for each subsystem.

Example 1

```
Pass/Selection Automated Function/'*'
Command Text
START
MYCLIST CICS1 &EHKVAR1


RECYCLE
INGREQ TESTAPPL REQ=STOP RESTART=YES SOURCE=EXTERNAL SCOPE=ALL
```

This example assumes that AUTO or COLD is added as a parameter to the START request in TWS to indicate which one of several startup procedures is to be used. The command specified in the **Command Text** field is a user-written CLIST. This CLIST is passed the parameter value (AUTO or COLD) in the &EHKVAR1 variable.

It also shows a RECYCLE type of operation (that is, bringing the subsystem down and restarting it immediately) being defined. The command is issued in linemode and verifies that it is accepted otherwise it posts the operation in error.

The OPCACMD entry of this example must be supplemented by an OPCA entry as in "Example" on page 78.

Example 2

```
   COMMANDS  ACTIONS  HELP
 -----------------------------------------------------------------------------
                       UET Keyword-Data Specification        Row 15 from 15
 Command ===> _____      SCROLL===> PAGE

 Entry Type : User E-T Pairs       PolicyDB Name   : SCENARIO
 Entry Name : NONSUBS              Enterprise Name : TEST
 UET Entry  : DUMMY               UET Type         : OPCACMD


 Action    Keyword/Data(partial)
 _____   CMD
           (UXCINITS,'MVS $TI20-30,C=P')
 ****************************** Bottom of data ********************************
```

This example shows a command that is not related to a subsystem known to SA z/OS (see "Non-Subsystem Operations" on page 101), and which, accordingly, must be defined as a USER E-T pair (see "Non-Subsystem Operations" on page 101). The jobname of the TWS request would be DUMMY.

TWS Automation recognizes such requests by the fact that the request name begins with 'UX'. In the example, TWS Automation simply issues the MVS command $TI20-30,C=P, which tells JES to change initiators 20 to 30 so that they process jobs of class P.

OPCAPARM

Purpose

The OPCAPARM entry supplies replacements for eventual request parameters and the name of a user-written timer module. The OPCAPARM entry is defined in the MESSAGES/USER DATA policy item of the subsystem which is to be put under control of TWS.

Format

```
Code 1          Code 2          Code 3          Value Returned
START                                           ,,
OPMSG                                           ,,USER_RTN1
```

Parameters

Code 1
Request specified in the TWS operation definition.

Code 2
Parameter 1 as specified in the TWS operation text.

Code 3
Parameter 2 as specified in the TWS operation text.

Value Returned
Enter the following parameters separated with commas.

parm1value
Substitution value used in the actual command.

parm2value
Substitution value used in the actual command.

timermod
Module called at the timer interval specified in the OPCA CODE entry for this subsystem. You must specify a timer module when the command specified in the OPCACMD entry relates to a subsystem defined to SA z/OS, but does not trigger a status change; see "User Functions Related to an SA z/OS-Defined Subsystem" on page 97.

Usage Notes

OPCAPARM is optional except for requests that relate to a subsystem defined to SA z/OS, but where the command specified in the OPCACMD entry is a user-supplied module that does not trigger a status change of the subsystem. In this case, a you must specify a timer module. See "Implementing Completion of a Request" on page 98 for more details.

Example

```
Code 1          Code 2          Code 3          Value Returned
START           AUTO                            ,,
START           COLD                            ,,
```

This example shows two entries, one for an automatic start, and one for a cold start, of a subsystem called CICS1. The AUTO or COLD parameter is added to the START request in TWS to indicate which one of several startup procedures is to be used.

Chapter 12. TWS Automation Common Routines and Data Areas

This chapter contains the common routines that are supplied by TWS Automation. Furthermore, it describes the data areas that are used to transfer requests from TWS to SA z/OS.

TWS Automation Common Routines

This chapter describes TWS Automation common routines which request information or perform tasks associated with TWS Automation. You can use these common routines in automation procedures you create. Examples, sample routines, and data area information are given to show how this might be done.

TWS Automation provides INGOPC and OPCAQRY to retrieve and update TWS Automation-unique information. These routines can also be used in user-written extensions of TWS Automation. The following routines are arranged alphabetically for easy reference.

> **Note:**
>
> The common routines listed below will automatically locate the active TWS Controller before executing PIF requests and will schedule all PIF interface calls on the same autotask to serialize access to the EQQMLOG data set.
>
> The active TWS Controller can be located in user routines by issuing the following sequence of commands:
>
> ```
> INGLIST CATEGORY=OPC,SUBTYPE=CONTROLLER,OBSERVED=AVAILABLE,OUTMODE=LINE
> ```
>
> Then for each subsystem returned from INGLIST issue:
>
> ```
> INGVARS GET subsystems_returned_above TWSACT OUTMODE=LINE
> ```
>
> The active TWS Controller will be in AVAILABLE status with the manager variable 'TWSACT' set to 'ACTIVE'.

OPCACAL

Purpose

The OPCACAL command retrieves TWS calendar status information. Use this command for your automation CLISTs. OPCACAL uses the EQQYCOM (also called the PIF) interface in TWS. For more information about this interface, see the *OPC/ESA Interfaces Guide*.

To show the use of this command, TWS Automation provides a REXX sample called EVJERCAL.

It is recommended that you use INGOPC.

Format

```
┌─ Syntax ──────────────────────────────────────────────────────────┐
│  OPCACAL [SUBSYS=subsystem,CALENDAR=calname]                       │
└───────────────────────────────────────────────────────────────────┘
```

Parameters

SUBSYS=*subsystem*
>   OPC/ESA subsystem ID — 4 characters.

>   OPCA is the default subsystem name.

CALENDAR=*calname*
>   Calendar ID — 16 characters.

>   DEFAULT is the default calendar name, used if this parameter is not coded.

Usage Notes

OPCACAL returns data in the following format:
* EVJ440I date_format day_of_week Work, or
* EVJ440I date_format day_of week Free

The date format is set by the NetView DEFAULTS LONGDATE value. For example:

```
EVJ440I 05/03/04 MONDAY Work
```

or

```
EVJ440I 20040502 SUNDAY Free
```

The EVJ440I message is PIPEd to the CONSOLE ONLY and does not appear in the netlog. The message can be processed by calling OPCACAL in a PIPE.

OPCACOMP

Purpose

The OPCACOMP command completes execution of a subsystem-related request by updating the TWS Automation control information and calling OPCAPOST (see "OPCAPOST" on page 91).

Format

```
┌─ Syntax ──────────────────────────────────────────────────────────┐
│                                                                    │
│  OPCACOMP  subsys,sequence_number,status [,error_code]             │
│                                                                    │
└────────────────────────────────────────────────────────────────────┘
```

Parameters

subsys
    Subsystem or pseudo-subsystem to identify the request.

sequence_number
    Sequence number assigned to this request by the EVJESPVY module.

status
    Operation status reflected to TWS Valid statuses:
    C   Complete
    E   Error

error_code
    Error code — 4-character value
        Takes the form *annn*, where *a* is alphabetic and *nnn* are numerics.
        Do not specify the values U*xxx* and S*xxx*; reserve them for TWS Automation.
        If the status is error, the error code is returned to TWS.

Return codes

0   Okay.

1   Error occurred, message issued.

Usage Notes

Call this routine in user-written functions that are related to a subsystem defined to SA z/OS whenever the standard modules for completing a request (EVJESPSC and EVJESPTE) cannot be used. See "Implementing Completion of a Request" on page 98.

Example

```
OPCACOMP  RMF,842,E,R028
```

This example shows setting the operation requested for RMF in an error status with an error code of R028.

OPCALIST

Purpose

The OPCALIST command retrieves TWS data. Use this command in your own automation CLISTS. It is recommended that you use the command INGOPC REQ=LIST.

The module creates a CPOPCOM call to TWS to retrieve the data. OPCALIST uses the EQQYCOM (also called the PIF) interface in TWS. For more information about this interface, see the *OPC/ESA Interfaces Guide*.

Format

```
 Syntax
 OPCALIST SUBSYS=subsystem,ADID=id,IA=yymmddhhmm,
          PRIORITY=nnnn,ERRCODE=cccc,STATUS=s,OPNO=nnnn,
          JOBNAME=name,WSNAME=name,
          GROUP=groupname,OWNER=name
```

Parameters

SUBSYS=_subsystem_
  TWS subsystem ID — 4 characters.

ADID=_id_
  Application description ID — up to 16 characters.

IA=_yymmddhhmm_
  Input arrival date _yymmdd_ and time _hhmm_.

PRIORITY=_nnnn_
  Priority — 4 digits.

ERRCODE=_cccc_
  Error code — 4 characters.

STATUS=_s_
  Occurrence status. Valid statuses:
  R   Ready
  S   Started
  C   Completed
  E   Error
  I   Interrupted

  Refer to the TWS documentation for more information.

OPNO=_nnnn_
  Operation number — 4 digits.

JOBNAME=_name_
  Job name — up to 8 characters.

WSNAME=_name_
  Workstation name — 4 characters.

GROUP=_groupname_
  OPC/ESA application group name — up to 8 characters.

OWNER=_name_
  OPC/ESA application owner name — up to 16 characters.

