

Kinematics Merging Tools (CH9)

BPA Delivery 8 for V5R20 (V5.8)

User Guide

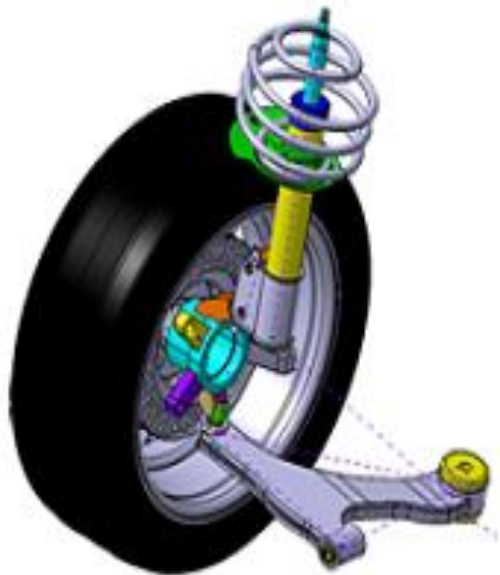


Table of Contents

Kinematics Merging Tools (CH9).....	1
BPA Delivery 8 for V5R20 (V5.8).....	1
User Guide	1
Table of Contents	2
Copyright Notice	3
Introduction	4
Overview of Kinematics Merging Tools	5
1.1 Workbench contents	5
Merge Structure	6
2.1 Purpose.....	6
2.2 Pre-requisite.....	6
2.3 User Operations.....	8
Merge Kinematics	9
3.1 Purpose.....	9
3.1.1 Scenario 1- Create A Common Product	10
3.1.2 Scenario 2- Do Not Create a Common Product	11
3.2 Pre-requisite.....	11
3.3 User Operations.....	12
3.3.1 Scenario 1- Create a Common Product	12
3.3.2 Scenario 2- Do Not Create a Common Product	15
Automatic Dress-up.....	17
4.1 Purpose.....	17
4.2 Pre-requisite.....	17
4.3 Mapping Mechanisms	18
4.4 Check Mapping group Information.....	20
4.5 User Operations.....	21
4.6 Help About-Kinematics Merging Tools.....	25

Copyright Notice

© 2010. Dassault Systèmes, All Rights Reserved.

This guide is delivered subject to the following conditions and restrictions:

CONFIDENTIAL - This document contains unpublished, confidential and proprietary information of Dassault Systèmes.

This document or any part thereof shall not be reproduced or transferred to other documents or formats, disclosed to others or used for any purpose other than that for which it is furnished, without the prior written consent of Dassault Systèmes.

It shall be returned to Dassault Systèmes upon request.

Dassault Systèmes is a registered trademark of Dassault Systèmes.

All other trademarks belong to their respective owners.

CATIA is a registered trademark of Dassault Systèmes SA.

Introduction

“Kinematics Merging Tools” is an add-in workbench provided over CATIA V5, where advance functionalities which are helpful for kinematics design process are provided. It consists of a dedicated workbench containing required commands and functionalities from other existing workbenches as well as newly developed commands specific to this domain.

The purpose of this document is to help readers understand how to use the BPA Kinematics Merging Tools.

Overview of Kinematics Merging Tools

This chapter introduces the different toolbars/ functionalities included into the Kinematics Merging Tools workbench.

1.1 Workbench contents

This workbench is containing all necessary commands required for the development of Kinematics Merging Tools.

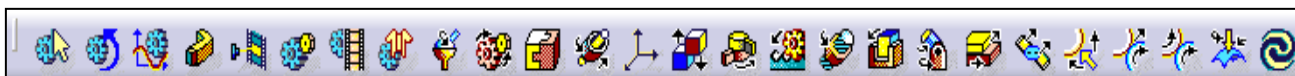
Three tool-bars:

- 1) **Toolbar:** - It contains the specific commands developed for the Kinematics design. It consists of five commands



- a. Merge Structure
- b. Merge Kinematics
- c. Automatic Dress-up
- d. Set Link Properties
- e. Display Link Properties

- 2) **DMU Toolbar:** - It contains all necessary commands from the DMU Kinematics workbench.



- 3) **Catalog Browser:** - This toolbar contains Catalog Browser



Merge Structure

2.1 Purpose

This command merges two product structures.

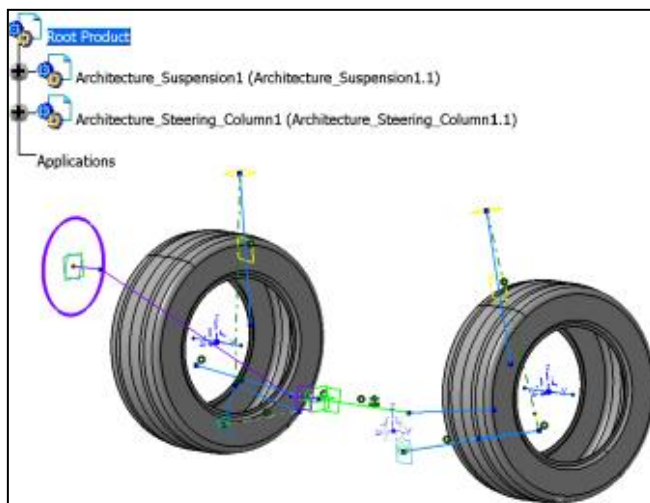
All the parts under both architectures (In the example below, Architecture Suspension and Architecture Steering Column) will get Copy-and-Pasted under the Root Product with Break link format and then the contextual links will be restored.

2.2 Pre-requisite

- 1) Two Architectures with mechanisms related to them.



- 2) Open these two architectures under one Product (Lets say Root Product)



Note:-

- 1) For successful working of this command, we should have strictly two Products containing kinematics under Root Product.
- 2) Two sub products must have mechanism related to it.
- 3) All the instance names of parts under two sub products MUST be unique. If not, you will have a problem at "Merge Kinematics". It is because of following reasons:
 - At "Merge Structure", if there are same instance names, they will be renamed by the command because you can't have a same instance name at the same level of product structure.
 - At "Merge Kinematics", some Kinematics joints will not be recreated properly because Kinematics joints rely on instance names and it will be lost if the name of pointing instance is modified.

► Hints and Tips: To share a common reference between two sub products

You can have a same reference (i.e., CATPart) between two sub products if instance names are different.

- It might be useful if you share a skeleton part between two products (i.e., Steering and Suspension).

