Using NRL Teach on Twin-Wrist Robots

This procedure describes NRL support of twin-wrist robots using NRL Teach.

Open the Twin_Wrist_OLP.CATProcess file, and choose Motoman to be the selected upload and download translator.

1. Set **NRL Configuration File Directory** to <intel_a\startup\OLP\NRLTeach>

2. Click **Native Robot Language Teach** and select task **RobotTask.2**.

3. Test the **Execute**, **Motion Instructions**, **V5 Properties** buttons.

4. Download the robot program and save.

5. Click **Import Robot Program** and select the twin-wrist robot.

6. Select the robot program file created in the previous step and select **Motoman.jar** as the upload translator.

7. Click **Robot Task Simulation**, and select the new task to run the simulation.