Usage Notes

Only as many parameters are required as necessary to identify the application(s) requested. Some parameters may be left unspecified (they will default). Some may be generic; that is they may be only partial and end with an asterisk (*) to indicate a partial match. You may also use a percent sign (%) to substitute for a single character.

The response to the OPCALIST is made up of three messages. The following example below shows a typical response where:

EVJ410I
> This is the message header, showing row titles. This is always present.

EVJ411I
> This is the detail message. If there are no entries matching the selection criteria this message is not produced.

EVJ412I
> This is the end of request message.

Response details are:

ADID
> Application Description Id — up to 16 characters

JOBNAME
> Job Name — up to 8 characters

WS
> Workstation Name — up to 4 characters

OPNO
> Operation Number — up to 4 numbers

S   Status (See "Parameters" on page 86 for valid statuses)

ERRC
> Error Code (set to none for no error)

IA   Input Arrival — date (yymmdd) and time (hhmm)

OPTEXT
> Descriptive Text — up to 24 characters

Example

```
EVJ410I   ADID   JOBNAME   WS  OPNO S ERRC IA          OPTEXT
EVJ411I   MAINT2 RMF        NV05 0010 C NONE 9707190615  STOP
EVJ411I   MAINT2 RMF        NV05 0015 C NONE 9707190615  START
EVJ411I   MAINT2 RMF        NV05 0010 C NONE 9707200615  STOP
EVJ411I   MAINT2 RMF        NV05 0015 C NONE 9707200615  START
EVJ412I   END OF REQUEST
```

OPCAMOD

Purpose

| The OPCAMOD command modifies TWS data. This command is used in the
| OPCACMD CLIST and could be used in your own automation CLISTS. It is
| recommended that you use the command INGOPC REQ=MOD.

The module creates a CPOPCOM or CPOCCOM call to TWS to perform occurrence
or operation changes. OPCAMOD uses the EQQYCOM (also called the PIF)
interface in TWS. For more information about this interface, see the *OPC/ESA
Interfaces Guide*.

Format

```
┌─ Syntax ──────────────────────────────────────────────────────┐
│ OPCAMOD SUBSYS=subsystem,ADID=id,IA=yymmddhhmm,                │
│         IANEW=yymmddhhmm,DEADLINE=yymmddhhmm,PRIORITY=nnnn,    │
│         ERRCODE=cccc,OPNO=nnnn,STATUS=s,                       │
│         JOBNAME=name,WSNAME=name,DESC=text,                    │
│         EDUR=hhmm,PSUSE=nnnn,R1USE=nnnn,R2USE= nnnn,           │
│         JCLASS=c,AEC=Y|N,ASUB=Y|N,AJR=Y|N,TIMEDEP=Y|N,        │
│         CLATE=Y|N,HRC=value,FORM=value,OPIA=yymmddhhmm,        │
│         OPDL=yymmddhhmm,RERUT=Y|N,USERDATA=userdata,          │
│         RESTA=Y|N,DEADWTO=Y|N                                  │
└───────────────────────────────────────────────────────────────┘
```

Parameters

SUBSYS=*subsystem*
    TWS/A subsystem ID — 4 characters (default OPCA).

ADID=*id*
    Application description ID — up to 16 characters (required).

IA=*yymmddhhmm*
    Input arrival date *yymmdd* and time *hhmm* (required).

IANEW=*yymmddhhmm*
    New input arrival date and time.

DEADLINE=*yymmddhhmm*
    Deadline date and time.

PRIORITY=*nnnn*
    Priority — 4 digits.

ERRCODE=*cccc*
    Error code — 4 characters.

STATUS=*s*
    Occurrence status. Valid statuses:
    R   Ready
    S   Started
    C   Complete
    E   Error
    I   Interrupted

    Refer to the TWS documentation for more information.

JOBNAME=*name*
    Job name — up to 8 characters.

WSNAME=_name_
　　Workstation name — 4 characters.

DESC=_text_
　　Descriptive text — 24 characters.

EDUR=_hhmm_
　　Estimated duration (hours and minutes).

PSUSE=_nnnn_
　　Number of parallel servers required — 4 digits.

R1USE=_nnnn_
　　Amount of resource 1 required — 4 digits.

R2USE=_nnnn_
　　Amount of resource 2 required — 4 digits.

JCLASS=_c_
　　MVS job class — 1 character.

AEC=Y|N

　　Y　Perform automatic error completion.

　　N　Do not perform automatic error completion.

ASUB=Y|N

　　Y　Perform automatic job submission.

　　N　Do not perform automatic job submission.

AJR=Y|N

　　Y　Perform automatic job hold and release.

　　N　Do not perform automatic job hold and release.

TIMEDEP=Y|N

　　Y　Time dependent job.

　　N　Not a time dependent job.

CLATE=Y|N

　　Y　Cancel if time job and late.

　　N　Do not cancel if time job and late.

HRC
　　Highest successful return code.

FORM=_value_
　　Form number — 8 characters.

OPIA=_yymmddhhmm_
　　Operation input arrival date and time.

OPDL=_yymmddhhmm_
　　Operation deadline date and time.

RERUT=Y|N

　　Y　Reroutable operation.

　　N　Not a reroutable operation.

USERDATA=*userdata*
> User data — up to 16 characters.

RESTA=Y|N

> **Y** Restartable operation.

> **N** Not a restartable operation.

DEADWTO=Y|N

> **Y** Issue WTO if deadline missed.

> **N** Do not issue WTO if deadline missed.

Usage Notes

OPCAMOD may be used to set the status of operations occurring on general workstations which are not automatically reporting (such as CPUs). OPCAPOST will set the status of operations which occur on automatically reporting general workstations (a NetView, for example).

Example 2

```
OPCAMOD SUBSYS=OPCA,ADID=TEST,IA=9403100900,OPNO=0010,
  STATUS=W
```

This example will set the status of operation number 0010 in application test, to waiting.

Example 3

```
OPCAMOD SUBSYS=OPCA,ADID=TEST,IA=9403100900,STATUS=W
```

This example will set the occurrence status of application TEST to WAITING. All operations in application TEST will be set to WAITING.

OPCAPOST

Purpose

OPCAPOST posts the status of an TWS Automation operation back to TWS. Because OPCAPOST uses the EQQUSINT interface, it can only change the status of operations on automatic reporting workstations. For more information on this interface, see *OPC/ESA Installation and Customization*.

Format

```
  Syntax
 OPCAPOST ADNAME=adname,WSNAME=wwww,OPNUM=nn,
          SUB=[subsystem],JOBNAME=jobname,
          TYPE={S|C|I|E|X},ERRCODE=xxxx,[ITIME=hhmm],
           [IDATE=yymmdd]
```

Parameters

ADNAME=adname
    Application name — 1 to 16 characters.

WSNAME=wwww
    Workstation name — 1 to 4 characters.

OPNUM=nn
    Operations number — 2 digits.

SUB=subsystem
    TWS subsystem ID — 4 characters (optional).

JOBNAME=jobname
    The jobname associated with the operation — 1 to 8 characters (optional).

TYPE={S|C|I|E|X}
    Type of call — 1 character. Acceptable event types:
    S   Started
    C   Complete
    I   Interrupted
    E   Error
    X   Reset

ERRCODE=xxxx
    Error code — 4 characters.

    Note: This parameter is only valid with TYPE=E.

ITIME=hhmm
    The input arrival time.

IDATE=yymmdd
    The input arrival date.

Usage Notes

OPCAPOST can be used to set the status of an operation which occurs on an automatically reporting general workstation (a NetView, for example) only. Due to restrictions in the TWS interface, OPCAPOST cannot set the status of operations on general workstations which are not automatically reporting (such as CPUs). INGOPC REQ=MOD is available to set the status of such operations if this is required.

OPCAPOST

TWS Automation sets a return code on completion of the execution of the OPCAPOST command processor, as follows:

0   Successful command

4   Parameter error

8   OPCAPOST failed.

Data Areas

This section contains the following:
- "Requestor ID Block (&EHKVAR9)"
- "Request Buffer" on page 94

Requestor ID Block (&EHKVAR9)

TWS Automation sets the task global variable (&EHKVAR9) in the request module and passes it to the user module, as follows:

```
Jobname, Sequence #, Module Name, Domain ID
```

where the variables have the following meanings:

Jobname
    The SA z/OS job name.

Sequence #
    The TWS sequence number.

Module Name
    Check module name that is invoked once the requested function has been completed.

Domain ID
    NetView domain ID that the function was executed in.

For example:

```
RMF,7842,OPCACOMP,NETVT
```

Note: Other options can also use this block. Although OPCACOMP is shipped with the TWS Automation option, you can also use a user-supplied module.

Request Buffer

Table 6 shows the request buffer layout for standard subsystem operations:

Table 6. Request Buffer Layout for Standard Subsystem Operations. Length represents the maximum length if the format is variable.