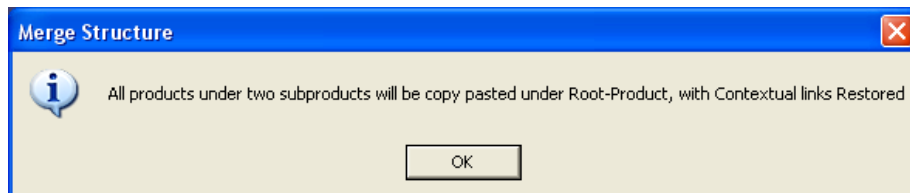
But as of now, at "Merge Kinematics", there is a limitation (you need to choose a Product [not a component] if you choose those two instances as "fixed components"). Please refer to 0.

2.3 User Operations

1) Click the Command.



2) Select Root Product and validate OK.



The result is illustrated in the adjoining screenshot.



Merge Kinematics

3.1 Purpose

This command recreates the mechanism for the “Merged Structure” (Result of command “Merge Structure”) at Root level.

► Hints and Tips: In case you need to define compound joints (Rack/Gear) later on

In some cases, you may want to add new compound joints (Rack/Gear) after merging to connect your two kinematics assemblies. For instance, suppose you merge steering kinematics and suspension kinematics. In that case, typically you need a Rack joint between the two. But obviously that Rack joint didn't exist in the original two kinematics models. So you need to add it by yourself.

The scenario will be something like following.

1. Create i) Suspension Kinematics, and ii) Steering Kinematics.
2. Merge those kinematics models.
3. Define a Rack joint which “connects” suspension and steering.

At step 3, you need to choose “Prismatic” joint from suspension side and “Revolute” joint from steering, because Rack joint is a compound joint. At this moment, one product must be commonly referred to by those two joints.

Figure 1 gives an example. P1 – P4 stand for products. R1 is Revolute Joint. Pris1 and Pris2 are Prismatic Joints. We can create Rack1, because R1 and Pris1 share P2. On the other hand, we can't define Rack2 because R1 and Pris2 don't share a product.

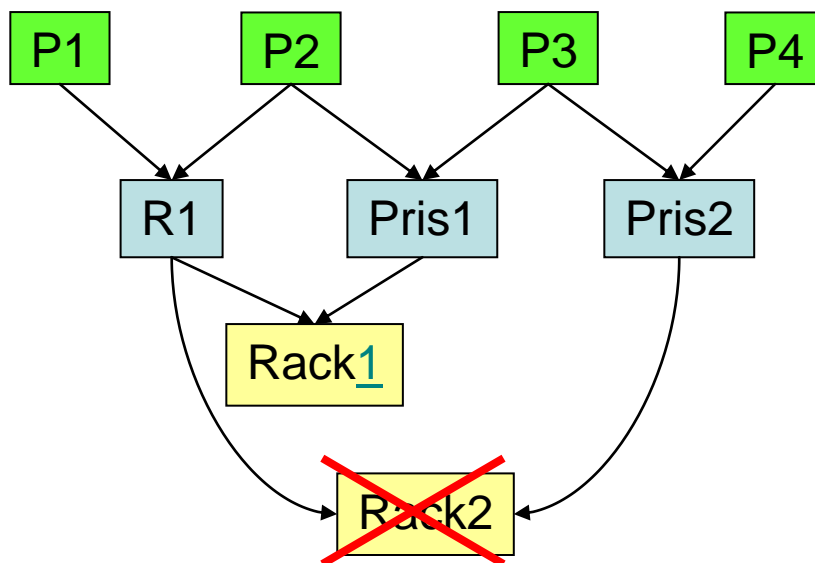


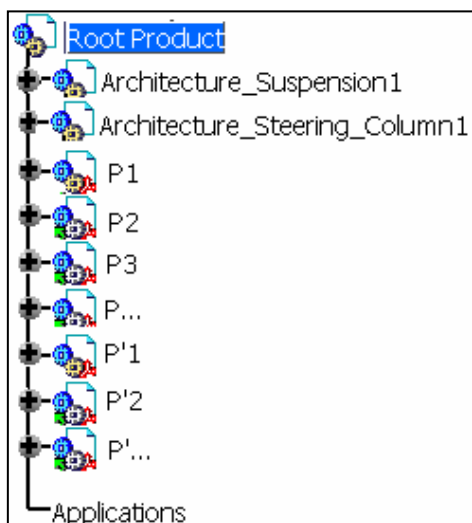
Figure 1 Prerequisite for Rack Joint Creation

Therefore, in case that you want to add a compound joint such as Rack that “connects” two kinematics definitions, you need to modify product structure and existing kinematics.

To deal with the case above, the command supports following scenarios.

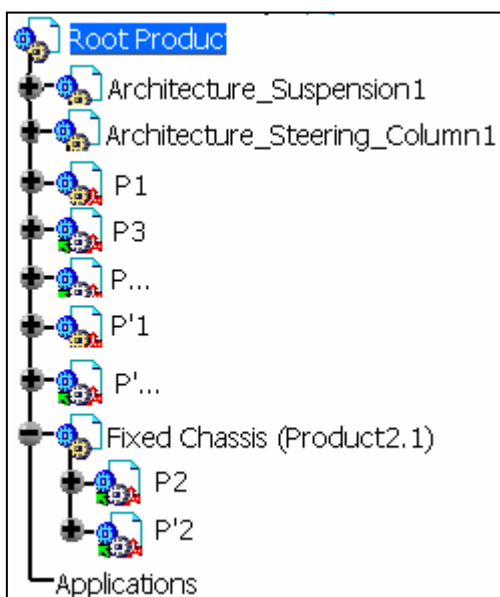
3.1.1 Scenario 1- Create A Common Product

1. Having Root Product with two architectures under it and all sub-products under each of architecture pasted at Root Level.



P1 , P2 , P3 ... are products from Architecture Suspension
P'1 , P'2 , P'3... are products from Architecture Suspension

2. Executing the command for creating a new product, a dialog will ask to select two products coming from two different architectures which will be then moved under the new product created. (Here let's say user have selected P2 and P'2)

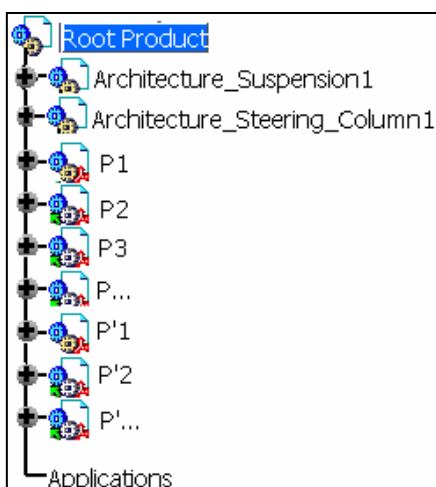


Fixed Chassis is a new product created.
Here P2 and P'2 are two products coming from two different architecture

3. Select Product (Lets say Fixed Chassis) to fix the mechanism:-
 - Mechanism created need to be fixed with reference to some product. Command allows you to choose the product with which user want to fix the mechanism.
4. Name the newly created mechanism.
 - A dialog will get pop-up to allow user to name the newly created mechanism.
5. Command ends with creating a Mechanism, reproducing the Joints and Commands from two architectures at Root Level

3.1.2 Scenario 2- Do Not Create a Common Product

1. Having Root Product with two architectures under it and all sub-products under each of architecture pasted at Root Level.