Field	Length	Format Fixed/Variable	Value	Obtained From
Request ID	8	F	EVJESPRQ	constant
delimiter	1	F	blank	constant
Application name	16	V	variable	ADNAME
delimiter	1	F	blank	constant
Workstation name	4	F	NV*nn*	WSNAME
delimiter	1	F	blank	constant
Operation no	3	V	1 – 255	OPNO
delimiter	1	F	blank	constant
Job name	8	V	variable	JOBNAME
delimiter	1	F	blank	constant
Request	8	V	variable	first field in TXTOP
delimiter	1	F	blank	constant
Parameter 1 (optional)	*	V	variable	second field in TXTOP
delimiter	1	F	blank	constant
Parameter 2 (optional)	*	V	variable	third field in TXTOP

Note: The length of Parameter 1 or 2 is from 1 to 8 characters.

Table 7 shows the request buffer layout for non-subsystem user extension (UXaaaaaa) operations:

Table 7. Request Buffer Layout for Non-Subsystem, User Extension (UXaaaaaaa) Operations. Length represents the maximum length if the format is variable.

Field	Length	Format Fixed/Variable	Value	Obtained From
Request ID	8	F	EVJESPRQ	constant
delimiter	1	F	blank	constant
Application name	16	V	variable	ADNAME
delimiter	1	F	blank	constant
Workstation name	4	F	NV*nn*	WSNAME
delimiter	1	F	blank	constant
Operation no	3	V	1 – 255	OPNO
delimiter	1	F	blank	constant
Job name	8	V	variable	JOBNAME
delimiter	1	F	blank	constant
Request	24	V	variable	TXTOP

Any parameter with a variable length is left-adjusted and all trailing blanks are ignored.

Data Areas

Chapter 13. Guidelines for User-Written Operations

TWS Automation allows two types of user-supplied extensions for implementation of functions beyond those provided by TWS Automation. These facilities provide support for the following types of user-supplied modules:

- A non-SA z/OS command or function that performs an action for a subsystem known to SA z/OS.
- An independent user-supplied function which is scheduled for the user. This type of function uses TWS Automation as a communications vehicle between TWS and the user-supplied module. A relationship is not required with any SA z/OS-defined subsystems.

The following sections describe an overview of each of these types of user-supplied modules and provide examples of each module's possible use.

User Functions Related to an SA z/OS-Defined Subsystem

TWS Automation provides support for stopping and starting SA z/OS-defined subsystems. Certain environments require you to issue a command or to perform a function outside the scope of SA z/OS. This may include a situation where a system command needs issuing or where a user-written function needs to perform a logical decision.

For example, you may need to issue a system command before taking action on a subsystem. If you always issue this command, specify it as part of the startup sequence in the SA z/OS policy database. However, since you may not need to use this command under certain conditions, TWS can initiate a user-supplied module to perform the command. You can split the startup sequence with the system commands, so TWS executes them separately from the subsystem startup commands. If this is the case, define each command sequence to TWS as an operation. Using scheduling parameters, such as specific types of days, you can include or exclude certain operations.

For example, consider a subsystem which normally runs on a specific processor. On weekends, you use this processor for testing purposes and move the application to another, perhaps smaller, processor within the same complex. On the days that the application needs moving, you need several VTAM® VARY commands to start the VTAM application statements.

In TWS, you can define an extra operation or application which runs on the first free day of each period, and another which runs on the first working day of each period. TWS calls the CLIST containing the VTAM commands. This allows the issuing of the appropriate VARY commands when needed before you start the application subsystem on the correct processor.

Triggering a user-written CLIST provides another example. This determines if all users of a specific application are logged off before issuing the commands to take down the subsystem.

Flow of Control

In a situation where a non-SA z/OS command needs issuing, specify the user CLIST or command processor in the OPCACMD entry of the subsystem. In

response to the request, instead of issuing an SA z/OS command, TWS
Automation passes control to this user CLIST or command processor. All
information available is made accessible to the user-supplied module. If the
user-supplied module does not trigger a status change of the subsystem and
returns control to TWS Automation synchronously, you are responsible for
completing the operation. This should be done by calling OPCACOMP once the
results of these commands are analyzed. The OPCACOMP module ensures that
actions are accomplished in the correct sequence, does some housekeeping,
updates the SA z/OS control information, and calls the OPCAPOST command
processor to return the specified completion code to TWS; for more details see
"Implementing Completion of a Request."

Figure 51 shows the flow including the user responsibilities.
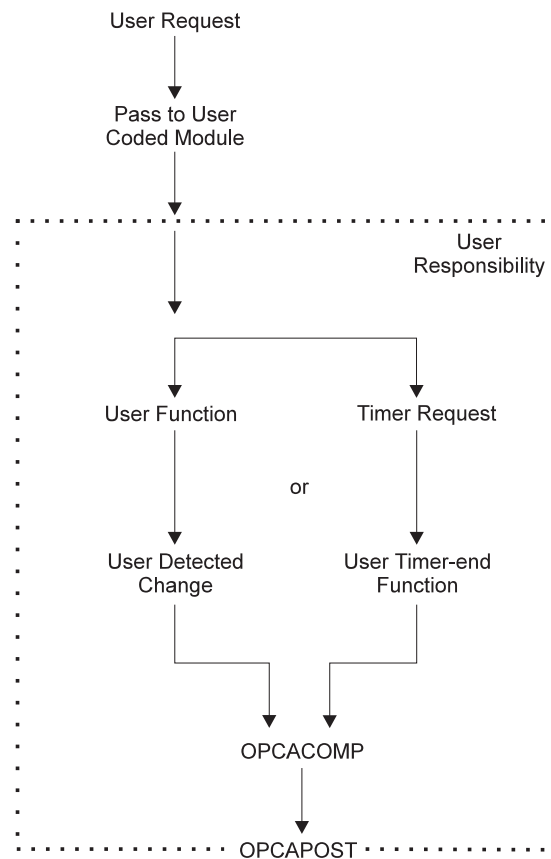
Figure 51. Request Flow for a Subsystem-Related User Function

To simplify implementation, you may plan to only use the timer function or only
the detection of the completion of the command. If you use only the event-driven
method, then consider what happens if the anticipated event fails to occur.

Implementing Completion of a Request

The general mechanism for executing requests for subsystems that have an OPCA
entry coded in their MESSAGES/USER DATA policy item is as follows:

1. The request (with one or two optional parameters) and the job name of the
   TWS operation are passed to TWS Automation.
2. TWS Automation identifies the SA z/OS definition of the subsystem through
   the job name of the TWS operation.

3. TWS Automation retrieves the expected result, the timer interval, and possibly a timer name, for the respective request/parameter combination from the OPCA entry of the subsystem.
4. TWS Automation then checks if an OPCAPARM entry is present and if that entry contains a timer module name.
5. If a timer module is specified, TWS Automation sets the timer with this timer module. Otherwise, it uses a standard timer module (EVJESPTE).
6. TWS Automation issues the command that is specified in the OPCACMD entry.

After the command has been issued, two things remain to be done:
- If the command was executed successfully, the TWS control information for this subsystem must be updated.
- The (positive or negative) result of the request must be posted back to TWS.

How this is done depends on the type of command specified in the OPCACMD entry.

Using TWS Automation Standard Modules
If the command specified in the OPCACMD entry triggers a status change of the subsystem to RUNNING, UP or AUTODOWN (no matter whether it is a user-written command or an SA z/OS standard command), you can leave it to TWS Automation to perform these two tasks. The modules responsible for this are the status change module (EVJESPSC) and the standard timer module (EVJESPTE), already mentioned in step 5 above; two flags, a completion flag and a timer flag, ensure that both modules are not active at the same time. The two standard modules operate as follows:

1. The *status change module* is called whenever the status of the subsystem changes. It first checks the timer flag. If that flag is set, EVJESPSC terminates at once. If the flag is not set, EVJESPSC checks if the status change is the result of a TWS request, and if the new status is identical to the expected result as specified in the OPCA entry. When both conditions are satisfied, the status change module assumes that the request was successfully executed and
   a. Purges the timer defined in the OPCA entry.
   b. Sets the completion flag in the TWS control information for this subsystem.
   c. Actualizes further fields of the TWS control information.
   d. Posts the result of the request back to TWS.
2. The *timer module* (EVJESPTE) is called after the timer set in step 5 has expired (except when you have specified your own timer module in the OPCAPARM entry). It first checks the completion flag. If that flag is set, EVJESPTE will terminate at once. If the completion flag is not set, EVJESPTE sets the timer flag and compares the current state of the subsystem with the expected result of the OPCA entry. If both are compliant, the timer module assumes that the request was executed successfully; it updates the TWS control information accordingly and posts a positive result back to TWS. If they are not compliant, it only posts the failure of the request back to TWS.

Programming your own Completion Routines
If you specify a command in the OPCACMD entry that does not change the status of the subsystem to UP, RUNNING or AUTODOWN, then you cannot use the standard modules for completing the request. In this case, you must perform the update of the TWS control information and the posting of the result to TWS. You can do that in the command module (specified in the OPCACMD entry) or in a

user-written timer module (specified in the OPCAPARM entry) or in both. The user-written timer module is called by TWS Automation in the following format:

```
MODULE_NAME subsystem_name expected_result TWS_application_ID
             TWS_workstation_ID request_sequence_number
```

To simplify completion of a user-written module, TWS Automation provides the following facilities.