2. Executing the command for not creating a new product, mechanism which will be the result of the merge of the two mechanisms from two architectures will get created.
3. Select Product to fix the mechanism.
4. Name the newly created mechanism.
5. Command ends with Creating a Mechanism, Reproducing the Joints and Commands from two architectures at Root Level.

3.2 Pre-requisite

For successful working of this command:

- Two Architectures (Products) under a Root product having their mechanisms defined and with their sub-products pasted at Root Level.

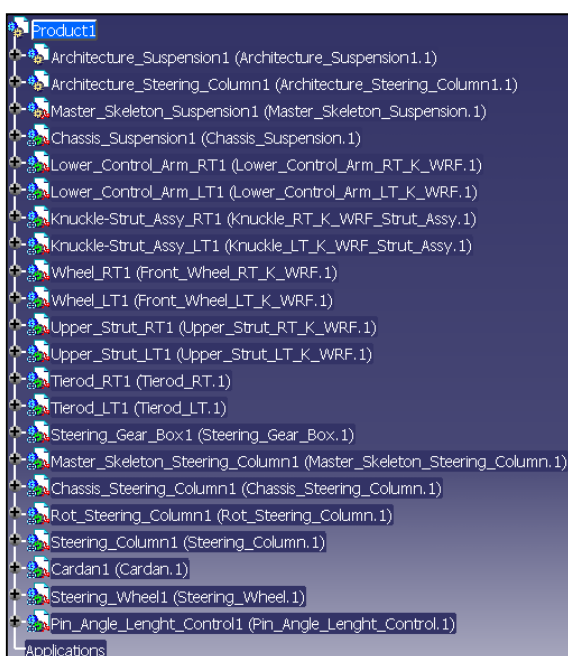
- Each architecture must have mechanism related to it.

Command will work on the result of Merge Structure command.

3.3 User Operations

3.3.1 Scenario 1- Create a Common Product

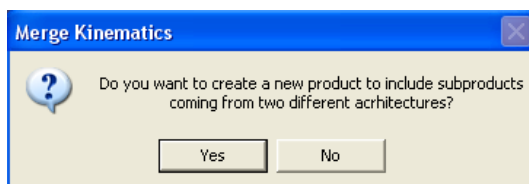
1. Actual data before executing the command.



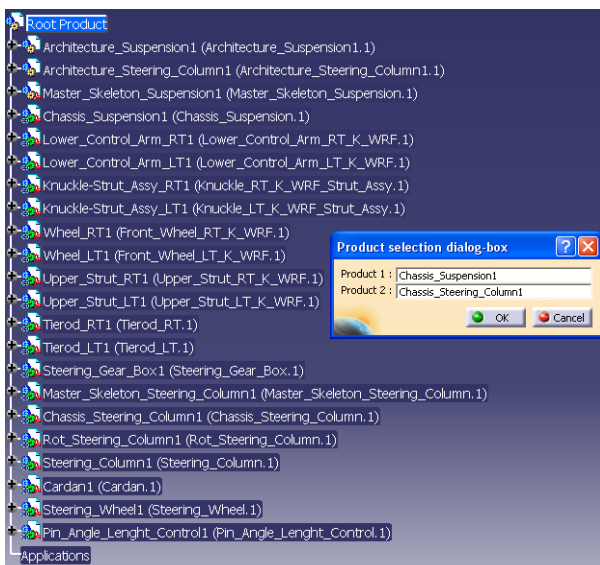
2. Click the command



3. Click “Yes” to create new product, which will contain two products coming from two different architectures (Products).



4. Select two products which will get moved under the new product getting created.



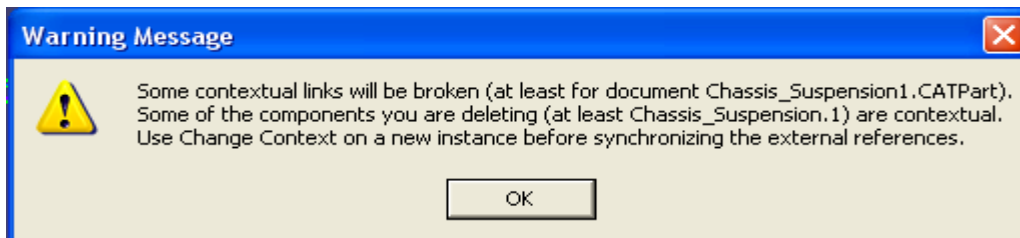
5. Choose to create product or component and name the newly created product/component.



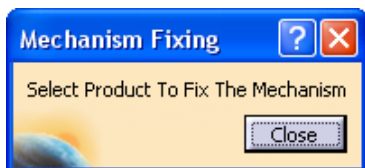
► Limitation: In case you share an identical reference between two sub products.

In case you choose two parts which had originally been the same reference (CATPart), you have to choose "Product" here (Do not choose "Component").

6. You will see the following Warning Message. Click OK



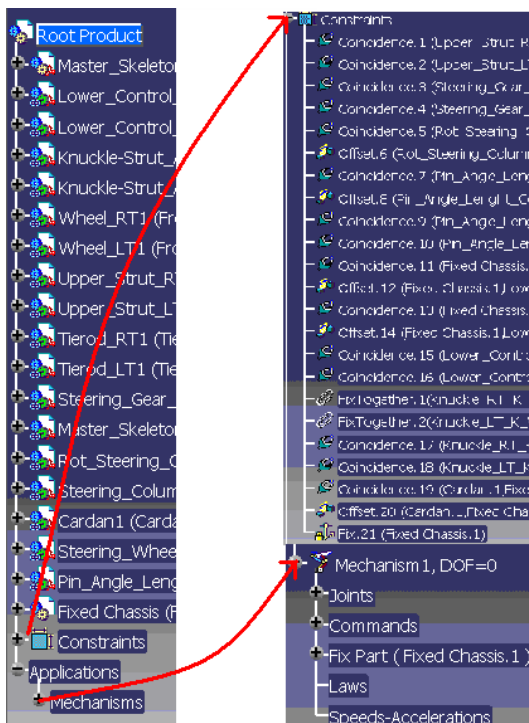
7. Click Close button and select the product to fix the mechanism.