The OPCACOMP Command: This command, which is described in more detail in "OPCACOMP" on page 85, updates the TWS control information and posts the result of the request back to TWS.

In particular, OPCACOMP first checks if the timer flag is set. If so, it will terminate at once. If not, it will

1. Set the completion flag in the TWS control information of the subsystem that it is called for.
2. Actualize further fields of the TWS control information.
3. Post the result of the request back to TWS.

The main difference between OPCACOMP and the standard modules (EVJESPSC and EVJESTPE) is that OPCACOMP does not check if the current status of the subsystem is in agreement with the expected result. Rather, it requires the (positive or negative) result of the request as one of its input parameters, and usually simply forwards this result to TWS. Thus, a user-written module must itself decide whether or not the request was executed successfully. It can then pass that information to OPCACOMP in order that the request be completed in an orderly manner.

One of the input parameters for OPCACOMP is the sequence number of the current request (see "OPCACOMP" on page 85). TWS Automation provides this and other information in some task global variables. Note, however, *that it will do this only when you have specified a timer module in the OPCAPARM entry*. You can specify a user-written timer module or the EVJESPTE standard module in the OPCAPARM entry. The following section describes the information contained in the global variables.

The &EHKVAR7, &EHKVAR8, and &EHKVAR9 Variables: When you supply a timer check module in the OPCAPARM entry (third value of the **Value Returned** field) TWS Automation sets some task global variables as follows:

&EHKVAR7   This variable contains the expected status, the timer interval, and the timer ID as specified in the OPCA entry. The values are separated by commas.

&EHKVAR8   This variable contains the string 'OPC'.

&EHKVAR9   This value contains the subsystem name, the sequence number, the name of the timer check module and the domain, separated by commas. This is also known as the Requestor ID block; see "Requestor ID Block (&EHKVAR9)" on page 93.

Do not modify the information in the task global variables. TWS uses information in &EHKVAR7 if the timer is purged. The SA z/OS problem determination uses information in &EHKVAR8. In order to call OPCACOMP, the sequence number of the current request must be known; this number is stored in &EHKVAR9.

Non-Subsystem Operations

Operations of this type, containing requests named UX*xxxxxx*, allow you to perform commands that are independent of a specific subsystem. Figure 52 shows the flow for these types of operations.
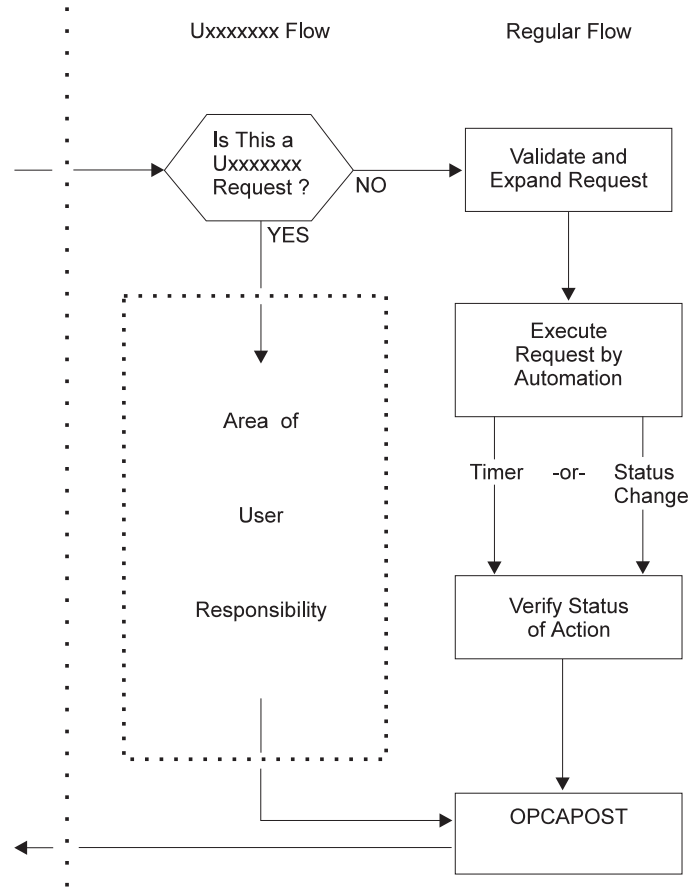
Figure 52. User Exit UXxxxxxx Flow

TWS Automation uses this type of exit for several purposes. At any point in the production cycle, TWS Automation allows you to invoke a user CLIST or procedure that can interact with system resources, such as the storage management subsystem.

Let's consider an example. Suppose, in a specific application flow within TWS, return codes show action that is taken by operations. When a specific job in this application completes, one of several user completion codes can result.

- A completion code of 0 indicates that application processing is to continue to the next operation.
- A user completion code of 50 indicates that the next two operations are skipped.
- A user condition code of 70 indicates that the application is completed at this operation.

Any other completion codes are treated as errors. Figure 53 on page 102 shows the subject operations in this application, and the desired flow of control on the basis of the condition codes of the job that runs as part of the CPU_20 operation.

```
             SAMPLE APPLICATION
                OPERATIONS

                     │
                     ▼
              ┌─────────────┐
              │             │
              │   CPU_20    │
              │             │
              └─────────────┘
                 │        │
          CC=0   │        │
                 │     CC=50      CC=70
                 ▼
              ┌─────────────┐
              │             │
              │   CPU_25    │
              │             │
              └─────────────┘
                     │
                     ▼
              ┌─────────────┐
              │             │
              │   CPU_30    │
              │             │
              └─────────────┘
                     │
                     ▼
              ┌─────────────┐
              │             │
              │   CPU_35    │
              │             │
              └─────────────┘
                     │
                     ▼
             APPLICATION COMPLETED
```
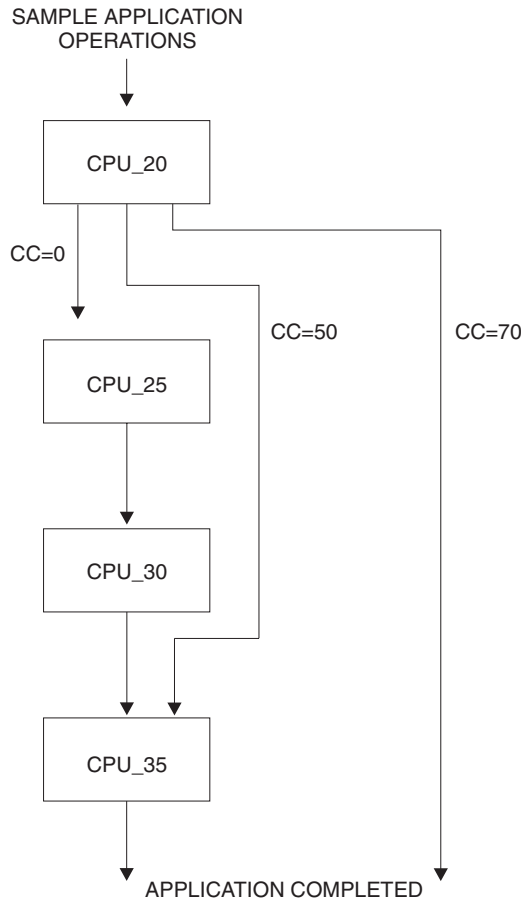
Figure 53. Condition Code Driven Application Flow

In the preceding example, TWS handles all condition code situations, except 50 and 70, which it intercepts. TWS accomplishes this interception in several fashions, such as user code in a JJC error exit. This code could then drive TWS Automation with a user exit (UX*xxxxxx*) request. This request would pass to the specified NetView to a user-written task. This task could then use the INGOPC REQ=MOD command to do a modify current plan to TWS for the application in question on the basis of the condition code received as part of the user exit request.

Flow of Control

When the name of a request starts with UX, TWS Automation assumes that the request is not related to a subsystem known to SA z/OS. As before, it expects to find an OPCACMD entry within a policy object that is identified through the **Job name** field of the TWS operation. However, if no match is found for USER E-T pair 'OPCACMD jobname', then TWS Automation will check for USER E-T pair 'OPCACMD OPCA', and if again no match is found, TWS Automation will check for USER E-T pair 'OPCACMD subsystem'. Although user exit processing is designed to be non-subsystem related, this approach provides flexibility for users who have jobnames that do not match subsystems names but still prefer subsystem-related processing. There are however two differences compared to subsystem-related requests:

- The only keyword that is needed is OPCACMD. OPCA and OPCAPARM are ignored.The CMD attributes of the OPCACMD entry should have the following format:

```
CMD=(UXxxxxxx,,'userfunc &EHKVAR1')
```

For &EHKVAR1, see "Parameters Passed to a User Exit."

- The policy object identified through the **Job name** field of the TWS operation should be a USER E-T pair (see "OPCACMD" on page 80).

For non-subsystem requests, TWS Automation immediately tries to issue the command specified in the OPCACMD entry. After issuing the command, the request module of TWS Automation terminates. It is up to the user function to determine whether or not the request was executed successfully. The user function should then call OPCAPOST (see "OPCAPOST" on page 91) with the corresponding completion code. This returns the control of the application processing to TWS. The samples contain a code template for a non-subsystem command (EVJERUX1).