8. Please enter the name for a newly created mechanism.



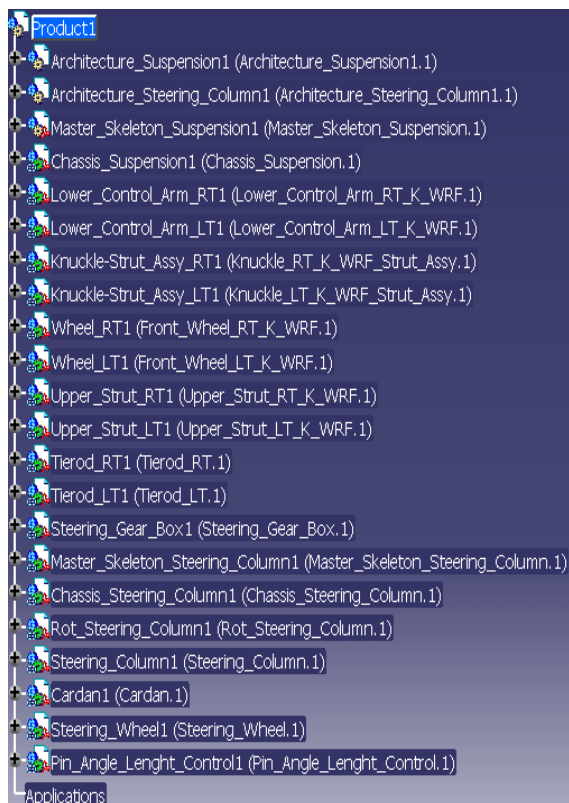
9. Result can be seen



All the Joints and commands from previous mechanisms (One from each architecture) are created under this architecture.

3.3.2 Scenario 2- Do Not Create a Common Product

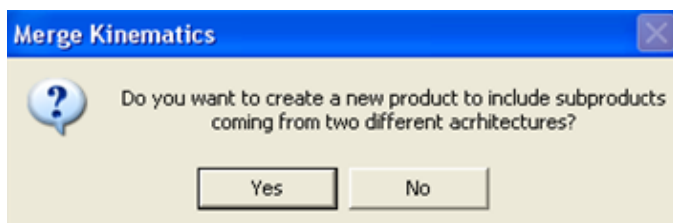
1. Actual data before executing the command.



2. Click the command.

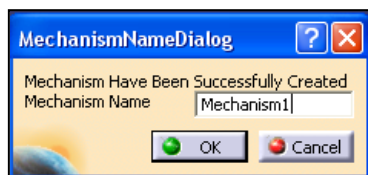


3. Click "NO"

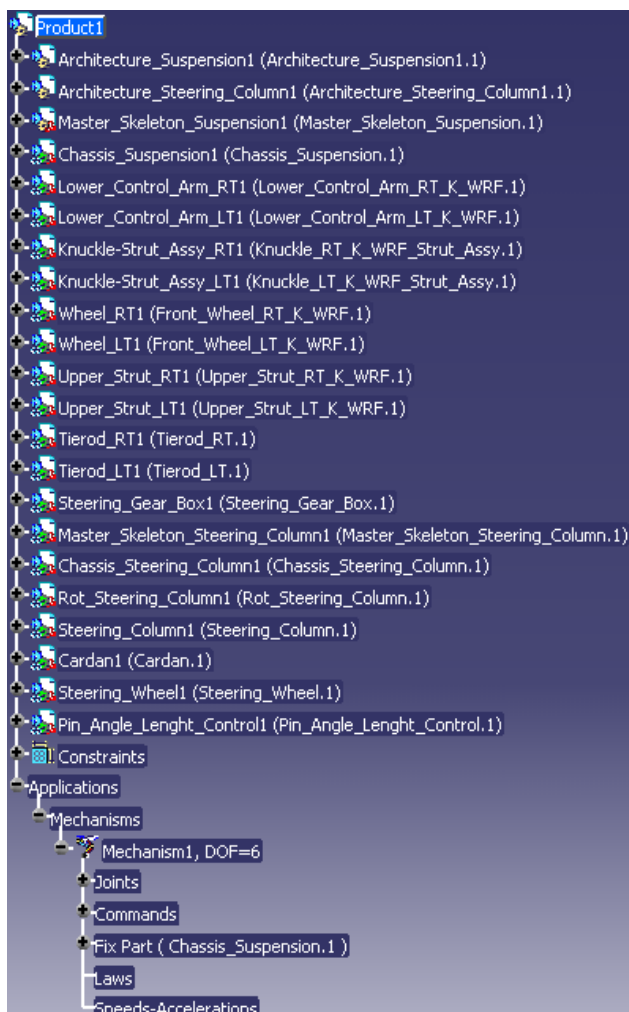


4. Mechanism has got created which will be result of merging of two mechanisms coming from two different architectures. Select a product to fix this mechanism.

5. Name the mechanism.



6. Result is indicated in the screenshot below



All the commands and joints from the two mechanisms from two architectures are now under this newly created mechanism.

Automatic Dress-up

4.1 Purpose

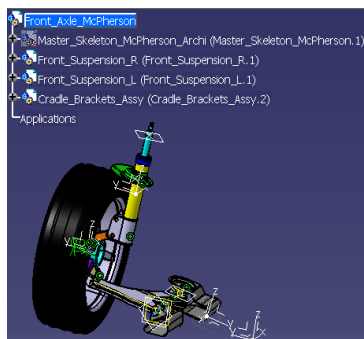
It automates Dress-up (link between kinematics models and corresponding 3D detailed parts) definition.

To find a relationship between kinematics models and 3D detailed parts, the command relies on the naming explained at 0.

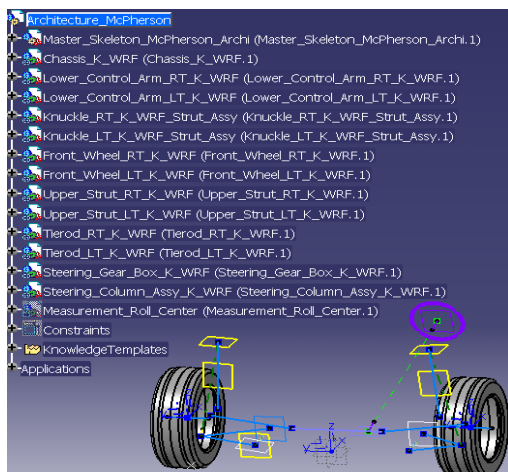
4.2 Pre-requisite

There need to exist an architecture with 3D parts and one architecture containing wireframe parts.