Parameters Passed to a User Exit

When the request name begins with UX TWS Automation stores the complete request buffer in the &EHKVAR1 task global variable. This variable must be forwarded to the command as an input parameter, as indicated in the format description above. &EHKVAR2 contains the input arrival time.

In contrast to a subsystem operation, the request buffer for a non-subsystem operation contains the entire request in one field. The format of the request buffer for 'UX' requests is described in Table 7 on page 94.

Interaction with CICS Automation

The following example shows how to use the INGCICS command of CICS Automation to open and close CICS files. The INGCICS command allows you to perform CEMT commands on any CICS subsystem. If CICS Automation is not installed, then you can perform a similar function using the MVS MODIFY command from a NetView CLIST. First, you need these requests:

UXCICSOP   Requests CICS to open a file.

UXCICSCL   Requests CICS to close a file.

The example selects the CLIST names of CICSOPEN and CICSCLOS. Using these names, the format of the CMD attributes of the OPCACMD entry (see "OPCACMD" on page 80) is as follows:

```
Action    Keyword/Data(partial)
          CMD
_____  (UXCICSOP,,'CICSOPEN &EHKVAR1')

          CMD
_____  (UXCICSCL,,'CICSCLOS EHKVAR1')
```

Figure 54. OPCACMD Entry for Interaction with CICS

Figure 55 on page 104 shows the definition of the operation text and other fields in TWS.

```
-------------------------------- OPERATIONS -------------------- ROW 1 OF 1
Command ===>                                               Scroll ===> PAGE

Enter/Change data in the rows, and/or enter any of the following
row commands:
I(nn) - Insert, R(nn),RR(nn) - Repeat, D(nn),DD - Delete
S - Select operation details
Enter the PRED command above to include predecessors in this list, or,
enter the GRAPH command to view the list graphically.

Application          : PAYMAINT       Payroll Master Update

Row  Oper    Duration Job name  Operation text
cmd  ws  no.  HH.MM
'''' NV04 015  0.01    DUMMY___  UXCICSCL CICS01 PAYROLL____
```

Figure 55. Defining Sample CICS Application in TWS

The example uses the CICS subsystem name and the file name as parameters to the request. These parameters are optional and flexible. Thus, the CICS name could also be passed through the **Job name** field. The REXX code for CICSOPEN and CICSCLOS is supplied in the samples as EVJERUX2 and EVJERUX3.

Interaction with IMS Automation

The following example shows how to use the INGIMS of IMS Automation to start and stop databases in IMS. The INGIMS command allows you to perform IMS MTO commands on any IMS in the system. Other IMS commands could be imbedded into IMSCMD and incorporated in NetView CLISTs you write yourself, using similar logic to that shown in the EVJERUX4 and EVJERUX5 CLISTs supplied with the samples. If IMS Automation is not installed, then you can perform similar function by replying to the outstanding reply ID of the IMS you wish to communicate with from a NetView CLIST you write yourself. First, you will need these requests:

UXIMSSDB   Requests to start a database.

UXIMSPDB   Requests to stop a database.

The example selects the CLIST names EVJERUX4 and EVJERUX5. Using these names, the format of the CMD attributes of the OPCACMD entry (see "OPCACMD" on page 80) is as follows::

```
Action   Keyword/Data(partial)
_____ CMD
         (UXIMSSDB,,'EVJERUX4 &EHKVAR1')

_____ CMD
         (UXIMSPDB,,'EVJERUX5 EHKVAR1')
```

Figure 56. OPCACMD Entry for Interaction with IMS

Figure 57 on page 105 shows the TWS definition of the operation text and other fields.

```
-------------------------------- OPERATIONS --------------------- ROW 1 OF 1
Command ===>                                               Scroll ===> PAGE

Enter/Change data in the rows, and/or enter any of the following
row commands:
I(nn) - Insert, R(nn),RR(nn) - Repeat, D(nn),DD - Delete
S - Select operation details
Enter the PRED command above to include predecessors in this lis
enter the GRAPH command to view the list graphically.

Application              : CUSTMAINT       Customer DB update

Row  Oper     Duration Job name  Operation text
cmd  ws   no.  HH.MM
'''' NV01 020   0.02    DUMMY___  UXIMSSDB IMS05Z_____
```

Figure 57. Defining Sample IMS Application in TWS

The parameters of the request are the IMS subsystem name and the database
name. The REXX code of EVJRUX4 and EVJERUX5 is supplied in the samples.

Chapter 14. TWS Automation Operator Commands

The following commands are used with TWS Automation:

Table 8. TWS Automation Commands

Command	Description
EVJESPIN	Normally used only during initialization of SA z/OS. The actions available with this command are INIT and RESET. See "EVJESPIN — Initialization" on page 109.
INGOPC	Queries or modifies a TWS controller. See *IBM Tivoli System Automation for z/OS Operator's Commands*.
OPC/OPCA	Displays the TWS Automation Main Menu (EVJKYOPC) that lists the most commonly used commands. See "TWS Automation Main Menu" on page 107.
OPCAPOST	Posts an operation to TWS from SA z/OS. See "OPCAPOST — Posting a TWS Operation from SA z/OS" on page 110.
OPCAQRY	Displays the status of TWS Automation operations. See *IBM Tivoli System Automation for z/OS Operator's Commands*.
SRSTAT	Determines the status of TWS special resources. See "SRSTAT — Setting TWS Special Resource Status" on page 111.

TWS Automation Main Menu

Type **OPCA** on the command line. After you press ENTER, TWS Automation displays the TWS Main Menu, as shown in Figure 58.

```
 EVJKYOPC                  SA z/OS  - Command Dialogs
 Domain ID  = IPUFA    ---------- OPC    ----------   Date = 05/15/05
 Operator ID = OPER1                                  Time = 15:55:23


 Resource        =>  _____     Format: name/type/system
 System          =>  _____        System name, domain ID or sysplex name

        1. List Applications   List OPC/TWS Applications   INGOPC  REQ=LIST
        2. List Workstations   List OPC/TWS Workstations   INGOPC  REQ=LIST
        3. List Special Res.   List OPC/TWS Special Res.   INGOPC  REQ=LIST
        4. List Calendars      List OPC/TWS Calendars      INGOPC  REQ=LIST
        5. SA Operations       List SA pending Operations  OPCAQRY
        6. Glossary            Glossary of OPC Terms




 Command ===>
   PF1=Help     PF2=End     PF3=Return                 PF6=Roll
```

Figure 58. TWS Main Menu

To define one or more OPC Subsystems to be processed, type in the name of a resource. This should be in the format name/type/system.

To display a list of all known OPC resources type a question mark (?) for the resource and specify the required system. The System field allows you to specify a TARGET parameter where you would like the required OPC function to be performed (system, domain or sysplex name). To limit the resource list to a specific system, use the */APL/system notation.

Otherwise, type the number of one of the listed functions and press ENTER.

EVJESPIN — Initialization

Purpose

TWS Automation uses this command during initialization when SA z/OS is started.

The INIT command acts on all TWS Automation controlled subsystems.

Syntax

EVJESPIN CMD=*action* **SUBSYSTEM=***subsystem*

Parameters

CMD=*action*   The command to execute where *action* is one of the following:

        INIT   Forces an equivalent action to that taken during normal initialization. Do not specify a subsystem parameter for this parameter. To properly understand the action of this command parameter and for a complete overview of the initialization process, refer to "Usage."

        RESET
            Resets the timer and completion flags to a null value, and unlocks a specific subsystem after a user error is detected and corrected. By resetting the timer and completion flags, TWS Automation again accepts requests from TWS.

    subsystem   The subsystem initialized. Do not specify a subsystem with INIT.

Usage

In certain situations, usually because of user-definition or sequence errors, the timer and completion flags prevent TWS Automation from accepting any new requests for a subsystem on a target NetView.

This ensures that errors are caught, TWS Automation actions for the given subsystem are halted, and creation of additional problems is avoided before the original error has been corrected. For example, if a subsystem startup request is being processed, then it is not prudent to process a shutdown request in the same interval. By not accepting any requests after an error has been detected, the TWS control information reflects the request that caused the problem. This should then simplify problem determination.

OPCAPOST — Posting a TWS Operation from SA z/OS

Purpose

This command is used by SA z/OS to inform TWS of status changes. This is accomplished by the OPCAPOST command processor, which is normally used internally in TWS Automation. Although you can issue OPCAPOST as an operator command, operators should use INGOPC TYPE=OP REQ=MODIFY, if possible. INGOPC provides a fullscreen interface to TWS and dynamically acknowledges the action unlike OPCAPOST.

If you determine that you must use the OPCAPOST command, refer to "OPCAPOST" on page 91.

SRSTAT — Setting TWS Special Resource Status

Purpose

This command lets you update the status of the specified TWS special resource to the value given in the parameters. The status is returned via messages.

Syntax

SRSTAT *srname*,**SUBSYS=**entity*subsys*,**AVAIL=Y|N**

Parameters

srname
> Special resource name — up to 44 characters.
>
> **Note:** The special resource name must be enclosed in single quotes if it contains any spaces or commas.

subsys
> The MVS subsystem ID of the TWS tracker — 4 characters.

AVAIL=Y|N
> Availability indicator.

Return Codes

SRSTAT has the following return codes:

0   Okay.

1   Bad parameters.

2   Invalid special resource name.

3   Invalid subsystem ID.

4   Invalid availability status.

Example

```
SRSTAT EOD.CICSPRD1.TRANS,SUBSYS=OPCT,AVAIL=Y
```

In this example, end-of-day transactions are required to finish before production work can begin. SRSTAT is executed when the transactions are complete. The special resource name EOD.CICSPRD1.TRANS is used to trigger OPC/ESA applications that are able to run when the transactions are finished. A number of applications are added to the current plan.

The variable used for *subsys*, OPCT, is the name of the tracker subsystem. The tracker subsystem name is only required with this command.

Chapter 15. Resynchronization and Recovery Considerations

TWS Automation combines the capabilities of two different subsystems, TWS and SA z/OS, which may reside over several systems. As a result, a failure or a scheduled interruption of services with one of the subsystems, processors, or telecommunications facilities may occur and prevent TWS Automation from processing operations. Further complications arise by shifting work load across multiple system images, either for scheduled workload balancing or as part of a recovery situation.

In such a case, a loss of synchronization can occur between the TWS schedule and the TWS Automation components in NetView. When this happens, you may need a manual process to examine the TWS schedule, to ensure that TWS Automation in NetView is performing actions as required and, in some cases, to resynchronize TWS and TWS Automation.

During a loss of contact or a failure with either TWS or NetView, TWS Automation's facilities invoke and restore the environment as it was before the failure so that event scheduling can pick up where it left off. This results in a satisfactory resolution and manual resynchronization is not required. See "Automated Recovery Functions" on page 116 for additional information.

Generally, the longer the outage, the more likely that resynchronization is required. This depends on the number of scheduled events that are not processed. A long outage during the day may have a smaller synchronization impact than a shorter outage during a period when many online facilities are started or shut down.

Examples and Scenarios

This section describes possible scenarios for resynchronization and recovery.

Loss of Contact Between TWS and TWS Automation

Under most situations, once TWS Automation re-establishes connectivity, its automatic recovery schedules requests for execution that it could not execute prior to connectivity. In some situations you may need to intervene manually, such as when the request is no longer valid. The following sections discuss several reasons for manual intervention.

Taking Action Too Late

The remaining processing window is too small to allow an operation to occur. For example, an online system may require a certain amount of time to initialize. If this amount of time is close to the scheduled shutdown time, you probably should override the request and complete the operation manually.

You should issue EVJESPIN CMD=RESET.

Queuing Several Actions for a Specific Target Subsystem

Rather than not having enough time for a system initialization as in the previous example, the outage may have lasted long enough for a specific subsystem to receive several queued operations that frequently conflict. For example, an online task may have a start request with an ended-in-error status because of connectivity problems. This same task may also have a stop request already due for scheduling.

If you allow automatic recovery for this application, the subsystem would start, but an immediate shutdown would follow.

Complete these operations manually. You should issue EVJESPIN CMD=RESET.

Backup on a Different Processor

If you perform a backup using a different processor, pay special attention to ensure that you properly restore the work load on the new system. Depending on the backup structure, you need to follow one of several different procedures discussed in the next sections.

Full Takeover onto a Standby System at the Same Site

This is the simplest type of backup. It becomes the same as a single-system recovery if the data is also available. TWS Automation uses the information in the status file to restore the various subsystems to the pre-backup status.

Full Takeover onto a Standby System at a Different Site

If the status file is not available, restructure the environment manually. Examine pertinent applications that control this specific NV*nn* workstation. The last completed NV*nn* operation requires manual triggering. You can achieve this with the INGOPC function, allowing the NetView operator direct access to the relevant applications. Although, at times, you may find it necessary to perform specific operations manually, in most cases, resetting an operation with EVJESPIN or restarting an application produces the desired effect.

Takeover onto a Working System

In most situations, the takeover is onto a working system and is restricted to certain critical applications. The previously discussed considerations as to whether the system is at the same site or at another site apply to this situation. Since not all applications are restarted on the backup system, several new considerations become important. Certain applications need cancelling before you can achieve a restoration of services. Some situations can result in duplications, such as with subsystems like TSO, which are frequently found on every MVS system. Although normally this is controlled by SA z/OS, TWS Automation can control this. Here, duplicate applications need cancelling for the backup period.

During the backup period, use one of these two methods to run TWS Automation:
- Add the new work load to the resident NetView by changing the NV*nn* workstation entry in the platform control file to point to the same NetView domain ID.
- Start another copy of NetView with the NetView domain ID used in the failing system.

The consideration of which method to use becomes important once you restore the original configuration.

With the single NetView solution method, you need to resolve the subsystems manually since their original identity is lost. With the extra NetView solution method, you can stop the subsystems controlled by the extra NetView by shutting it down. This simplifies the restoration process, requiring almost no manual intervention.

In both cases, restoring the environment follows similar procedures used to backup a host onto a standby backup system.

Long Term Outage

You must manually intervene when the outage duration is more than a single scheduling cycle. This type of recovery is confusing since many applications are shown as late in the TWS plan. Carefully review these applications since some of the them still need scheduling, while others need to be cancelled. For applications that need scheduling, certain operations involving the online portion need cancelling or holding. To ensure success, this type of recovery needs precise planning and monitoring. Otherwise, you can use the scenarios previously outlined.

Example Using Doubly-Defined NetView Domain IDs

The example in Figure 59 shows the WORKSTATION DOMAINS entry for a 4-processor environment:

```
Code 1          Code 2          Code 3          Value Returned
NV00                                            NVTOR
NV01                                            XBAOF
NV02                                            AOFT5
NV06                                            AOFS6
```

Figure 59. Mapping of NVxx Workstations to Domain IDs

Here, NV00 maps to the NVTOR NetView domain ID, and the NV01 workstation maps to the XBAOF NetView domain.

Under normal circumstances, each NetView domain ID represents a processor with its MVS operating system and a unique NVxx general automatic reporting workstation. For situations such as testing, backup, or work load management, this relationship needs no maintenance.

In the previous example, both NV00 and NV06 TWS-defined workstations represent their own specific NetView domain, NVTOR and AOFS6, respectively.

Assume that the system represented by NVTOR has failed, and you make the decision to shift the work load to the AOFS6 system. You can accomplish this by changing the domain ID in the first CODE statement from NVTOR to AOFS6. This would imply that the AOFS6 domain is associated with two TWS workstations, namely NV00 and NV06.

If you accomplish this change without altering the TWS definitions, you must reload the SA z/OS control file. The scheduler or operator needs to ensure that the TWS-defined applications that are running in the failed system are restarted on the backup system. Because the SA z/OS status records are on the failed system, the scheduler manually recovers the failed environment. Once resynchronization completes, any new scheduled event originally intended for the NetView domain ID NVTOR automatically is scheduled for AOFS6. After you resolve the problem on the NVTOR system, perform the previous scenario in reverse order to restore the system to its original configuration.

When double definitions of this type are used, exercise caution to avoid creating conflicting requests for specific subsystems. For example, if RMF exists in the AOFS6 domain, TWS can then schedule a shutdown request on NV00 and a start request on NV06.

Automated Recovery Functions

Only a small portion of TWS Automation resides in the TWS address space in TWS user exits. These exits communicate to the rest of TWS Automation which resides in the NetView address space. A loss of contact results if a NetView address space becomes unavailable or if TWS Automation code in NetView is unavailable. Also, a communication failure can prevent a request from reaching its ultimate destination.

TWS Automation automated recovery determines which operations are affected by a specific loss of communications. It also determines when the connectivity and availability of a given target NetView is corrected and the NV*nn* operation is reset to the ready state. This redrives the EQQUX007 exit, allowing it to re-create the original request.

TWS Actions in a Loss-of-Contact Situation

The EQQUX007 exit or an intermediary NetView with an ended-in-error status and a return code of Sxxx reports a connectivity loss to TWS. TWS does not schedule any dependent operations and shows an error on the operations ended-in-error Status Display Facility panel. TWS takes no further action until the connectivity is restored and TWS Automation automatic recovery is invoked.

The operator or scheduler can manually override the ended-in-error status, thus allowing the application to continue or cancelling it.

TWS Automation Actions in a Loss-of-Contact Situation

If loss of connectivity to NetView is detected in the TWS Automation portion of the EQQUX007 exit (using the EQQUSINT function directly), then TWS Automation posts an ended-in-error status with a UNTV return code. TWS Automation uses this mechanism because the EQQUX007 exit cannot directly modify operation status.

If the request is received in NetView, but TWS Automation cannot propagate the request to the appropriate target system, TWS Automation uses the OPCAPOST function to post the operation as ended-in-error with an S999 return code.

Glossary of Terms

The intent of this glossary is to define terms as TME 10 OPC uses them. However, where applicable, terms are taken from the *IBM Dictionary of Computing*, New York; McGraw-Hill, 1994. These terms are marked by an asterisk (*). Unless otherwise noted, the definitions below apply equally well to OPC/ESA and TME 10 OPC.