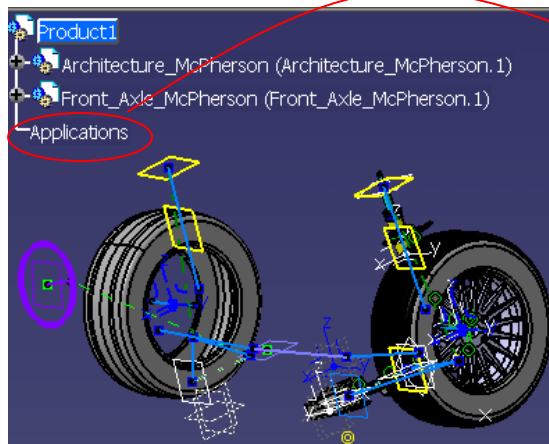
1. 3D Parts:-



2. Wireframe Parts:-



3. Open 3D parts and Wireframe under so as to have one common Father Product (here it is Product1)



Check that there is NO any imported mechanism.
If present then delete that one.

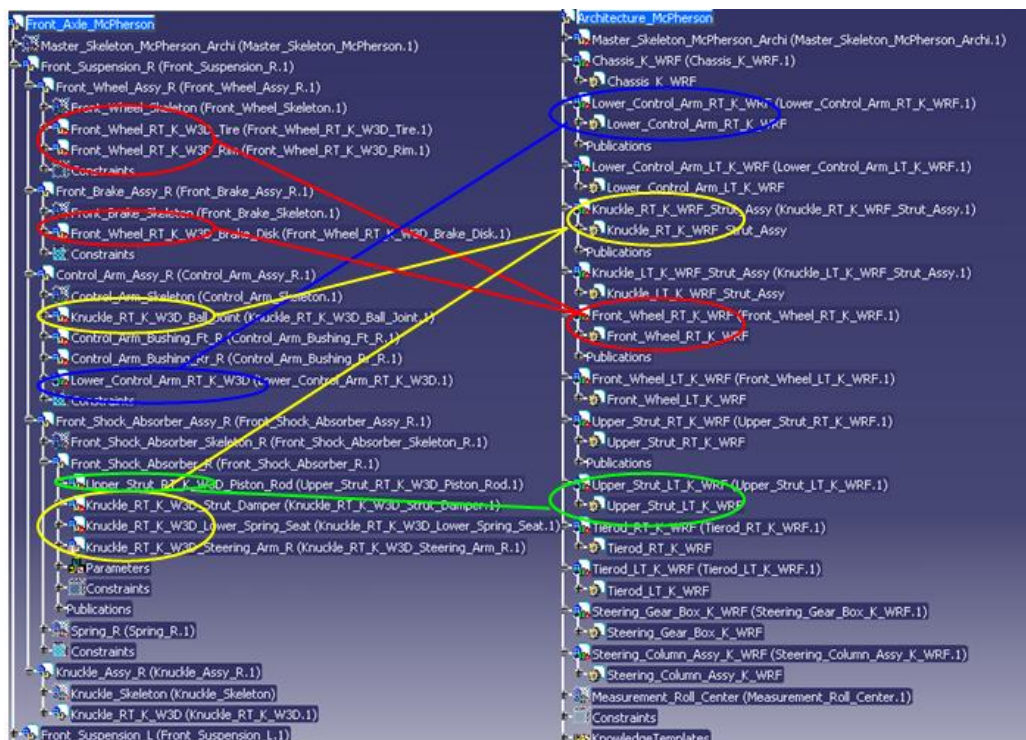
4.3 Mapping Mechanisms

Choose mapping conventions and set Products values for dress-up

There are two mapping conventions for automatic dress-up: Instance Naming Convention and Property Value Convention.

1. Instance Naming Convention

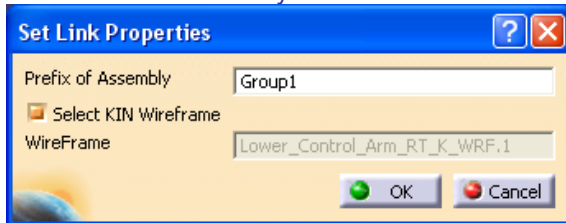
Check for the existence of respective match with appropriate Suffix of Product Instance name (Like here, _K_WRF for wireframe and _K_W3D for 3D parts)



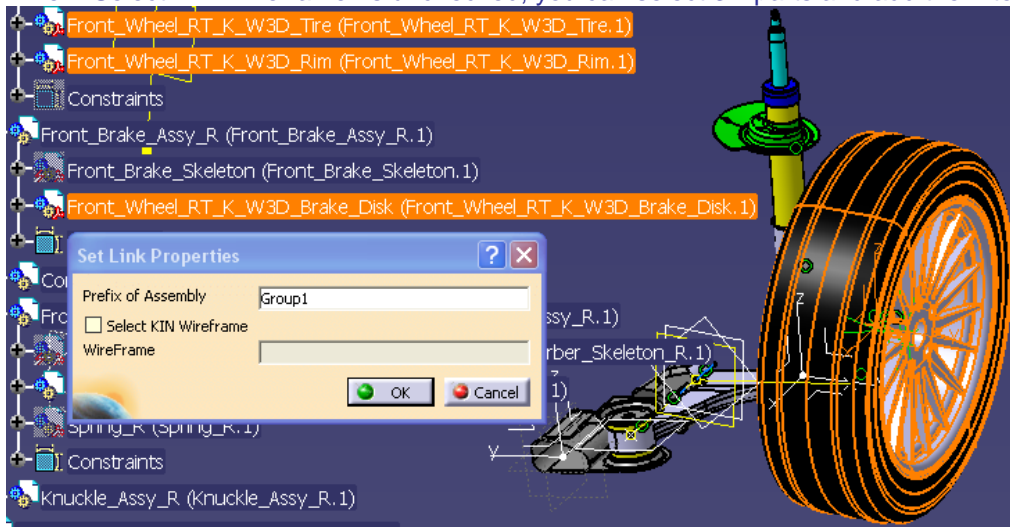
2. Property Value Convention

Use command  to define the wireframe & 3D Parts mapping group.

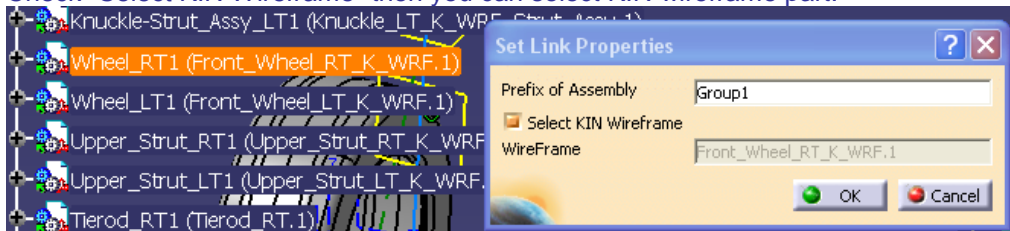
Edit “Prefix of Assembly” value. This value is the identifier of the merging group name.