A

actual duration. At a workstation, the actual time in hours and minutes it takes to process an operation from start to finish.

APAR. Authorized program analysis report. A report of a problem caused by a suspected defect in a current unaltered release of a program.

all workstations closed. A user defined interval during which *all* TWS's workstations are not available for running applications under TWS's control.

Note: All the workstations could be either shut down *or* simply not available to TWS.

application. (1) A group of related operations performed together to satisfy a specific end user task. (2) A measurable and controllable unit of work that completes a specific user task such as the running of payroll or financial statements. The smallest entity that an application can be broken down into is an operation. Generally, several related operations make up an application.

application description. A database description of an application.

application ID. The name of an application. Examples: Y1976, Payroll.

arrival (A). Status of an operation that indicates it is waiting for the input to arrive before processing.

authority. The ability to access a protected resource.

authority group. A name used to generate a RACF resource name for authority checking.

automatic events. Events recognized by or triggered by an executing program. Automatic events are usually generated by TWS job tracking programs but may also be created by a user-defined program.

automatic reporting workstation. A workstation that reports events (the starting and stopping of operations) in real time to TWS, such as a processor or printer.

automatic job recovery. a TWS function which allows you to specify, in advance, alternative recovery strategies for applications or operations ended in error.

availability. * The degree to which a system (and in TWS, an application) or resource is ready when needed to process data.

B

batch loader. a TWS batch program you can use to create and update information in the application description and operator instruction databases.

bracketed DBCS. A MIXED format field consisting of a DBCS part only, that is, DBCS characters enclosed by a shift-out/shift-in control character pair.

browse. An ISPF/PDF dialog function that manages data for display only. This function lets the user view but not change data.

C

CP. Current plan.

calendar. The data that defines the operation department's processing schedule in days and periods.

capacity. The actual number of parallel servers and workstation resources available during a specified open time interval.

capacity ceiling. The maximum number of operations a workstation can handle simultaneously.

case code. A code in the automatic job recovery function that represents a group of abend codes or return codes. Any code in the JOBCODE and STEPCODE parameters is considered a potential case code if defined as such in the case code macro.

closed workstation. A workstation that is unavailable to process work for a specific time, day, or period.

command. * A request from a terminal for the performance of an operation or the execution of a particular program. A character string from a source external to a system that represents a request for system action.

complete. Status of an operation indicating that it has finished processing.

completion code. a TWS system code indicating how the processing of an operation ended at a workstation.

complex of processors. A JES2 multi-access spool system or a JES3 system with more than one processor.

computer workstation. A workstation that performs MVS processing and usually reports status to TWS automatically. A processor when used as a workstation. It can refer to single processors or multiprocessor complexes serving a single job queue (for example JES2 or JES3 systems).

controller. The portion of TME 10 OPC or OPC/ESA that runs on the controlling processor and contains the tasks that manage TWS databases and plans.

critical path. The route within a network with the least amount of slack time.

current plan. A minute by minute schedule of each operation of an application. It reflects the current state of the operating environment showing the status of work completed and work still to be done.

current schedule. The database that contains the current plan information.

cyclic interval. The number of days in a cyclic period.

cyclic period. A period with a specific origin date and set frequency. A cyclic period can be broken down into two types:
- Those that include work and free days
- Those that include only work days.

Cyclic periods must always represent a fixed time period in days. For example, week (7 days).

D

daily plan. A set of plans that shows work that the operations department does on a particular day or shift. A list by day and application of all operations to be performed within the operations department.

default calendar. (1) A calendar that you have defined for TWS to use when you do not specify a calendar in an application description. (2) A calendar that TWS uses if you have neither specified a calendar in an application description, nor defined your own default calendar.

deadline. See deadline date and deadline date.

deadline date. The latest date by which an occurrence must be complete.

deadline time. The latest time by which an occurrence must be complete.

defined. An open day status which indicates that specific open time intervals exist for a workstation on a particular day.

dependency. A relationship between two operations where the first operation must successfully finish before the second operation can begin.

dialog. The user's online interface with TWS.

displacement. A number specifying 'Number of Days from Period Start' or 'Number of Days from Period End'. Sometimes called offset. See offset.

duration. The time an operation is active at a workstation.

E

edit. An ISPF/PDF dialog function that is used for editing text, collecting data, and modifying data.

end user. A person who uses the services of the data processing center.

ended in error (E). The TWS reporting status for an operation that has ended in error at a workstation.

error code. The system completion code or program return code for automatic reporting workstations. The code entered by the workstation operator for manually reporting workstations.

exclusive. The state of a special resource indicating that it is fully used by one operation and cannot be used simultaneously by other operations.

exclusive resource. A workstation resource that is solely used by one operation and cannot be shared with other operations.

expected arrival time. The time when an operation is expected to arrive at a workstation. It may be calculated by daily planning or specified in the long-term plan.

extend current period. a TWS function that allows the user to extend the current plan up to a maximum of 504 hours (21 days) from the current end date.

external dependency. A relationship between two occurrences where an operation in the first occurrence must successfully finish before an operation in the second occurrence can begin processing. See dependency.

external predecessor. The name given to the operation in the first occurrence of an external dependency that must finish before its external successor can begin processing.

external successor. The name given to the operation, in the second occurrence of an external dependency, that cannot begin until its external predecessor completes.

F

free day. A nonworking day.

free day rule. A rule that determines how TWS will treat free days when the application run day falls on a free day. The rule is as follows:

    Excluded: Free days excluded; only work days are taken into account.

    Included: Free days included; all days are taken into account, as follows:
    (1)   Run before the free day.
    (2)   Run after the free day.
    (3)   Run on the free day.
    (4)   Do not run on the free day.

G

general workstation. A workstation where activities, usually manual, and other than printing and processing, are carried out. Manual activities might be data entry or job setup. A general workstation reporting to TWS is usually manual, but can be automatic.

generic search argument. A portion of a key containing a generic search character which in TWS is an asterisk (*) or percent sign (%). The asterisk represents any string of characters and the percent sign any single character. Use with any portion of a key to search the database for items to be displayed as part of a listing. Examples: %ABC, A*C, A*.

H

host processor. * A processor that controls all or part of a user application network. * In a network, the processing unit in which the access method for the network resides.

highest return code. A numeric value from 0 to 4095. If this return code is exceeded during a job's processing, the job will be reported as ended in error.

I

incident log. An optional function available under the job completion checker.

input arrival. The user-defined date and time an operation or an application becomes ready for processing.

internal dependency. A relationship between two operations within an occurrence where the first operation must successfully finish before the second operation can begin.

internal predecessor. The name given to the operation of an internal dependency that must finish before its internal successor can begin processing.

internal successor. The name given to the operation of an internal dependency that cannot begin until its internal predecessor completes processing.

ISPF. Interactive System Productivity Facility.

interrupted (I). a TWS reporting status for an operation indicating that the operation has been interrupted while processing.

J

job. * A set of data that completely defines a unit of work for a computer. A job usually includes all necessary computer programs, linkages, files, and instructions to the operating system. In TWS, an operation performed at a CPU workstation.

job completion checker (JCC). An optional function of TWS that provides an extended checking capability of the results from CPU operations.

job control language (JCL). * A problem-oriented language designed to express statements in a job that are used to identify the job or describe its requirements to an operating system.

JES. Job Entry Subsystem.

job entry subsystem (JES). * A system facility for spooling, job queuing, and managing I/O.

job setup. The preparation of a set of JCL statements for a job at a TWS workstation you defined for this purpose.

job submission. a TWS process that presents jobs to MVS for running on a TWS defined workstation at a time specified in the daily plan.

JS. The JCL repository data set.

K

keyword. * A symbol that identifies a parameter. * A part of a command operand that consists of a specific character string (such as DSNAME=).

keyword parameter. * A parameter that consists of a keyword, followed by one or more values.

L

LTP. Long-term plan.

last operation. (1) An operation in an occurrence that has no internal successor. (2) The terminating node in a network.

latest start. The latest start day and time (calculated by TWS) for an operation that will allow all occurrences to meet their deadline.

layout ID. A unique name that identifies a specific ready list layout.

limit for feedback. See feedback limit.

local. * Synonym for channel-attached.

local processor. * In a complex of processors under JES3, a processor that executes users' jobs and that can assume global functions in the event of failure of the global processor. In TWS, a processor in the same installation that communicates with the controlling TWS processor through shared DASD communication.

long-term plan. A high-level schedule of processing activities for the forthcoming weeks and months. The scope of a long-term plan can be from one day to four years.

The long-term planning function produces a list of application occurrences identified by name, date, and run time for a specified planning period.

M

manual reporting workstation. A type of workstation reporting where events, once they have taken place, are manually reported to TWS. This type of reporting requires that some action be taken by a workstation operator. Manual reporting is usually performed from a list of ready operations.

mass updating. A function of the application description dialog where a large update to the application database can be requested.

modify current plan. a TWS dialog function used to dynamically change the contents of the current schedule to respond to changes in the operation environment. Examples of special events that would cause alteration of the current schedule are: a rerun, a deadline change, or the arrival of an unplanned application.

most critical application occurrences. Those unfinished applications that have a latest start time that is less than or equal to the current time.