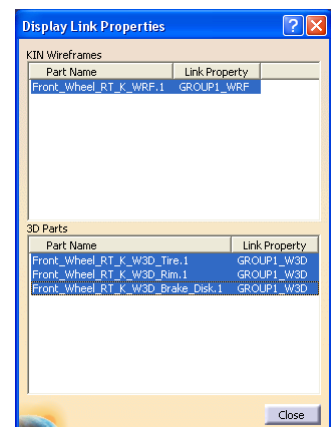
When “Select KIN Wireframe” is unchecked, you can select 3D parts and add them to the target list



Check “Select KIN Wireframe” then you can select KIN wireframe part.



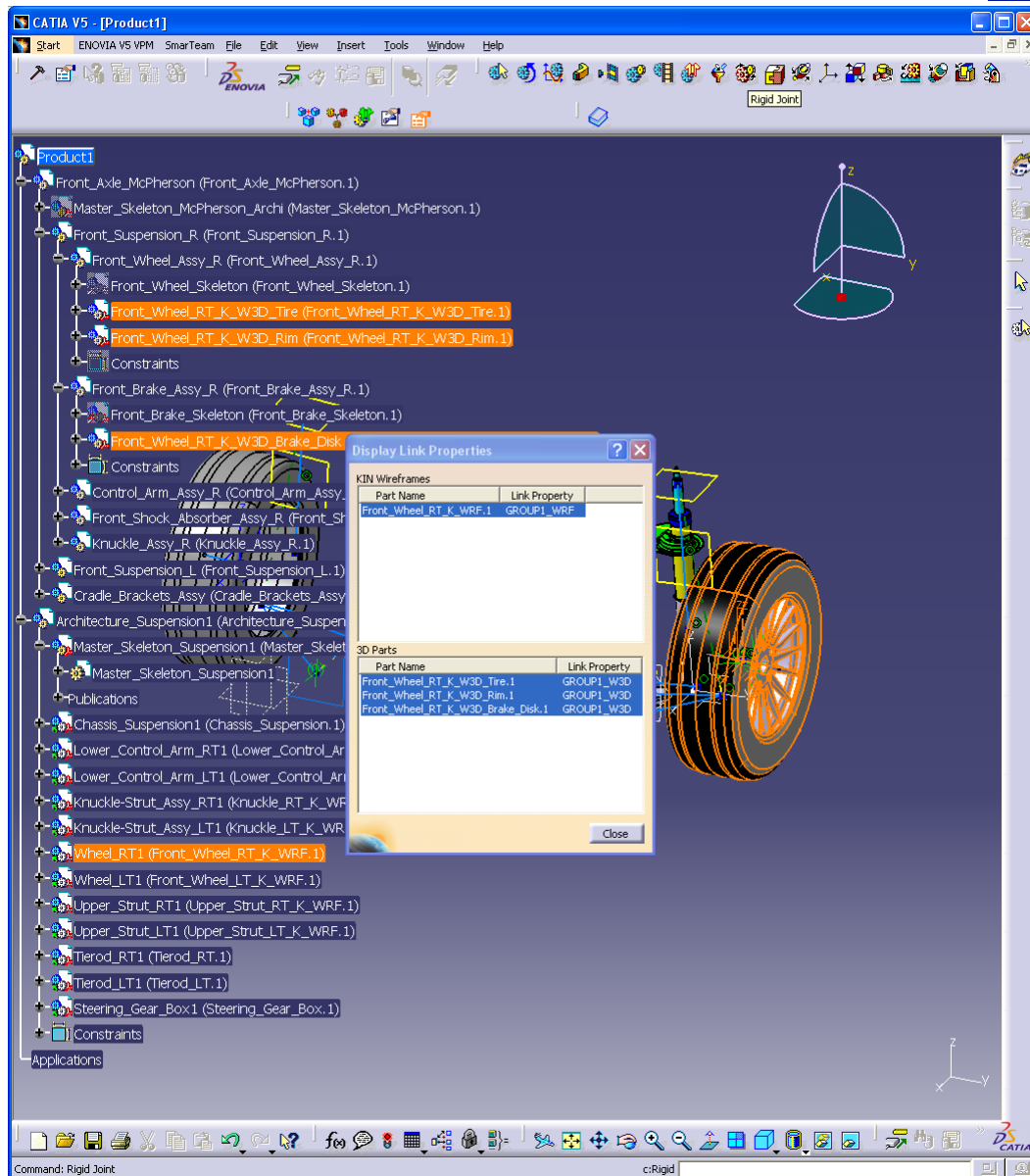
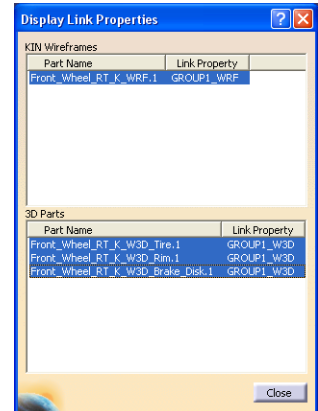
Click on OK will create the link properties in the all the selected members.



4.4 Check Mapping group Information

Use command  to confirm the defined link properties

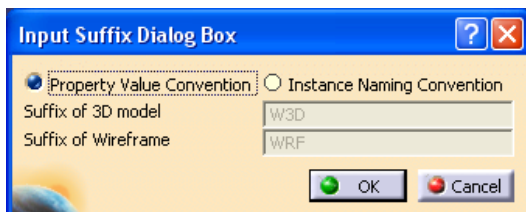
If multiple groups are defined, you can select one of the members in the panel or specification tree then all the corresponding members will be highlighted in the panel, tree and 3D view.



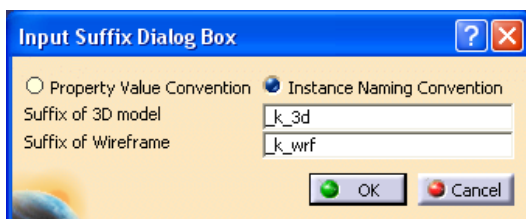
4.5 User Operations

5. Click the command 
1. Select an architecture containing wireframe parts.
2. Select the dress-up mapping convention

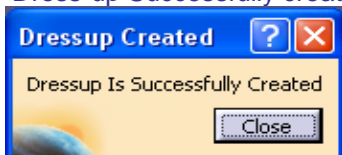
a. Property Value Convention



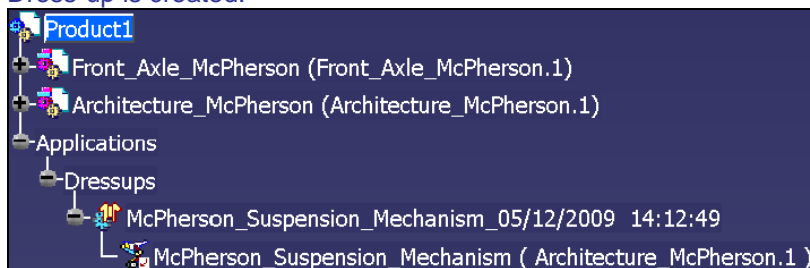
b. Instance Naming Convention Enter the appropriate suffix



3. Click on OK
4. Dress-up Successfully created



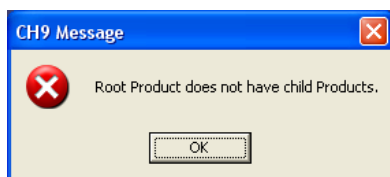
5. Dress-up is created.




6. If the Dress-up is not created than a message "Dress-up could not be created" is shown.

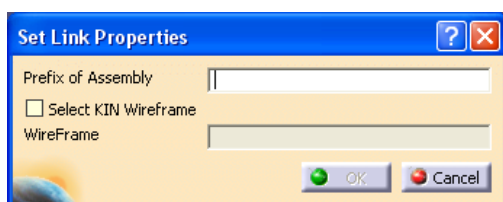


7. If there is no Parts\Product under the Root Product and any command is clicked then following message is shown:



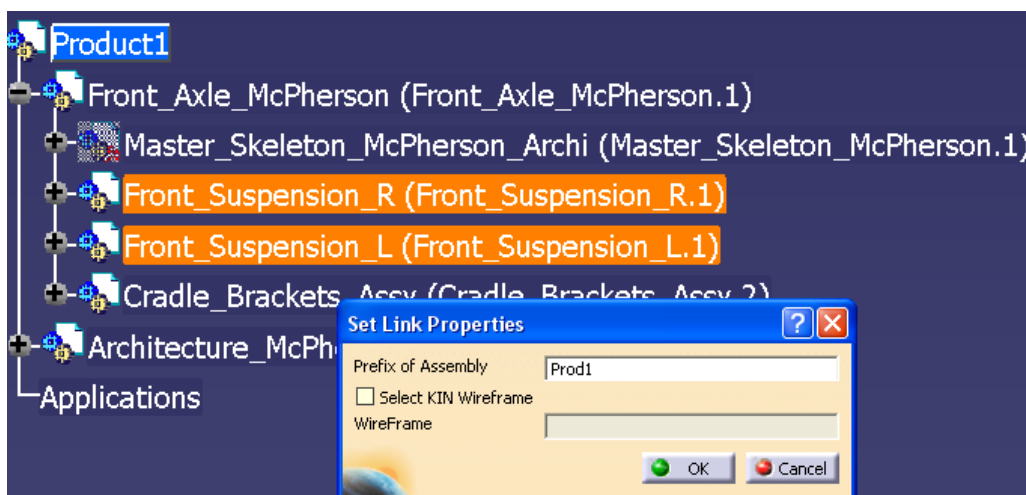
Set Link Properties

8. Click the command 
9. When the command is launched, the following dialog box will be shown.



There are three functionalities in this command:

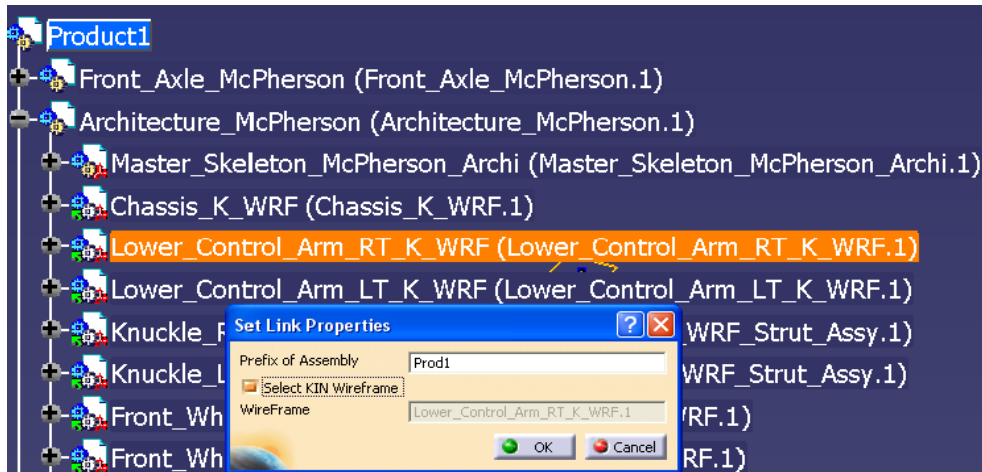
- a. To select the 3D parts\product, deselect the option “Select KIN wireframes” from the dialog box.



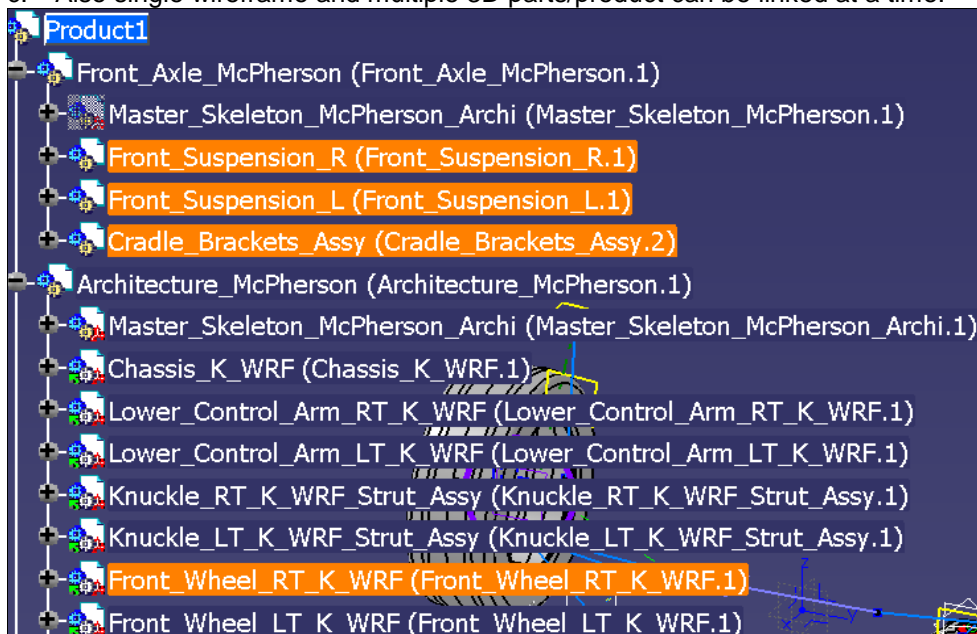
Note:-

3D models selected are not shown in the Panel, they are highlighted only in the tree.