N

node. * In a network, a point where one or more functional units interconnect transmission lines.

noncyclic period. A period that has a varying frequency for which you must define each origin date. Examples: month, payroll period, and quarterly.

nonreporting. A reporting attribute of a workstation which indicates that information is not fed back to TWS.

O

OPC/ESA. Operations Planning and Control/Enterprise Systems Architecture

occurrence. Each instance of an application in the long-term plan and current plan is called an occurrence.

An application occurrence is one attempt to process that application. Occurrences are distinguished from one another by run date, input arrival time, and application ID. For example, one application that runs four times a day is said to have four occurrences a day.

offset. A maximum of 12 positive and 12 negative values in the ranges 1 to 999 and -1 to -999 that indicate on which days of a calendar period an application shall run. See displacement.

TWS host. The processor where TWS updates the current plan database.

TWS local processor. A processor that connects to the TWS host or remote processor through shared event data sets.

open time interval. The time interval during which a workstation is active and can process work.

operation. An operation is a unit of work that is part of an occurrence and is processed at a workstation.

operation waiting for arrival. The status of an operation that indicates that the necessary input has not arrived at a workstation so that the operation can begin processing. This status is applicable only for operations without predecessors.

operation status. The status of an operation at a workstation.

An operation's status can be one of the following:

A   Waiting for input to arrive.

R   Ready for processing. All predecessors are complete.

*   Ready for processing. There is a nonreporting predecessor. All predecessors are complete but

one or more predecessors were executed at a nonreporting workstation.

S   Started.

I   Interrupted operation.

C   Complete.

E   Operation ended in error.

W   Waiting for predecessor to complete.

U   Undecided. The status is not known.

operator. * (ISO) A symbol that represents the action to be performed in a mathematical operation. * In the description of a process, that which indicates the action to be performed on operands. * A person who operates a machine.

option. A selection item on a menu panel in the TWS dialog.

origin date. The date on which a period (cyclic or noncyclic) starts.

P

panel. * A particular arrangement of presentation windows used to show information to the user. TWS uses only fixed-format panels.

parallel operations. Operations at workstations that are not dependent on one another and therefore can be performed simultaneously.

parallel server. The function that processes operations at a workstation, especially when there is more than one such function. See server.

parameter. * (ISO) A variable that is given a constant value for a specified application and that may denote the application. * A name in a procedure that is used to refer to an argument passed to that procedure.

pending application description. An application description which is incomplete and not ready for use in planning or scheduling.

period. A business processing cycle. A time period defined in the TWS calendar. They are used to describe when, and how often, applications are to run.

period name. A name of a period. Examples are week, month, quarter and fiscal period end.

period type. Periods are of two types: cyclic or noncyclic.

PDF. program development facility.

predecessor. An operation of an internal or external dependency that must finish successfully before its successor operation can begin.

printout routing. The ddname of the daily planning printout data set.

print workstation. A workstation that prints output and usually reports status to TWS automatically.

priority. A digit from 1 to 9 (where 1 = low, 8 = high, and 9 = urgent) that determines how TWS schedules applications to run. A number from 1 (low priority) to 9 (high priority) which establishes the importance of an application relative to other applications.

processor. * (ISO) In a computer, a functional unit that interprets and executes instructions. * A functional unit or part of another unit (such as a terminal or a processing unit) that interprets and executes instructions.

program interface. a TWS interface that allows a user-written program to issue various types of requests to the TWS subsystem.

Q

QCP. Query current plan.

R

RACF. Resource Access Control Facility.

read authority. A type of access authority that allows a user to read the contents of a data set, file, or storage area, but not to change it.

ready (R). The status of an operation indicating that predecessor operations are complete and that the operation is ready for processing.

ready list. A display list of all the operations ready to be processed at a workstation. Ready lists are the means by which workstation operators manually report on the progress of work.

recovery. See automatic job recovery.

remote processor. A processor connected to the TWS host processor by a VTAM network.

remote job tracking. The function of tracking jobs on remote processors connected by VTAM links to a TWS controlling processor. This function enables a central site to control the submitting, scheduling, and tracking of jobs at remote sites.

replan current period. a TWS function that recalculates planned start times for all occurrences to reflect the actual situation.

reporting attribute. A code that specifies how a workstation will report events to TWS.

rerun. a TWS function where an application or part of an application that ended in error can be run again.

rescale factor. A value from 0 to 100 used to reduce the new duration value by a given percentage amount.

return code. An error code issued by TWS for automatic reporting workstations.

row command. A dialog command used to manipulate data in a table.

run cycle period. A time frame defining the effective period and run days of a calendar period.

run day. The date on which an application is to run. It is expressed as a number relative to the start or the end of a run cycle period.

S

SAF. System Authorization Facility.

search argument. A value that is used to search the database for an item that is to be part of a displayed listing.

selection criteria. Search arguments entered on a list criteria panel in the dialog that limit the contents of a listing.

server. A program or device set up for a workstation to perform a service for that particular type of workstation. For example, an initiator is a server for a computer workstation. A printer is a server for a print workstation.

service functions. Functions of TWS that let the user deal with exceptional conditions such as investigating problems, preparing APAR tapes, and testing TWS during implementation.

shared DASD. Direct access storage device that can be accessed from more than one processor.

shared resource. A special or workstation resource that can be used simultaneously by more than one operation while the operation is processed at a work station.

slack. Used to refer to 'spare' time. Can be calculated for the critical path by taking 'Deadline less the Input Arrival less the Sum of Operation Durations'.

smoothing factor. A value between 0 and 100 that controls the extent to which actual durations are fed back into the application description database.

SMP. System Modification Program.

special resource. Resources that are not associated with a particular workstation but are needed to process work there.

splittable. Refers to an operation that can be interrupted while processing at a workstation.

standard. User specified open time intervals for a typical day at a work station.

status. The current state of an operation or an occurrence.

started (S). a TWS reporting status of an operation or an application indicating that an operation or an occurrence is started.

submit/release data set. A data set shared between the TWS host and a local TWS processor that is used to send job stream data and job release commands from the host to the local processor.

subresources. A set of resource names and rules for the construction of resource names. TWS uses these names when checking a user's authority to access individual TWS records.

subsystem. * A secondary or subordinate system, usually capable of operating independently of, or asynchronously with, a controlling system.

successor. An operation in an internal or external dependency that cannot begin until its predecessor completes processing.

sysout class. * An indicator used in data definition statements to signify that a data set is to be written on a system output unit. It applies only to print workstations.

T

temporary operator instructions. Operator instructions that have a specific time limit during which they are valid. They will be displayed to the workstation operator only during that time period.

TME 10 OPC. TME 10 Operations Planning and Control

tracker. The portion of TME 10 OPC or OPC/ESA that runs on every system in your complex. It acts as the communication link between the MVS system that it runs on and the controller.

tracking event log. A log of job tracking events and updates to the current schedule.

transport time. The time allotted for transporting materials from the workstation where the preceding operation took place, to the workstation where the current operation is to occur.

TSO. Time Sharing Option.

time zone support. A feature of TWS that allows applications to be planned and run with respect to the

local time of the processor that runs the application. Some networks may have processors in different time zones. The controlling processor will make allowance for differences in time during planning activities, for example the input arrival time of predecessor applications, to make sure that interacting activities are correctly coordinated.

turnover. A subfunction of job tracking that is activated when job tracking creates an updated version of the current schedule.

U

undecided (U). a TWS reporting status for an operation or an application indicating that the status is not known.

update authority. Access authority given to a user by RACF to use the ISPF/PDF edit functions of the TWS dialog. Access authority to modify a master file or data set with the current information.

V

validity period. The time interval defined by an origin date and an end date within which a run cycle or an application description is valid.

versions. Applications with the same ID but different validity dates.

VSAM. Virtual Sequential Access Method.

VTAM. Virtual Telecommunication Access Method.

W

waiting (W). a TWS reporting status (for an application) indicating that it is waiting for a predecessor operation to complete.

waiting list. A list of submitted jobs that are waiting to be processed.

work day end time. The time at which TWS will consider a work day to have ended when that work day immediately precedes a free day. For example, if you specify Saturday to be a free day, you could specify 08.00 hours. Saturday morning as the end of Friday's work day. TWS can then plan work to be done from 00.00 to 08.00 Saturday morning, as if that time was actually part of Friday.

workstation. A unit, place, or group that performs a specific data processing function. A logical place where work occurs in an operations department.

TWS requires that you define the following characteristics for each workstation: the type of work it does, the quantity of work it can handle at any

particular time, and the times it is active. The activity that occurs at each workstation is called an operation.

workstation description database. a TWS database containing descriptions of the workstations in the operations department.

workstation resources. Limited resources defined for each workstation that an operation requires a certain amount of to process work.

workstation type. Each workstation can be one of three types: computer, print, or general.

work day. A day on which applications can normally be scheduled to start.

Index

Special characters

Readers' Comments — We'd Like to Hear from You

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TWS Automation
Programmer's Reference
and Operator's Guide
Version 3 Release 1

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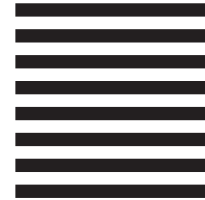
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