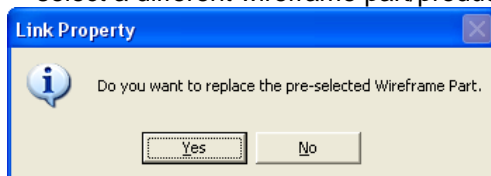
- b. To select the Wireframe parts\product, select the option “Select KIN wireframes” from the dialog box.



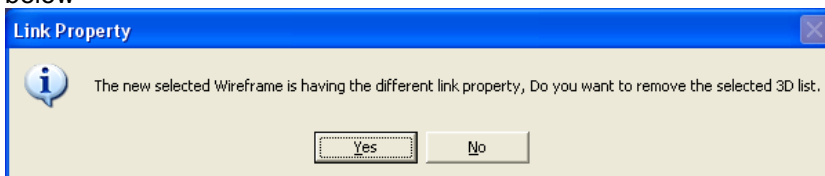
c. Also single wireframe and multiple 3D parts/product can be linked at a time.



d. select a different wireframe part/product at a time gives a the following message:




e. If the wireframe model is already linked with some other 3D model then it will show a message shown below

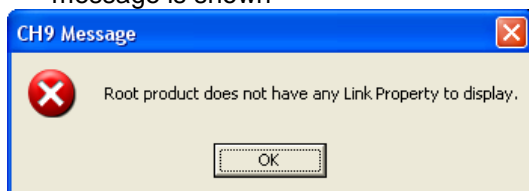


Click on Yes, the selected 3D list will be removed.

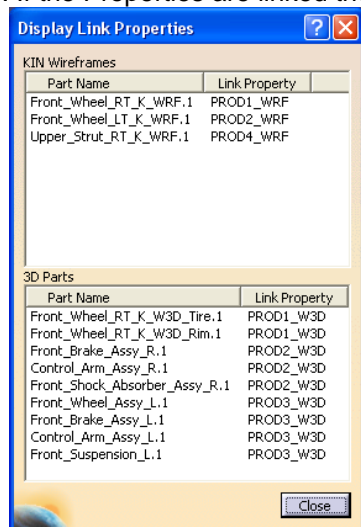
Display Link Properties

15. To check how the properties are linked, click on this command 

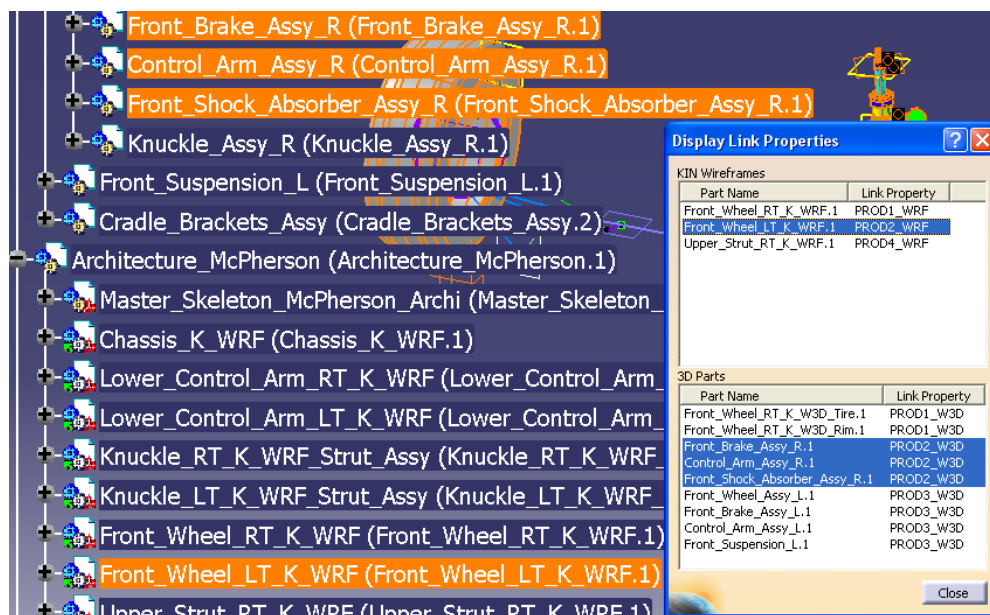
- a. If there are no properties Linked in any 3D and Wireframe product then the following popup message is shown



- b. If the Properties are linked then all the Link properties will be shown in the Panel

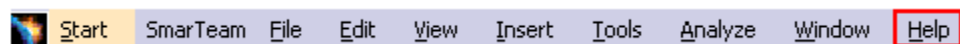


Now select any Parts/Product in the panel it will highlight all the Parts/Products having same Link properties in the tree as well as in the panel and vice versa.

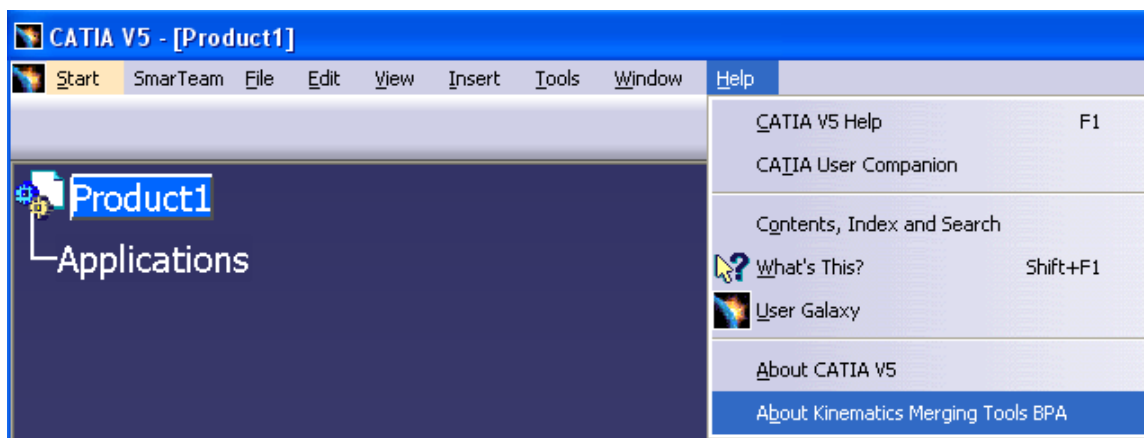


4.6 Help About-Kinematics Merging Tools

1. Click on the help tab in the Menu bar



2. Click on about Kinematics Merging Tools BPA



3. Help about window for Kinematics Merging Tools

